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### **LESSON 1**

### **INTRODUCTION**

#### **STUDENT LEARNING OBJECTIVES**

Upon completion of this course, the technician will be able to:

- Use a DRB III and/or MDS to interpret the signals generated by the various input sensors, as displayed on these tools.
- Use the service manual procedure to properly depressurize the fuel system, attach the appropriate test equipment, and test fuel system pressure.
- Given a vehicle equipped with either a V-6 or V-8 engine, the appropriate Service Manual and Powertrain Diagnostics manual, the technician will be able to properly diagnose electrical and mechanical malfunctions of inputs and outputs to the Powertrain Control Module.
- Use a DVOM on vehicle to measure, record, and interpret the voltage/ resistance of various PCM-related system inputs and outputs.

### **GENERAL DESCRIPTION**

This publication contains information regarding the systems controlled by the Powertrain Control Module (PCM). These include fuel, emissions, speed control, charging, PCM-related A/C control functions, and PCM-related transmission control functions on all the 1996 and 1997 vehicles equipped with either a 3.9L, 5.2L, 5.9L Magnum engine. This includes the  $Jeep_{\&}$  Grand Cherokee, Dodge Dakota, Dodge Ram Pickup and Dodge Ram Van.

The fuel system for all these engines utilizes a speed density sequential multiport fuel injection system, to deliver precise amounts of fuel to each cylinder. Fuel for all vehicles is delivered by an in-tank pump module.

All engines use a distributor-type ignition. The PCM controls the ignition and fuel injector operation and provides outputs to fuel and ignition components to promote the most efficient operation possible.

All vehicles equipped with the 3.9L, 5.2L, 5.9L Magnum engine comply with the OBD II phase-in plan.

**NOTE:** Early 1997 PCMs have an eight-digit part number and operate like a 1996 PCM. Later 1997 models have a 10-digit part number.

### **ACRONYM LIST**

- Air Bag Control Module ACM
- Air Conditioning A/C
- Auto Shutdown Relay ASD relay
- Barometric Pressure Baro
- Battery Temperature Sensor BTS
- Body Control Module BCM
- Camshaft Position Sensor CMP sensor
- Chrysler Collision Detection Bus C<sup>2</sup>D
- Crankshaft Position Sensor CKP sensor
- Data Link Connector DLC
- Diagnostic Trouble Code DTC
- Digital Multimeter DMM
- Duty Cycle Purge Solenoid DCP solenoid
- Electrically Erasable Programmable Read-Only Memory EEPROM
- Engine Coolant Temperature Sensor ECT sensor
- Engine Position Pulse EPP
- Idle Air Control Motor IAC motor
- Intake Air Temperature Sensor IAT sensor
- Jeep<sub>®</sub>/Truck Engine Controller JTEC
- Leak Detection Pump LDP
- Malfunction Indicator Light MIL
- Manifold Absolute Pressure Sensor MAP sensor
- Mopar Diagnostic System MDS
- Mechanical Instrument Cluster MIC
- Negative Temperature Co-efficient NTC
- Oxygen Sensor O2 Sensor
- Park/Neutral P/N
- Positive Temperature Coefficient PTC
- Power Distribution Center PDC
- Powertrain Control Module PCM
- Throttle Position Sensor TPS
- Vehicle Speed Sensor VSS
- Vehicle Theft Security System VTSS

### **POWERTRAIN CONTROL MODULE (PCM)**

Introduced in 1996, the Jeep<sub>®</sub>/Truck Engine Controller (JTEC) does not require air to flow through the controller for cooling. There are two different suppliers of JTEC controllers. Each supplier uses a different housing. The housing that looks like an aluminum casting is made by Motorola (fig. 1). The other housing looks like a stamped "tin can" and is made by Huntsville (fig. 2).

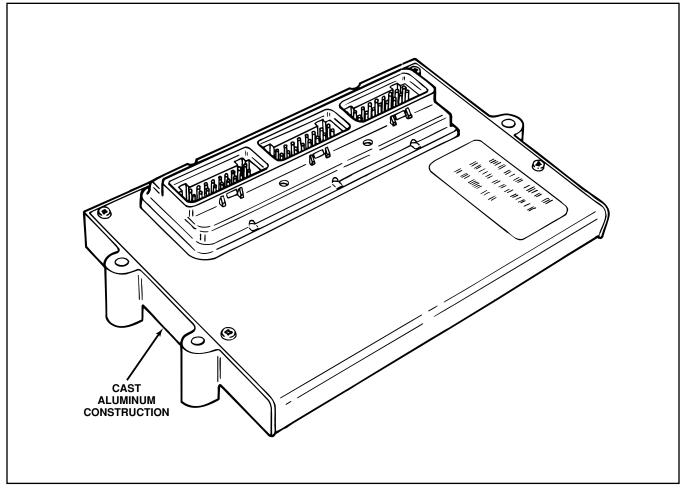


Figure 1 Motorola Powertrain Control Module

These controllers are interchangeable within the same emissions package. The changes to the PCM from previous Chrysler controllers include:

- Increased memory
  - 2k '96
  - 4k '97
- Increased speed at which the processor runs:
  - Clock speed (8 MHz)
  - 16-bit microprocessor
  - Two 8-bit microprocessors
- Increased number of drivers to control outputs from 22 to 30.
- Increased number of terminals in the connector from 60 to three 32-way connectors (96 total).

- Gold-plated, low-insertion-force terminals (new tool No. 6932 required for servicing the terminals).
- Uses an Electrically Erasable Programmable Read-Only Memory (EEPROM) on all PCMs (flashable).

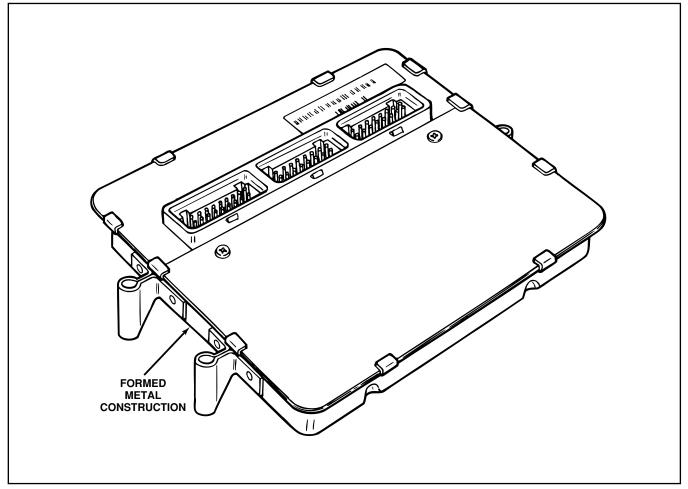


Figure 2 Huntsville Powertrain Control Module

The PCM is a multiprocessor unit, containing one 16-bit microprocessor and two 8-bit microprocessors. The PCM controls operation of the fuel, emissions, charging, idle, air conditioning and speed control systems. This is accomplished by the 16-bit processor, which transmits fuel and spark requirements to the two 8-bit processors, communicating with outside devices; and processing some of the analog inputs. One of the 8-bit processors controls fuel-injector timing pulses and some 1-bit inputs and outputs. The other 8-bit processor controls spark timing pulses, handles a few analog inputs and some 1-bit (on/off) inputs and outputs. After processing the information, the PCM operates outputs that regulate the engine performance, the ignition components, the generator field, the air conditioning compressor, and the speed control servo. This cycle of input/processing/output ensures that the engine meets emissions, performance, fuel economy, driveability and customer expectations.

The JTEC PCM uses voltage level detection to determine when a device or circuit is present. This means that the internal circuit of an input is constructed in a way that there must be a specific voltage present for the JTEC PCM to recognize a change. The voltage required is approximately 5 volts.

The analog to digital (A/D) converters are part of the micro-processors in the JTEC. The A/D converter changes the analog signal from a sensor into a digital signal with the same value. The digital signal is then processed by the micro-processor.

### **GENERAL PCM INFORMATION**

Because the same basic controller is used on a wide variety of engine packages, it is necessary for the PCM to learn the options actually on the vehicle. This function is shown as "Learned Vehicle Configuration" on the DRB III. In order for the PCM and DRB III to diagnose and report faults, for items such as speed control and air conditioning, the PCM must see the input of the item at least once with the engine running. The PCM then knows that the vehicle is equipped with that option. This is important because if the DRB III does not show the item as equipped, it will not display any fault codes, even though they may be present in the PCM.

Anytime the direct battery is disconnected from the PCM, for approximately 60 seconds, the "Learned Vehicle Configuration" is erased. Erasing fault codes with the DRB III causes the PCM to perform a battery reset function if PCM has an 8-digit number. This means that the previously mentioned configuration is erased, as well as all learned memory functions, such as Long Term Adaptive Memory and IAC steps. On 10-digit part numbered PCMs, erasing DTCs clears faults, freeze frames and similar conditions only.

#### **SPEED DENSITY**

A speed density system measures the engine rpm, as well as the intake manifold absolute pressure. Coolant temperature and throttle position are necessary inputs also. On the 1996 V-6/V-8 engine speed density systems, **both** the crankshaft and camshaft (sync signal) position inputs are needed to start and run the engine. The engine cannot run without them. The RPM signal tells the PCM <u>how often</u> to add fuel, while the Manifold Absolute Pressure (MAP) sensor input determines <u>how much</u> fuel the engine receives (fig. 3).

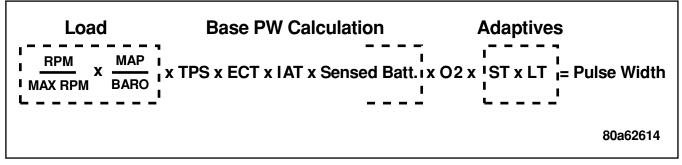


Figure 3 Speed Density Engine Management Strategy

For a speed density system to operate, the first and most important piece of information that must be determined is the amount of air that is entering the engine. To do this, the PCM looks first at the current rpm, divided by the MAX rpm. This allows the PCM to calculate the greatest volume of air entering the engine at that rpm. The PCM then looks at the present manifold vacuum, compared to the barometric pressure that was seen at key on.

This gives the PCM the reference for current air pressure in the intake system. With these two pieces of information, the PCM determines the current load being placed on the engine. For instance, if rpm was low and vacuum nearly matched baro (WOT), then the PCM would know that the engine is under a heavy load and inhaling as much air as possible for that rpm.

The PCM uses the TPS to determine the current mode of operation such as idle, offidle acceleration, WOT, or deceleration. The PCM uses this information to perform various operating strategies. If the TPS increases rapidly, the injectors will be held open to increase fuel flow. If the TPS is closed and the vehicle is moving, then the PCM will limit and/or close off injectors during coast down.

The PCM has to see a value for every sensor so that it can correctly calculate the pulse. If a sensor goes bad, a value must be substituted. If the MAP sensor is bad, the PCM will use the TPS and rpm to make up a value to use as MAP.

The next modifier is Engine Coolant Temperature (ECT), which is the second biggest modifier of pulse width, after MAP. If the engine is cold, the fuel will not atomize easily. To overcome this problem, the PCM will add extra fuel, depending on the value from the ECT. Conversely, if the engine is very hot, fuel will be limited. If the ECT signal is lost, the PCM will substitute a preset (limp-in) value.

Intake Air Temperature (IAT) is also used to modify the amount of fuel delivered, although it is not as big a modifier as ECT. If ECT is high and IAT shows cold (dense air), then the PCM will add extra fuel. Another feature of IAT is that spark advance is limited, if the air is hot (thin). If the IAT signal is lost, the PCM will substitute a value based on Battery/Ambient Temperature sensor.

Sensed battery voltage is needed as a modifier because the injectors are rated for specific flow at a specific voltage. If the voltage is lower than what the injector was rated at, it will take longer for the injector to open, and it may not open as far. So the PCM needs to know the voltage, so that it can compensate by changing the pulse width.

Up to this point, it is not necessary that any fuel was burned, and/or the PCM is in an open-loop operating condition.

After the fuel is delivered, the PCM looks at the O2 signal to determine how well it did on the initial calculation. The O2S provides the PCM with the raw input, as to how much oxygen was left over, after the combustion process.

The adaptive memories allow the PCM to do two things. First, it gives it the capability to change the pulse width to bring the O2S to its mid-range of operation (short term). Second, it allows to store in memory corrections required for specific operating conditions (long term).

Based upon all of these inputs, the PCM delivers what it believes to be the optimum pulse width, to deliver the correct emissions performance, fuel economy, and driveability.

### FUEL DELIVERY SYSTEM

The fuel system receives fuel pressure from an in-tank pump module. The PCM controls the operation of the fuel system by providing battery voltage to the fuel pump through the fuel pump relay. The PCM requires only two inputs and a good ground to operate the fuel pump relay. The two inputs are:

- Ignition voltage.
- Crankshaft Position (CKP) sensor.

**NOTE:** The PCM uses inputs from the CMP and CKP sensors to calculate engine speed.

### **EMISSIONS SYSTEM**

The emissions system has several components, all used to lower the quantities of hydrocarbons (HC), carbon monoxide (CO) and oxides of nitrogen (NOx). Emissions systems are required not only to control the quantity of emissions out the tailpipe, but also any emissions that might be escaping into the atmosphere from the fuel system and engine. The emissions system includes:

- Evaporative control system
- Engine crankcase pressure-control system (positive crankcase pressure)
- Exhaust emissions

The PCM controls the evaporative emissions by the operation of a Duty-Cycle Purge (DCP) solenoid. The inputs required to control the DCP solenoid include:

- ECT sensor
- O2 Sensor
- TPS
- Engine speed
- MAP sensor
- Ambient/Battery Temperature sensor

The engine crankcase is ventilated by a Positive Crankcase Ventilation (PCV) valve that is not controlled by the PCM. All 1996 V6/V8 engines use a breather cap on the rocker arm cover in the PCV system. In 1997, V6/V8 engines, except those installed in Dakota pickups, also use a breather cap. A V6/V8 engine in a Dakota uses a tube that connects between the rocker arm cover and the air inlet to the throttle body. There are some early 1997 Dakota pickups that were built with the breather cap.

The exhaust emissions are controlled by the use of a catalytic converter, EGR valve and almost every input and output of the PCM. The only inputs and outputs that do not control emissions are:

- Speed-control switches and servo
- Tachometer
- Air Conditioning (A/C) request circuit, A/C relay and the A/C pressure switches
- ASD and fuel pump relays

### **IDLE CONTROL SYSTEMS**

The PCM maintains a quality idle by controlling the Idle Air Control (IAC) motor. Inputs to the PCM required to operate the IAC motor include:

Spark scatter (output)

• Park/Neutral switch

- TPS
- MAP sensor
- ECT sensor
- VSS

- A/C switch
- Ambient/Battery Temperature sensor

### **CHARGING CONTROL SYSTEMS**

### **1996**

The PCM maintains battery voltage within a range of approximately 13.04 volts to 15.19 volts by providing battery voltage to the generator field through the ASD relay and by controlling the ground side of the generator field.

The inputs required to maintain the proper battery voltage are:

•

- Battery voltage
- BTS
- Engine speed

#### **1997**

The 1997 PCM maintains battery voltage within a range of approximately 13.04 volts to 15.19 volts by providing both battery voltage and ground to the generator field through the PCM.

### **VEHICLE SPEED CONTROL SYSTEMS**

The PCM is designed to operate the speed control system to allow the driver of the vehicle to maintain a constant vehicle speed automatically. The speed control servo receives battery voltage directly from the PCM. The PCM on all vehicles operates the ground side of the vacuum and vents solenoids of the servo. The brake switch controls the dump solenoid. For more information, refer to the Vehicle Speed Control section of this publication.

#### A/C CONTROL SYSTEMS

Finally, the PCM uses the A/C Request and Select circuits to identify when to energize the A/C relay. The A/C relay provides the A/C compressor clutch with battery voltage, when energized. Besides the A/C Request and Select circuits, the PCM uses the following inputs to determine when the A/C relay should be energized:

- Engine speed
- TPŠ

- A/C pressure switches
- ECT sensor
- Engine Running Timer

### **TRANSMISSION CONTROL**

The RE transmission Powertrain Control Module (PCM) controls operation of the converter clutch, overdrive clutch, and governor pressure solenoid. It determines transmission shift points based on input signals from the transmission thermistor, transmission speed sensor, engine speed sensor, vehicle speed sensor and throttle position sensor. Operating voltage is 12 volts, and is provided through the battery terminal on the PCM. The ignition voltage signal is provided through PCM terminal.

**NOTE:** The following pages of this student reference book describe each section in detail. The function and operation of the inputs and outputs are explained the first time each input or output is introduced. Subsequent sections will elaborate on any input or output not previously described.

#### **CONNECTOR REPAIR**

Poor electrical connections can cause intermittent complaints which can be very difficult to diagnose. Once diagnosed, the repair can range from simply reconnecting an electrical connector, to complete wiring harness replacement. The following drivetrain electrical connector repair components have recently been made available to aid in drivetrain electrical repairs without replacing a complete harness. If it is determined that a customer complaint could be related to a poor electrical connection, use the following diagnosis to inspect the electrical connectors.

#### **Diagnosis:**

This information pertains to electrical connections for the following components:

- Throttle Position Sensor (TPS)
- Oxygen (O2) sensor
- Crankshaft Position (CKP) sensor
- Vehicle Speed Sensor (VSS)
- Ignition coil
- Purge solenoid
- Engine Coolant Temperature (ECT) sensor and gauge sending unit
- Manifold Absolute Pressure (MAP) sensor
- Camshaft Position ("Sync") sensor
- Fuel injector
- Idle Air Control (IAC) motor
- Transmission solenoid (eight-way)

Inspecting the connectors begins with a thorough check of the insulator. If the insulator locking tab is damaged or broken, replace the insulator. If the insulator end seal or seal ring is damaged, replace the seal. Gently pull on one wire of the connector at a time. If the wire pulls out of the insulator, remove and inspect the wedge lock. Also inspect the locking tab inside the insulator. Replace the wedge lock if there are any signs of damage.

Inspect all wire terminals for corrosion. If corrosion is evident, replace the terminal ends and both insulator seals. To verify how securely the terminal fits to the component, insert and remove the harness side connector terminals onto the mating terminal of the component. Then, rotate the terminal 90°, 180° and 270° while inserting and removing the harness side connector terminal onto the pin(s) of the component. **Check each unique terminal-to-pin connection for any multi-terminal connector.** 

If any connection is loose, replace the harness side connector terminal after verifying a good connection with the new terminal. For information regarding service procedures for electrical connectors, refer to Section 8W of the appropriate Service Manual.

Component	Insulator Part Number	Terminal Part Number	Wedge Lock Part Number	End Seal Part Number	Ring Seal Part Number
Throttle Position and Vehicle Speed Sensors	4450545	4625130	4450091	4450092	4450093
Manifold Absolute Pressure Sensor	4450090	4625130	4450091	4450092	4450093
Upstream Oxygen Sensor	4707126	4400110	N/A	N/A	N/A
Downstream Oxygen Sensor	4707127	4400110	N/A	N/A	N/A
Crank Position Sensor (MANUAL TRANSMISSION)	56016982	4604597	56016987	4414474	56016985
Crank Position Sensor (AUTO TRANSMISSION)	56016983	4604597	56016987	4414474	56016985
Crank Position S	ensor Retainer I	P/N 56016988			
Camshaft Position Sensor	4414468	4604597	4414470	4414474	56017460
Engine Coolant Temperature Sensor (3.9L, 5.2L and 5.9L)	56006291	4558005	N/A	N/A	N/A

### **Parts Required:**

Component	Insulator Part Number	Terminal Part Number	Wedge Lock Part Number	End Seal Part Number	Ring Seal Part Number
Engine Coolant Temperature Gauge Sending Unit	56006431	4558005	N/A	N/A	N/A
Intake Air Temperature Sensor	4414270	4331568	N/A	N/A	N/A
Oil Pressure Sensor	4414048	4625130	4414024	4414047	4414049
Fuel Injector	4604512	N/A	N/A	N/A	4604519
Ignition Coil	4481614	4625130	4414024	4414047	4414049
Idle Air Control Motor	56018428	4331568	N/A	N/A	N/A
Purge Solenoid	4661957	4604597	4661974	N/A	N/A
Transmission Solenoid	56017053	56017057	N/A	N/A	N/A

### **LESSON 2**

### **FUEL DELIVERY SYSTEM**

#### **FUEL TANK**

#### Fuel Tank — 96 AN

The fuel tank for this vehicle is located on the driver's side of the vehicle. It is made from high-density polyethylene (HDPE) material. There are no rollover valves on the tank. The single rollover valve is located on the fuel pump module.

#### Fuel Tank — 97 AN

This fuel tank is located on the driver's side of the vehicle and is made from High-Density Polyethylene (HDPE) material. There is one rollover valve located on the tank. There is no longer a rollover valve in the pump module. This valve prevents fuel flow through the vent valve hose that serves the evaporative canister.

#### Fuel Tank — 96 AB

The fuel tank for the RAM van is located across the rear of the vehicle. It is made from high-density polyethylene (HDPE) material. There are no rollover valves on the tank. The single rollover valve is located on the fuel pump module.

#### Fuel Tank — 97 AB

This fuel tank is also located across the rear of the vehicle. It is made from highdensity polyethylene (HDPE) material. New for 1997 are two interconnected rollover valves located in the top of the tank. Both of these valves may be serviced by prying them out of the grommet.

#### Fuel Tank — BR

The fuel tank for the RAM pickup truck is located on the driver side of the vehicle. It is made from high-density polyethylene (HDPE) material. There are no rollover valves on the tank. The single rollover valve is located on the fuel pump module and may be serviced separately.

#### Fuel Tank — ZJ

The fuel tank for the Grand Cherokee is located across the rear of the vehicle. The tank is made from HDPE material. There is one rollover valve welded in the top of the tank. This valve prevents fuel flow through the vent valve hose serving the evaporator canister.

### FUEL PUMP MODULE

The  $Jeep_{\circledast}/Truck$  fuel pump module is an in-tank unit with an integral fuel-level sensor and pressure regulator. The pump is driven by a 12-volt DC motor, anytime the fuel pump relay is energized. Serviceable components on the module may be:

- Inlet strainer.
- Fuel level sensor.
- Fuel filter/pressure regulator.

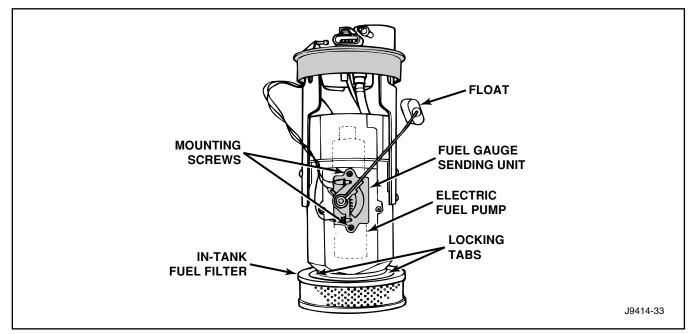


Figure 4 1996 Typical Dodge Truck Fuel Pump Module

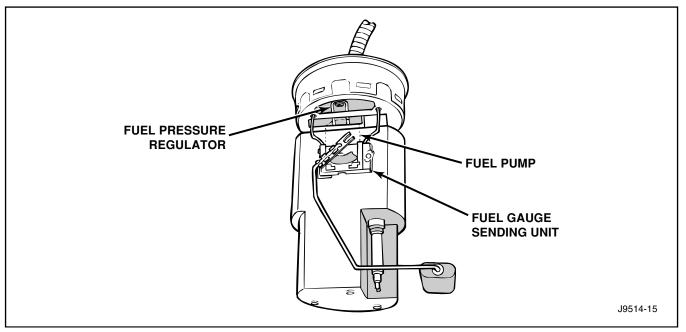


Figure 5 1996 ZJ Fuel Pump Module

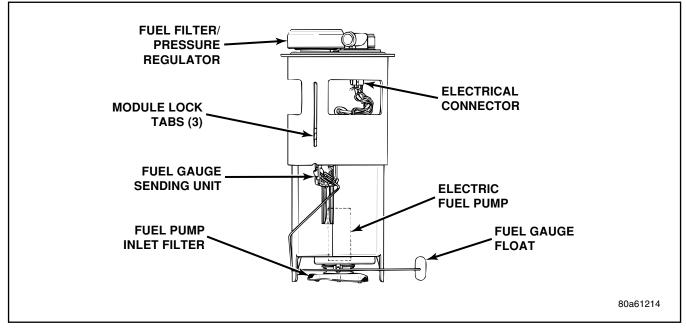


Figure 6 Typical 1997 Dodge Truck Fuel Pump Module

The pump draws fuel through a strainer and pushes it through the motor to the outlet. The pump contains two check valves. One valve relieves internal fuel pump pressure and regulates maximum pump output. The second valve, in the pump outlet, maintains pump pressure during engine-off conditions.

### **CHECK VALVE OPERATION**

The electric fuel-pump outlet contains a one-way check valve to prevent fuel flow back into the tank and to maintain fuel supply-line pressure (engine warm) when the pump is not operational. It is also used to keep the fuel supply line full of gasoline when the pump is not operating. After the vehicle has cooled down, fuel pressure may drop to 0 psi (cold fluid contracts), but liquid gasoline will remain in the fuel supply line between the check valve and the fuel injectors. Fuel pressure that has dropped to zero psi on a cooled-down vehicle (engine off) is a normal condition. When the electric fuel pump is activated, fuel pressure should immediately rise to specification.

The fuel systems use a positive displacement, gerotor, immersible pump with a permanent magnet electric motor. Figures 4, 5 and 6 illustrate the other fuel pump modules.

This fuel system does not contain the traditional fuel return lines. The regulator contains a calibrated spring, which forces a diaphragm against the fuel filter return port. When pressure exceeds the calibrated amount, the diaphragm retracts, allowing excess pressure and fuel to vent into the tank.

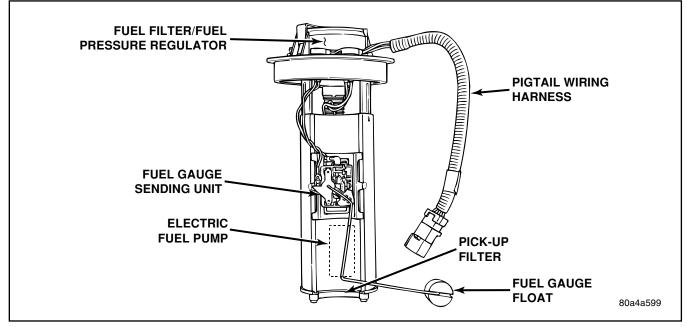


Figure 7 Typical 1997 Jeep<sub>®</sub> Fuel Pump Module

If the fuel delivery system becomes blocked between the fuel pump and the regulator, the maximum deadhead pressure of the pump is approximately 880 kPa (130 psi). The regulator adjusts fuel system pressure to approximately 338 kPa ( $49 \pm 5$  psi).

A fuel gauge level sending unit is attached to the fuel pump module. The fuel level input is used as an input for OBD II. Fuel level below 15% or above 85%, on LDP-equipped vehicles, of total tank capacity disables several monitors. There are diagnostics for the fuel level circuit open and shorted (Table 1).

Diagnostic	DTC	MIL
OBD II Major Monitors	Disabled	Disabled
Front O2S Voltage Checks	Active	Active
Rear O2S Voltage Checks faults	Active	Active
Front/Rear O2 Heater	Active	Active
VSS Rationality	Disabled	Disabled
P/N Switch Rationality	Disabled	Disabled

Table 1Fuel Level Diagnostics

**WARNING:** Be very careful when removing the fuel pump module from the fuel tank as gasoline remaining in the module reservoir will spill.

### FUEL PRESSURE REGULATOR

### Fuel Pressure Regulator — Chrysler

All Jeep<sub>®</sub> and Dodge truck vehicles use a returnless fuel system. On a return system, all fuel is routed through the hot environment of the engine compartment. Without a return line, the fuel remains in the tank and is cooler. This reduces evaporative emissions, resulting in less evaporative canister purging.

Returnless fuel systems do not have a return line routed from the fuel rail to the fuel tank. The pressure regulator is part of the fuel pump module (figs. 9 and 10). It is part of a filter/regulator assembly on some vehicles and a separate piece on others (fig.8).

The pressure regulator is a mechanical device that is not controlled by the PCM. The regulator contains a calibrated spring and a diaphragm that actuates the regulator valve. Fuel pressure operates on one side of the diaphragm, while spring pressure operates on the other side. The diaphragm opens the valve to the return port, allowing fuel to be dumped back into the fuel tank. System fuel pressure reflects the amount of fuel pressure required to open the port. The spring on the opposite side of the diaphragm attempts to close the valve, causing an increase of pressure on the fuel as it travels to the fuel rail. The spring is not adjustable and is calibrated to maintain approximately 338 kPa ( $49 \pm 5$  psi) of fuel pressure.

In the past, the regulator was mounted on the fuel rail so that as the manifold vacuum at the tip of the injector changed, fuel pressure was modified to maintain a constant injector flow volume. With the regulator mounted at the tank, a constant fuel pressure is always supplied to the injectors. The PCM uses a special formula using MAP information, that calculates the pressure differential across the injector and then adjusts injector pulse width.

### **Fuel Flow**

Depending upon the vehicle, the fuel flow is as follows:

- **Remote-mounted filter (two hoses)** Fuel flows from the pump to the filter. From the filter, it flows to the fuel rails. The regulator in the tank maintains the  $49 \pm 5$  psi in the filter and lines.
- **Integral filter** Fuel flows from the pump, through the regulator, through the filter to the fuel rail.

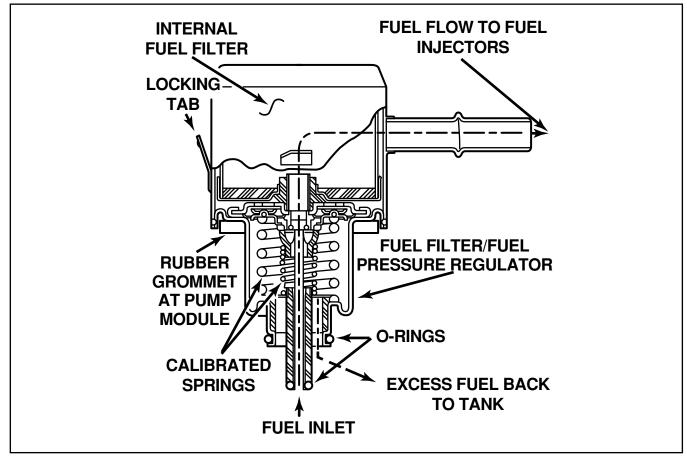


Figure 8 Typical One-Piece Filter/Regulator

### FUEL PUMP RELAY

The fuel pump relay is located inside the Power Distribution Center (PDC). It is energized to provide power to operate the fuel pump under the following conditions:

- For approximately 1.8 seconds during the initial key-on cycle.
- While the CKP sensor is providing an RPM signal that exceeds a predetermined value.

Ignition voltage is provided to the fuel-pump relay coil anytime the key is in the RUN/START position (fig. 9). The PCM provides the ground control to energize the relay. Unlike previous Chrysler systems (non-OBD II), the fuel pump relay does not provide power to operate the O2 Sensor heater.

The relay is energized when the key is cycled to RUN to prime the fuel rail with liquid fuel, allowing for a quick start-up. Anytime the CKP sensor indicates that an RPM signal exceeds a predetermined value, the relay is energized to ensure proper fuel pressure and volume during engine cranking and running conditions. Anytime the CKP sensor signal is lost (engine has been shut off or the sensor indicates no rpm), the fuel pump relay is de-energized.

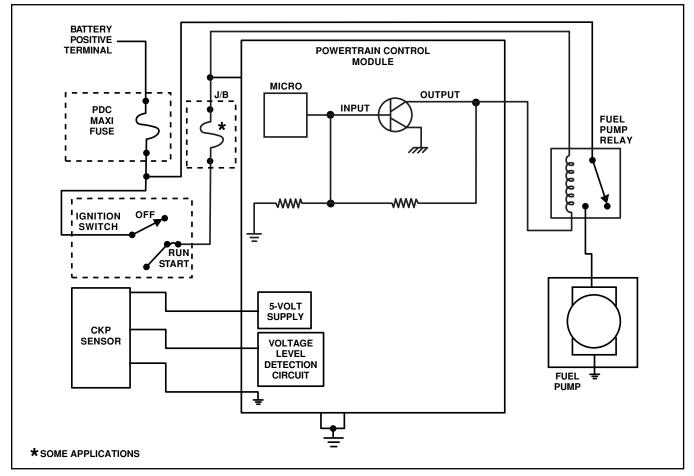


Figure 9 Fuel Pump Relay Circuit

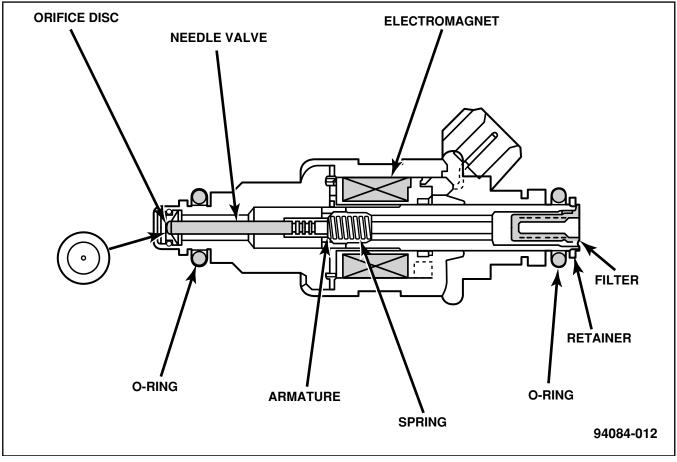
### **FUEL INJECTORS**

**WARNING:** Release fuel system pressure before servicing fuel system components. The procedure is described in the Service Manual. Service vehicles and fuel system components in well-ventilated areas. Avoid sparks, flames and other ignition sources. Never smoke while servicing the vehicle's fuel system.

The 3.9L, 5.2L and 5.9L engines use top-feed fuel injectors mounted to the fuel rail with push-on retaining clips. O-rings prevent leakage between the injectors and the fuel rail.

The fuel injectors are 12-ohm electrical solenoids. Each injector contains a needle valve that closes off an orifice at the nozzle end. When electrical current is supplied to the injector, the armature and needle move a short distance against a spring, allowing fuel to flow out the orifice. Because the fuel is under high pressure, a fine spray is developed in the shape of a hollow cone. The spraying action atomizes the fuel, adding it to the air entering the combustion chamber (fig. 10).

The fuel injectors are positioned in the intake manifold with the nozzle ends directly above the intake valve port for the corresponding cylinder.



Fuel is dispersed through one opening at the bottom of each injector (fig. 10). This design allows for an atomized spray, similar to that of a pintle injector, but with the low cost and easy serviceability of a pencil-stream injector.

#### **FUEL FILTER**

There are two different types of fuel filters. One is integral with the fuel pressure regulator and attaches to the fuel pump module. The other is mounted just outside the tank. The remote filter has two lines attached to it. Both filters are life-of-thevehicle items. Replacement is necessary, only if something has caused the filter to become plugged, such as contaminants in the fuel. Regular maintenance is no longer required because only the fuel actually being used by the engine is filtered.

#### **FUEL LINES AND RAIL**

#### **Fuel Lines**

The high-pressure line from the tank to the filter or engine is a combination of rubber, plastic and steel lines. The hose clamps used to secure rubber hose sections have a special rolled edge construction to prevent the edge of the clamp from cutting into the hose.

**NOTE:** If the O-rings at the quick-connect fittings become damaged, the line must be replaced.

**NOTE:** Always lubricate the O-rings inside the quick-connect fittings with engine oil, before reassembling the fuel line connections at the fuel pump module, fuel filter, fuel lines and the fuel rail.

### **Fuel Rail**

The fuel rail assembly is mounted on the intake manifold and is attached to the fuel line with a quick-connect fitting (fig. 11).

### **Metal Fuel Rail**

If the O-rings on the fuel line become damaged, the line must be replaced.

### **Plastic Fuel Rail**

If the O-rings inside the fuel rail are damaged, the fuel rail must be replaced. A fuel pressure test port is provided on some applications at the center of the fuel rail, to enable fuel pressure testing. Always follow the procedures in the Service Manual when removing fuel system components.

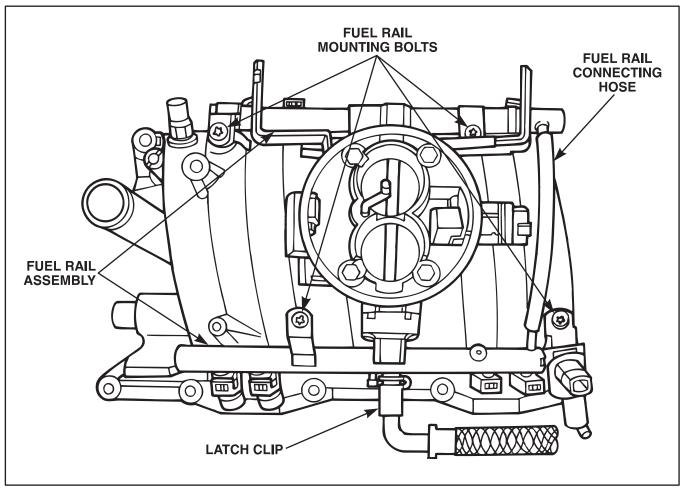


Figure 11 Fuel Rail — V6/V8 Engines

**WARNING:** The clips used to hold the injectors to the fuel rail are for assembly only. The clips are not designed to hold the injectors on with 49 psi of fuel pressure.

### **THROTTLE BODY**

The throttle body mounts to the intake manifold. These models use a contoured (tapered bore) throttle body (fig. 12).

The contoured throttle body changes air velocity slightly with moderate pedal movement. The first 1/3 of opening takes a lot of throttle movement, then opening occurs much faster. This helps reduce buck and bobble at light throttle positions.

The Throttle Position Sensor (TPS), MAP sensor and Idle Air Control (IAC) motor are attached to the throttle body.

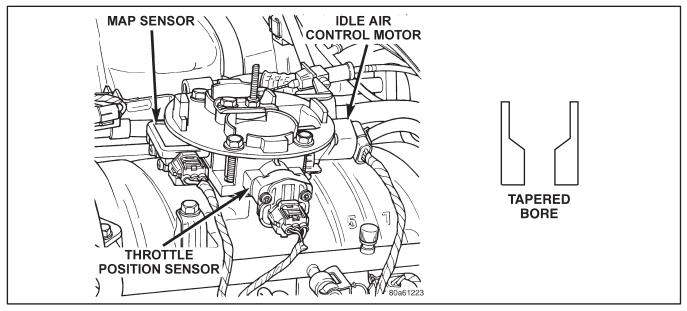


Figure 12 V6/V8 Throttle Body

### ACTIVITY 1 — FUEL SYSTEM TEST

### Instructions

Have the instructor assign you to a vehicle equipped with either a V6 or V8 engine. Use the Service Manual and DRB III to assist in answering the following questions:

- 1. In which section of the Service Manual will you find the fuel system test procedures?\_\_\_\_\_
- 2. According to the Service Manual, what is the fuel pressure specification for the V6/V8?
- 3. The following questions pertain to releasing the fuel system pressure.

What could happen if the gas cap is not removed from the fuel tank before starting this procedure?

The procedure in the Service Manual identifies the first step in releasing fuel system pressure as "removing the fuel pump relay." Where is the relay located?

- 4. List the appropriate tools required to depressurize and test the fuel system.
- 5. Following the procedure listed in the Service Manual, depressurize the fuel system on the assigned vehicle and connect the appropriate tools. Using the DRB, access the Actuator Test for Fuel System Test. Perform the fuel pressure test. What is the fuel system pressure of the vehicle?

What is the DRB III doing to accomplish this test?\_\_\_\_\_

After completing this task, return the vehicle to its original state.

### **LESSON 3**

### **POWERTRAIN CONTROL MODULE**

#### **POWER SUPPLIES AND GROUNDS**

In order to function, the PCM must be supplied with battery voltage and a ground (fig. 13). The PCM monitors battery voltage during engine operation. If the voltage level falls, the PCM increases the initial injector opening point to compensate for low voltage at the injector. Low voltage causes a decrease in current flow through the injector and can prevent the injector plunger from fully opening in the allotted time, resulting in decreased fuel flow.

Battery charging rate is controlled by the PCM. The target charging rate voltage is based upon inputs from Battery Temperature Sensor (BTS). The BTS is located in the bottom of the battery tray.

The PCM must be able to store diagnostic information. This information is stored in a battery-backed RAM. Once a DTC is read by the technician, the technician can clear the RAM, by disconnecting the battery for approximately 60 seconds or using the DRB III scan tool.

The PCM has two power inputs: direct 12 volts and switch ignition 12 volts. Battery voltage is supplied to the PCM to power the 5-volt power supply and allow the PCM to perform fuel, ignition and emission control functions. The PCM monitors this direct battery-feed input to determine charging rate, control the injector initial opening point, and back up the RAM used to store the DTC functions. This is called sensed battery and will be discussed later.

When the ignition switch is turned ON, the 12-volt input acts as a "wake up" signal to an integrated circuit that then turns on the power supply.

The power supply output of 5 volts supplies multiple locations within the controller and is also used as the reference voltage for sensor operation. Some of the locations within the controller that use 5 volts are all of the microprocessors. Another output of the 5-volt power supply is a line that is split to make the primary and secondary 5-volt outputs; pins A17 and B31 respectively.

The primary output is used as a reference voltage for the TPS and MAP sensor as well as a power supply to operate the CMP and CKP sensors. The secondary output is used as a reference voltage for the transmission governor pressure transducer when equipped with an RE transmission. It is also used as a power supply for the VSS.

Another use of the power supply is a reference voltage for the internal use of the PCM. The microprocessors determine current sensor state by comparing the sensor signal to the reference voltage. The difference between the two voltages equals the sensor state.

The PCM has two grounds, both are identified as power grounds. All the high current, noisy devices are connected to these grounds as well as all the sensor returns. The sensor return comes in, passes through noise suppression and is then connected to the power ground.

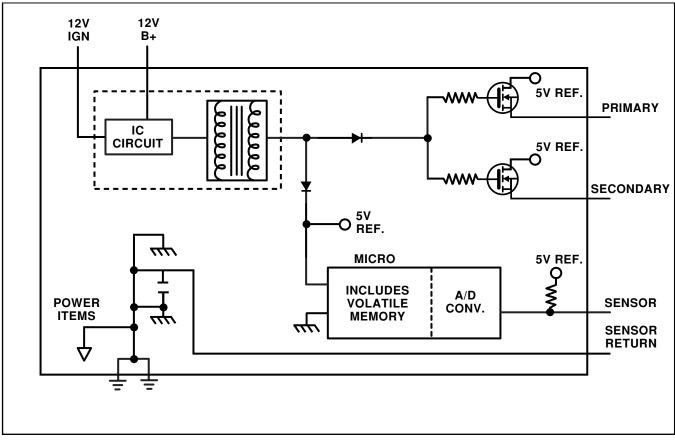


Figure 13 Power Supplies and Grounds

### **CCD Bused Messages**

In 1996, the Grand Cherokee was the only  $Jeep_{\otimes}/Dodge$  product using the Chrysler Collision Detection (CCD) data bus system (figs. 14 and 15). In 1997, Dodge Dakota trucks also began using this system.

The CCD bus passes information collected by the PCM to the instrument cluster. This eliminates the need for both the PCM and the instrument cluster to receive the same inputs. The ZJ also uses the information to send information from the A/C control head via the Body Control Module (BCM) to the PCM. The following is a list of inputs and outputs that are transmitted by the CCD bus:

- Engine RPM
- Fuel level
- A/C Select
- Oil pressure
- Vehicle speed
- Coolant temperature
- Voltage
- Transmission temperature
- Engine model
- Upshift lamp
- Vehicle Identification Number (VIN)
- Speed control enable
- Check Engine light operation
- Check gauges light operation

The Powertrain Control Module also uses information, such as fuel level. This input is used by the PCM Task manager for On Board Diagnostics II (OBD II). If a vehicle is equipped with Theft Alarm, an "OK to start" message is bused from the security alarm module to the PCM.

The PCM also delivers fault code information to the instrument cluster. This information is used for Malfunction Indicator Lamp (MIL) illumination and Diagnostic Trouble Code (DTC) retrieval.

### **Data Link Connector**

The PCM maintains communication with scan tools through the vehicle Data Link Connector (DLC). The DLC connector is located under the instrument panel, to the left of the steering column bracket.

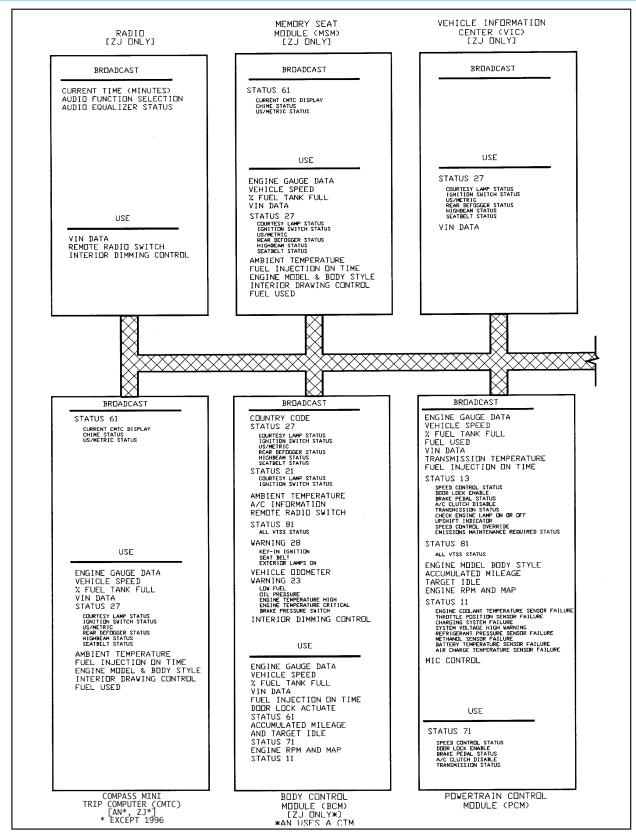


Figure 14

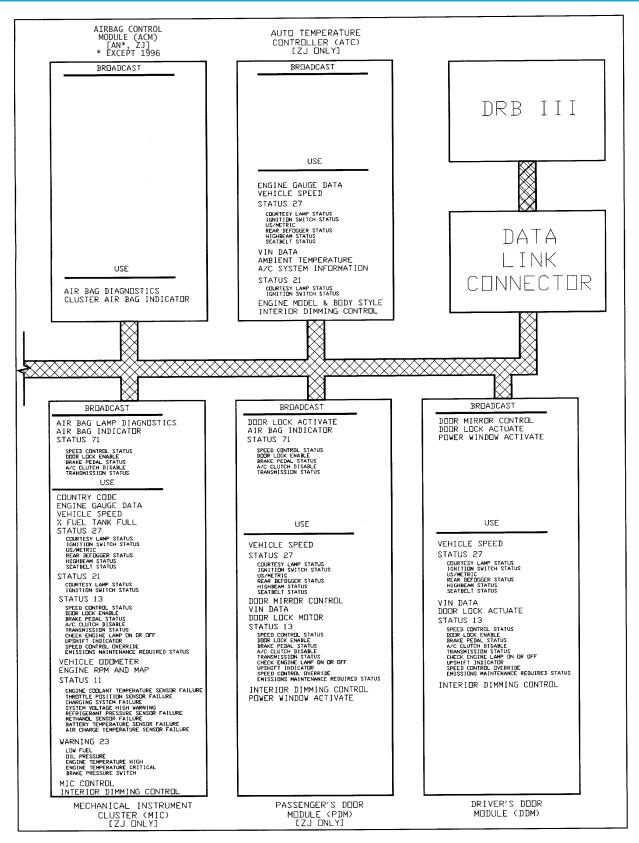


Figure 15

### **ACTIVITY 2 — PCM POWER AND GROUNDS**

### **Instructions**

Have the instructor assign you to a vehicle equipped with either a V6 or V8 engine. Use the Service Manual and the Powertrain Diagnostic Procedures manual to assist in answering the following questions.

1. Can the PCM connectors be interchanged?
--

- 2. Are the connectors numbered?
- 3. Using the Powertrain Diagnostic Procedures manual, what are the pins for power?
- 4. Using a voltmeter, and with key off, what is sensed battery ignition?
- 5. Turn the key on. What is sensed battery voltage?
- 6. Reverse the leads on the voltmeter. Identify the ground pins and probe them for voltage. What are the voltage readings?
- 7. Hook up DRB III to engine. What does the learned vehicle configuration show?

### **LESSON 4**

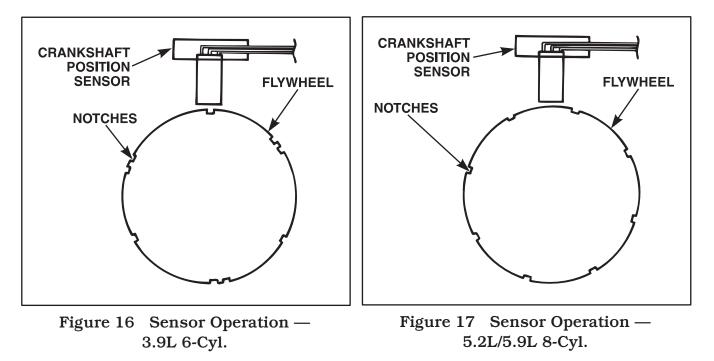
### **FUEL INJECTION SYSTEM — PCM INPUTS**

### **CRANKSHAFT POSITION SENSOR**

The 3.9L/5.2L/5.9L engines use a Hall-effect Crankshaft Position (CKP) sensor as a PCM input (figs. 16 and 17). The Hall-effect crankshaft position sensor is mounted on the transmission bell housing where it detects the passing of slots on the flywheel. The signal generated provides crankshaft position information to the engine controller and is used in conjunction with the sync signal to synchronize fuel injection and timing.

The PCM uses the crankshaft position sensor to calculate the following:

- Engine rpm
- TDC 3.9L — Nos. 1 and 4, 6 and 3, 5 and 2 5.2L/5.9L — Nos. 1 and 6, 8 and 5, 4 and 7, and 3 and 2
- Ignition timing
- Injector synchronization



### **V6/V8**

The engine will not operate if the PCM does not receive a crankshaft position sensor input.

The PCM sends approximately 5 volts to the Hall-effect sensor. This voltage is required to operate the Hall-effect chip and the electronics inside the sensor. A ground for the sensor is provided through the sensor return circuit.

The input to the PCM occurs on a 5-volt reference circuit (fig. 18) that operates as follows: The Hall-effect sensor contains a powerful magnet. As the magnetic field passes over the metal between the slots, the 5-volt signal is pulled to ground (0.3 volt) through a transistor in the sensor. When a flywheel slot passes the sensor's magnet, the magnetic field turns off the transistor in the sensor, causing the PCM to register the 5-volt signal. The PCM identifies crankshaft position by registering the change from 5 to 0 volt.

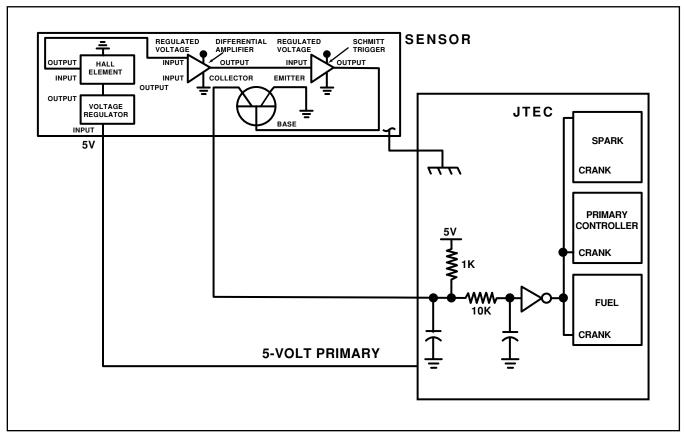


Figure 18 Crankshaft Position Sensor Circuit

### **3.9L**

The flywheel has six sets of notches at its outer edge (fig. 19). Three sets are double notches and the other three are single notches. The double notches represent TDC compression and are used to determine ignition coil firing. The single notches represent TDC exhaust and are used to synchronize injector firing (figs. 20 and 21).

The 3.9L engine uses a 90° block. This means that the combined angle of the bore center lines of the opposing banks is 90° and that a piston comes up to TDC every 90 degrees. With only six cylinders, each one would be fired in 540° of crankshaft rotation (6 x 90 = 540). To match cylinder firing with crankshaft rotation, it was necessary to make an "odd fire" engine. This means that all the cylinders are not fired at the same amount of crankshaft rotation. Three of them are fired 112° and the other three are fired 128°. All of these angles added together total 720° or two complete crankshaft revolutions. Because of the odd firing, it is necessary to have the double notches to properly stagger spark timing.

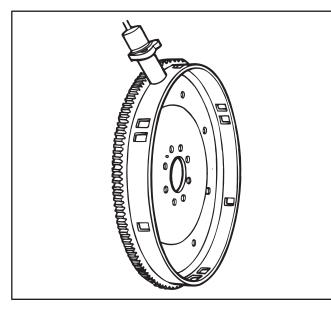


Figure 19 V6 Crankshaft Sensor

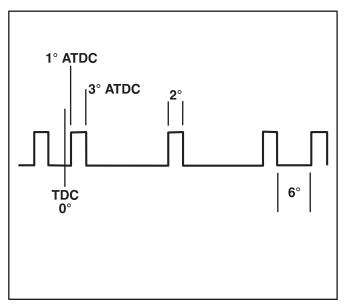


Figure 20 3.9L Crankshaft Syncs

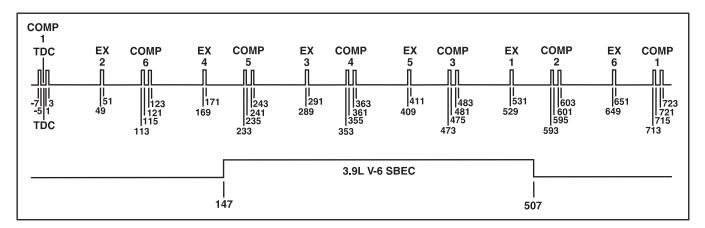
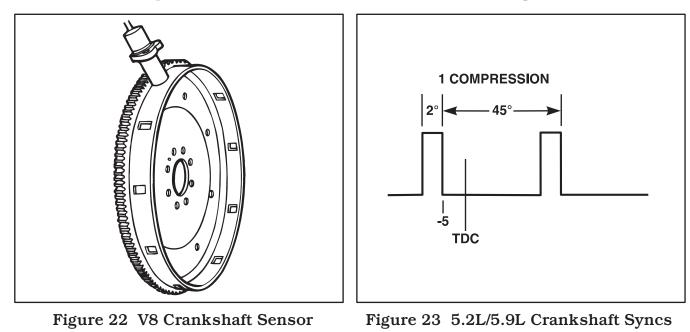


Figure 21 Crankshaft Position Sensor Notches — 3.9L

### **V8**

The flywheel has eight equally spaced notches at its outer edge (fig. 22). Every other notch represents a cylinder coming to Top Dead Center (TDC). However, if the first notch is TDC compression, the second notch is TDC exhaust (figs. 23 and 24).



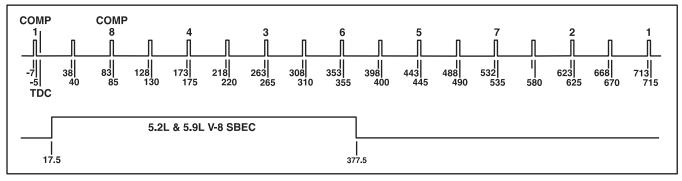


Figure 24 Crankshaft Position Sensor Notches — 5.2L/5.9L

### **Crankshaft Position Sensor Service**

The sensor's powerful magnet is susceptible to damage. Do not drop the sensor on a metal table, or store sensors face to face. The clearance between the sensor and the counterweight is not adjustable. Though the clearance is critical, manufacturing tolerances allow for some differences in clearance.

#### In order for the vehicle to start, both the cam and crankshaft position sensor signals must be present. On eight-digit part number PCMs, both the cam and crankshaft position sensor signals are necessary for continued operation.

On 10-digit part number PCMs, once the engine is running, the cam sensor signal is not needed for continued operation.

### **CAMSHAFT POSITION (SYNC) SENSOR**

The PCM sends approximately 5 volts to the Hall-effect sensor. This voltage is required to operate the Hall-effect chip and the electronics inside the sensor. A ground for the sensor is provided through the sensor return circuit. The input to the PCM occurs on a 5-volt output reference circuit (fig. 25). The CMP sensor operates the same as the CKP sensor, except that there are only two edges to detect. The PCM identifies camshaft position by registering the change from 5 to zero volts or zero to 5 volts, as signaled by the camshaft position sensor.

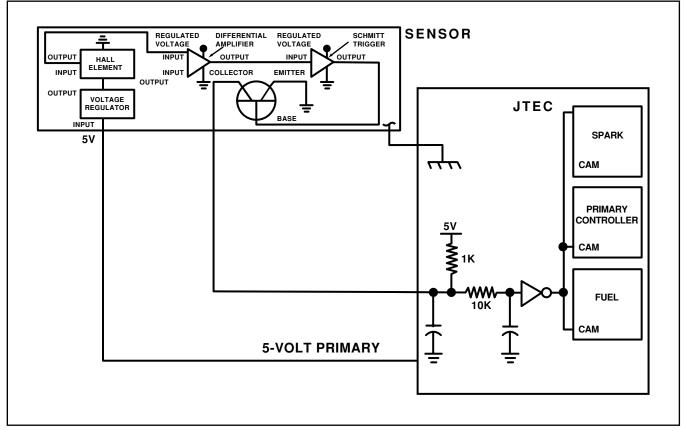


Figure 25 Camshaft Position Sensor Circuit

The PCM determines fuel injection synchronization and cylinder identification from inputs provided by the camshaft position sensor and crankshaft position sensor. From the two inputs, the PCM determines crankshaft position (figs. 26 and 27).

In order for the vehicle to start, both the CMP and CKP sensor signals must be present. On 1996 vehicles, both CMP and CKP sensor signals are necessary for continued engine operation.

On 1997 vehicles, once the engine is running, the CMP sensor signal is not needed for continued engine operation.

#### **SYNC SIGNAL**

#### **3.9L**

Proper firing order is maintained by locating pistons 5 and 2. As the pulse ring rotates in the distributor, it passes through a Hall-effect sensor. When the pulse ring (leading edge) enters the Hall-effect sensor, the output voltage of the Hall-effect goes to five volts, indicating the position of piston No. 5. When the pulse ring (trailing edge) leaves the Hall-effect sensor, the output voltage goes to 0.3 volt, indicating the position of piston No. 2. The engine controller receives this information and is able to determine the proper injection firing sequence (fig. 26). The PCM can begin firing the injectors in the proper sequence and at the proper time.

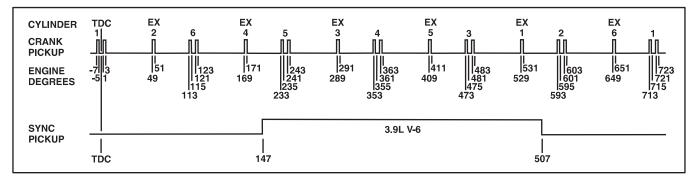


Figure 26 V6 Injector Pulse Widths

#### 5.2L/5.9L

Proper firing order is maintained by locating pistons 8 and 5. As the pulse ring rotates in the distributor, it passes through a Hall-effect sensor (fig. 27). When the pulse ring (leading edge) enters the Hall-effect sensor, the output voltage of the Hall-effect goes to five volts, indicating the position of piston No. 8. When the pulse ring (trailing edge) leaves the Hall-effect sensor, the output voltage goes to 0.3 volt, indicating the position of piston No. 5. The engine controller receives this information and is able to determine the proper injection firing sequence (fig. 28). The PCM can begin firing the injectors in the proper sequence and at the proper time.

The engine controller always opens an injector when a piston is on the exhaust stroke. This allows time for the fuel to enter the intake manifold and thoroughly mix with incoming air during the intake stroke.

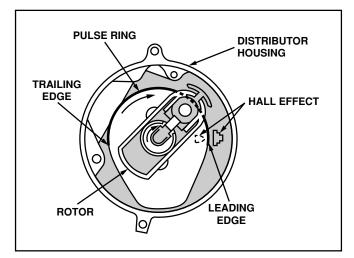


Figure 27 Camshaft Position (Hall-Effect) Sensor

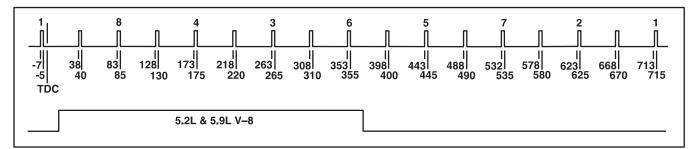


Figure 28 V8 Injector Pulse Widths

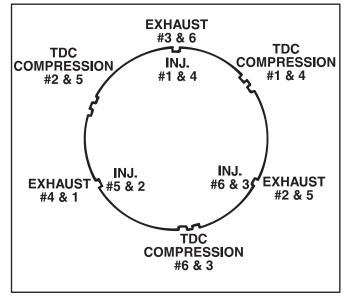
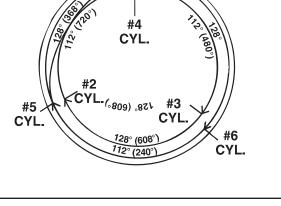


Figure 29 3.9L Injector Firing Sequence



#1

CYL.

Figure 30 3.9L Ignition Coil Firing Sequence

#### **DISTRIBUTOR PLACEMENT**

The PCM utilizes the hall-effect sensor in the distributor to identify TDC compression (fig. 29), so that it can properly synchronize the fuel and spark strategies to the mechanical events occurring in the cylinder (fig. 30).

The PCM is controlling the base ignition timing and spark advance based on the input from the CKP. Therefore, rotating the distributor will not change ignition timing, however, it will change the relationship of the distributor rotor tip to the distributor cap tower terminal. If the distributor is rotated too far, a crossfire condition may occur, especially under light-load, high-spark advance conditions. Crossfire occurs when the rotor is aligned closer to the terminal adjacent to where it should be, causing a surge, bucking or misfire condition.

Refer to the service manual for the correct distributor installation procedure.

#### **CAM/CRANK DIAGNOSIS**

In order for the PCM to diagnose either the CAM or CRANK sensor signals, one of the signals must be present.

### **ACTIVITY 3 — CAMSHAFT POSITION SENSOR ACTIVITY**

### **3.9L**

The camshaft position sensor (sync) is located in the distributor.

### Activities

- 1. Find the sensor and unplug the connector. Using voltmeter, what is the voltage at pins A18 and A17?
- 2. Connect DRB III and select monitors. What is the voltmeter reading of pin A4?
- 3. Crank engine. What does the DRB III indicate for CMP state?
- 4. Using a voltmeter, measure the voltage on the three wires of the harness side connector. What are the voltages?
- 5. Plug the connector together and change the DRB III to read DTCs. What DTC is present and why? \_\_\_\_\_\_

If the CMP sensor wire was shorted to ground, what DTC would be present? \_\_\_\_\_

- 6. Crank engine. What does the DRB III indicate for CMP state? \_\_\_\_\_
- 7. Short the 5 volts to ground. What does voltmeter read?

Remove the grounded circuit.

8. Turn key off and wait about five seconds. Turn key on. What does voltmeter read?

### 5.2L/5.9L

The camshaft position sensor (sync) attaches to the rear of the cylinder head.

### Activities

- 1. Find the sensor and unplug the connector. Using voltmeter, what is the voltage at pins A18 and A17?
- 2. Connect DRB III and select monitors. What is the voltmeter reading of pin A4?
- 3. Crank engine. What does the DRB III indicate for CMP state?
- 4. Using a voltmeter, measure the voltage on the three wires of the harness side connector. What are the voltages?
- 5. Plug the connector together and change the DRB III to read DTCs. What DTC is present and why? \_\_\_\_\_\_

If the CMP sensor wire was shorted to ground, what DTC would be present?

- 6. Crank engine. What does the DRB III indicate for CMP state?
- 7. Short the 5 volts to ground. What does voltmeter read?\_\_\_\_\_

Remove the grounded circuit.

8. Turn key off and wait about five seconds. Turn key on. What does voltmeter read?

### **MANIFOLD ABSOLUTE PRESSURE (MAP) SENSOR**

The MAP signal serves as a PCM input, using a silicon-based sensing unit to provide data on the manifold vacuum that draws the air/fuel mixture into the combustion chamber. The PCM requires this information to determine injector pulse width and spark advance. When MAP voltage (engine running) equals the voltage seen when barometric pressure was learned or updated, the pulse width will be at maximum.

Also, like the cam and crank sensors, 5 volts is supplied from the PCM and the MAP sensor returns a voltage signal to the PCM that reflects manifold pressure (fig. 31). The MAP sensor operating range is from 0.45 volt (high vacuum) to 4.8 volts (low vacuum). The sensor is supplied a regulated 4.8 to 5.1 volts to operate the sensor. Like the cam and crank sensors, ground is provided through the sensor return circuit.

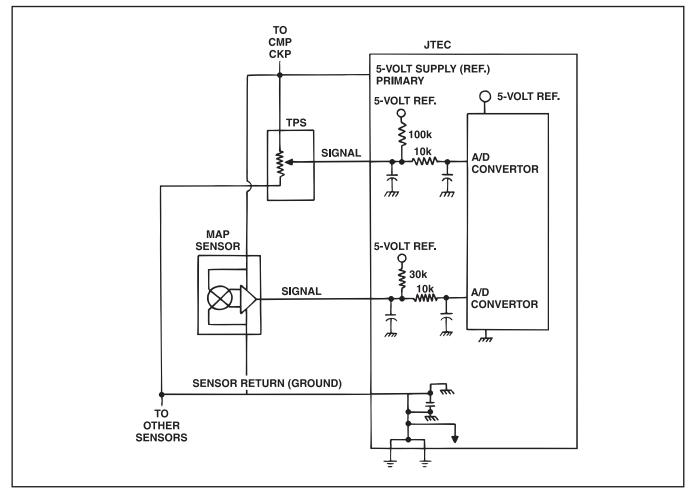


Figure 31 Manifold Absolute Pressure Sensor Circuit

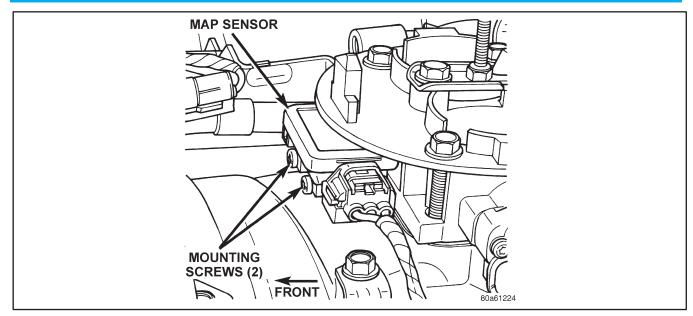


Figure 32 Manifold Absolute Pressure Sensor Location

The MAP sensor input is the number one contributor to pulse width. An important function of the MAP sensor (fig. 32) is to determine barometric pressure (fig. 33). The PCM needs to know if the vehicle is at sea level, or in Denver at 5,000 feet above sea level, because the air density changes with altitude. It will also help to correct for varying weather conditions. This is important, because as air pressure changes, barometric pressure changes. Barometric pressure and altitude have a direct inverse correlation — as altitude goes up, barometric pressure goes down. The first thing that happens as the key is rolled on, before reaching the crank position, the PCM powers up, comes around and looks at the MAP voltage, and based upon the voltage it sees, it knows the current barometric pressure relative to altitude.

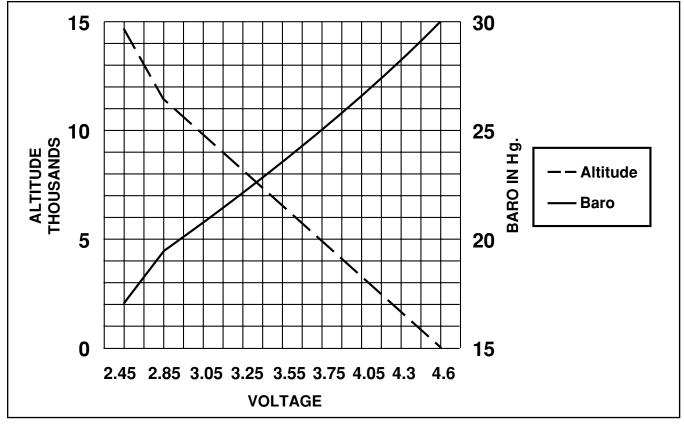


Figure 33 MAP Sensor Voltage Values

Once the engine starts, the PCM looks at the voltage again at the trailing edge of the last slot on the current cylinder and the leading edge of the first slot of the next cylinder. These two values are added and then divided by 2 to get an average. It then averages these signals and compares the current voltage to what it was at key ON. The difference between current and what it was at key ON is manifold vacuum.

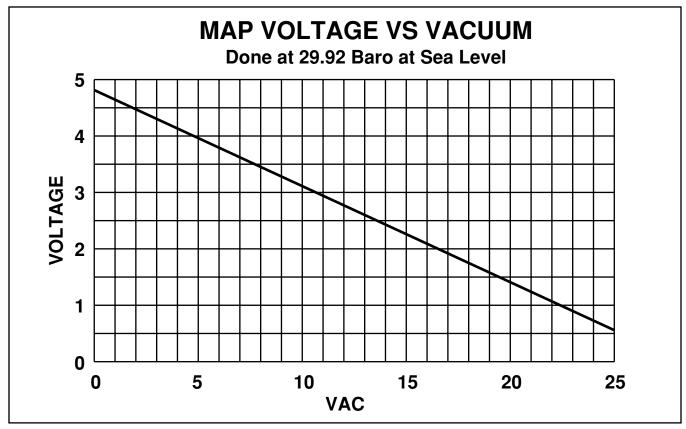


Figure 34 MAP Voltage vs. Vacuum

During key ON (engine not running) the sensor reads (updates) barometric (Baro) pressure. A normal range can be obtained by monitoring a known, good sensor.

As the altitude increases, the air becomes thinner (less oxygen). If a vehicle is started and driven to a very different altitude than where it was at key ON, the barometric pressure must be updated. Anytime the PCM sees at least 1.8 volts above minimum TPS, and based upon rpm, it will update barometric pressure in the MAP memory cell. With periodic updates, the PCM can make its calculations more effectively. Also, if MAP is ever greater than Baro, such as coming down from a high altitude, Baro automatically updates.

The PCM uses the MAP sensor to aid in calculating the following:

- Barometric pressure.
- Engine load.
- Manifold pressure.
- Injector pulse width.
- Spark-advance programs.
- IAC position.
- Deceleration fuel shutoff.

The MAP sensor signal is provided from a single silicone piezoresistive element located in the center of a diaphragm. The element and diaphragm are both made of silicone. As the pressure changes, the diaphragm moves, causing the element to deflect, which stresses the silicone. When silicone is exposed to stress, its resistance changes. As manifold vacuum increases, the MAP sensor input voltage decreases proportionally (fig. 34). The sensor also contains electronics that condition the signal and provide temperature compensation.

The PCM recognizes a decrease in manifold pressure by monitoring a decrease in voltage from the reading stored in the barometric pressure memory cell. The MAP sensor is a linear sensor. As pressure changes, voltage changes proportionately. The range of voltage output from the sensor is usually between 4.6 volts at sea level to as low as 0.3 volt at 26 in. of Hg (Table 2). Barometric pressure is the pressure exerted by the atmosphere upon an object. At sea level, on a standard day, no storm, barometric pressure is 29.92 in. of Hg. For every 100 feet of altitude, barometric pressure drops 0.10 in. of Hg. A storm can either add (high pressure) or decrease (low pressure) from what should be present for that altitude. You should know the average pressure and corresponding barometric pressure for your area. Always use the Diagnostic Test Procedures Manual for MAP sensor testing.

Inches of Mercury Absolute	Inches of Mercury Vacuum	MAP Sensor Signal Voltage (Volts)
31.0	0.5 psi	4.8
29.92	0.00	4.6
27.00	2.92	4.1
25.00	4.92	3.8
23.00	6.92	3.45
20.00	9.92	2.92
15.00	14.92	2.09
10.00	19.92	1.24
5.00	24.92	0.45

Table 2 MAP Sensor Values

### **MAP Sensor Diagnostics**

There are three MAP sensor diagnostic routines:

- MAP voltage high.
- MAP voltage low.
- No change in MAP voltage at start-to-run transfer.

With the engine running between 400 to 1,500 rpm, near closed throttle and if MAP voltage is above 4.9 volts, the voltage high fault is set. Beginning with the 1997 model year, the MAP diagnostic range is 416 to 3,500 rpm.

There are two different ways to set the voltage low fault. If MAP voltage is below 2.35 volts at startup, the fault will be set. The other is MAP voltage below 0.1 volt while the engine is running.

To set the rationality fault, no change in MAP from start to run, the PCM must see too small a difference between MAP voltage with engine running and Baro at key on. This is checked at all times. If rpm becomes close to idle speed and the throttle is closed, vacuum should be greater than a calibrated amount. If vacuum is not high, then a fault will be set.

MAP voltage is only looked at when the vehicle is near closed throttle and rpm between approximately 400 to 1,500 rpm. This means that if a MAP sensor is faulty at an rpm above 1,500, the PCM will believe whatever reading it gets from the MAP sensor as real. Beginning with the 1997 model year, the MAP diagnostic range is 416 to 3,500 rpm.

### **MAP Sensor Limp-in**

The PCM stores a DTC when the MAP sensor malfunctions. When the PCM sets a DTC, the MAP sensor's information is considered inaccurate. At this point, the PCM moves into "limp-in" mode. Limp-in for the MAP sensor allows the engine to continue to function, without input to the PCM from the MAP. The PCM must calculate the amount of air being consumed by the engine, which is accomplished by calculating MAP values, based upon readings from the CKP sensor (RPM) and the Throttle Position Sensor (TPS). Anytime the PCM sets a DTC for MAP, the Malfunction Indicator Light (MIL) is illuminated.

### **Component Locations**

The MAP sensor on V6/V8 engines is located on the throttle body.

### ACTIVITY 4 — MANIFOLD ABSOLUTE PRESSURE (MAP) SENSOR

### **3.9L**

### **Activities**

- 1. Find the sensor on the vehicle and unplug the connector. How many wires does it have? \_\_\_\_\_ What does the DRB III indicate for Baro, vacuum and voltage?
- 2. Using a voltmeter, measure the voltage on the three wires. What are the voltages? \_\_\_\_\_
- 4. Change the DRB III to read DTCs. What DTC is present and why? \_\_\_\_\_
- 5. Plug the connector together.
- 6. Change the DRB III to read sensors. Now what does the DRB III indicate for Baro, vacuum and voltage?
- 7. If the MAP sensor wire was shorted to ground, what DTC would be present?
- 9. Go to DTCs. What DTC is present and why? \_\_\_\_\_

### 5.2L/5.9L

### Activities

- 1. Find the sensor on the vehicle and unplug the connector. How many wires does it have? \_\_\_\_\_ What does the DRB III indicate for Baro, vacuum and voltage?
- 2. Using a voltmeter, measure the voltage on the three wires. What are the voltages? \_\_\_\_\_
- 4. Change the DRB III to read DTCs. What DTC is present and why?
- 5. Plug the connector together.
- 6. Change the DRB III to read sensors. Now what does the DRB III indicate for Baro, vacuum and voltage?
- 7. If the MAP sensor wire was shorted to ground, what DTC would be present?
- 9. Go to DTCs. What DTC is present and why?

### **THROTTLE POSITION SENSOR (TPS)**

The throttle position sensor is mounted to the side of the throttle body. The PCM needs to identify the position of the throttle blade at all times to assist in performing the following calculations:

- Ignition timing advance.
- Fuel injection pulse-width.
- Idle (learned value or minimum TPS).
- Off-Idle (0.04 volt above minimum TPS).
- Wide-Open Throttle (WOT) open loop (2.7 volts above learned idle voltage).
- Deceleration fuel lean-out.
- Fuel cutoff during cranking at WOT (2.4 volts above learned idle voltage).

The PCM supplies the TPS with a regulated voltage that ranges from 4.8 to 5.1 volts (fig. 35). This output regulated voltage is the same regulated voltage that the MAP, cam and crank sensors use. The TPS receives its ground from the PCM. The input of the TPS to the PCM is through a 5-volt sensor circuit.

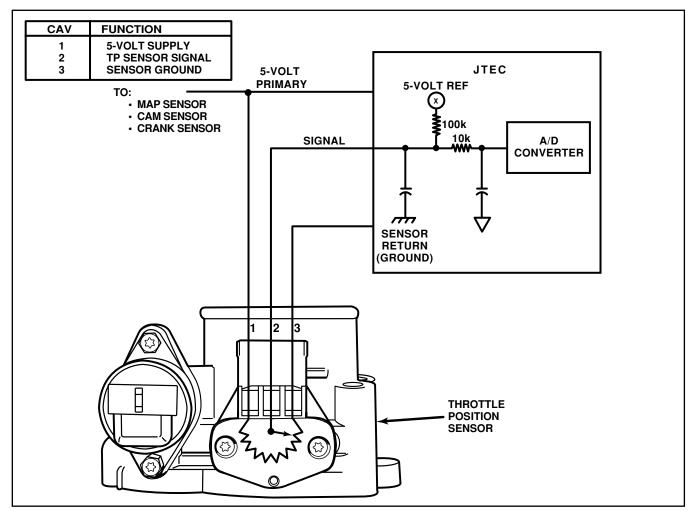


Figure 35 Throttle Position Sensor Circuit

### **TPS PROGRAMS**

### Idle

As with other Chrysler fuel-injection systems, the PCM is able to recognize an idle command based upon inputs from the TPS. Also, like other Chrysler systems, the PCM is programmed to monitor the TPS signal whenever the key is ON. While the key is on and the engine is running, the PCM assumes that the lowest voltage it can receive, above the fault threshold, must be where the throttle blade lever hits the idle stop. Normally, this voltage range is approximately 0.5-1.0 volt. At the low-voltage position, the PCM records the signal as "idle," better known as "minimum TPS."

The PCM's memory is updated anytime the sensed voltage is less than the recorded value in the memory cell. The PCM uses voltage change to determine when the throttle has returned to the previously learned value. At key ON, the PCM will raise the target voltage value in the TPS Minimum idle memory cell by approximately 0.04 volt. This new value becomes the new minimum TPS. When the engine is started, if the actual TPS voltage is lower than the new memory value, the PCM will store actual as minimum TPS.

If the key is cycled ON without starting the engine (start-to-run transfer), the value in target memory will increase up to a maximum of approximately 1.8 volts. This is a calibrated value and may change. Once the maximum is reached, the voltage will automatically drop by approximately 1.0 volt. At the next key-on, the minimum TPS will increase in 0.04-volt increments and stays in this loop until the PCM can learn a new actual minimum TPS with the engine running.

Anytime the PCM receives the idle voltage signal, the PCM is programmed to maintain idle, using timing and the Idle Air Control (IAC) motor. Idle speed may vary, based on ECT.

Spark advance curves and injection pulse-width programs are unique as they are specifically calibrated for idle conditions. If equipped with an automatic transmission, the PCM also has separate programs for idle neutral and idle drive.

### **Off-Idle**

Once the throttle is opened, the PCM moves into its off-idle program at approximately 0.04 volt above minimum TPS. At this point, spark scatter advance is no longer being used to control idle speed. The IAC motor has been repositioned to act like a dashpot. The dashpot function operates the IAC motor to prevent the possibility of the engine dying out during a sudden deceleration. So, if the throttle blade is actually closed but the TPS voltage did not drop to minimum TPS (dirty throttle body) idle, quality will be poor: minimum TPS with engine running cannot be learned upward (higher voltage than minimum TPS to 0.04 volt). Only a lower voltage can be learned.

#### Acceleration

A rapid rise in TPS voltage within a specified time frame causes the injector pulse width to increase. The amount of pulse width increase is determined by the rate of voltage rise. For maximum response, the PCM will momentarily increase the pulse width for all the injectors.

#### Wide Open Throttle (WOT)

With the engine running, the PCM spark-advance and fuel pulse-width programs are affected during WOT conditions. The PCM is programmed to go into open loop anytime the TPS voltage exceeds 2.7 volts (80% throttle blade) above minimum idle. This enables the PCM to enrich the air/fuel ratio at WOT to allow the combustion chamber to run a little cooler.

#### **Deceleration**

Under deceleration, the PCM is programmed to "lean out" the air/fuel ratio, since engine power is not needed. One of the main components involved with the deceleration program is the TPS. If, while the vehicle is in motion (based on the Vehicle Speed Sensor), the TPS is closed, and manifold vacuum is high, the PCM narrows the pulse width, so that the air/fuel ratio becomes leaner. In some instances, the pulse width goes to 0.0 msec., at which time no fuel is supplied to the engine. This action causes extremely low vehicle emissions. During deceleration, the adaptive numerator is updated, as there is no load on the crankshaft. The adaptive numerator is explained in detail in the On Board Diagnostics II Student Reference Book.

#### Wide Open Throttle Fuel Cutoff During Cranking

One last function that the PCM performs from inputs delivered by the TPS is the WOT fuel cutoff, while cranking. To ensure short cranking times, the PCM fires all of the injectors simultaneously, once during cranking. After that, the PCM waits two revolutions, then fires the injectors sequentially. If the programmed pulse width allows too much fuel into the combustion chamber, or if circumstances do not allow the engine to start up with the programmed quantity of fuel, the driver can operate the accelerator pedal to WOT, so that the PCM de-energizes all injectors. This program occurs only during cranking and when the TPS voltage exceeds 2.4 volts above minimum TPS.

#### **TPS Diagnostics**

There are three TPS diagnostic routines:

- TPS voltage high.
- TPS voltage low.
- TPS voltage does not agree with MAP.

The diagnostic routine TPS voltage does not agree with MAP, fault is set when the PCM interprets the MAP indication as a load condition that does not agree with what it sees from the TPS. Basically, if the voltage gets too low (0.1 volt or if road speed is above 20 mph, with rpm greater than 1,500, and vacuum less than 2''), the PCM sets the short-to-ground (voltage low) fault. If the voltage gets too high (4.9 volts), it sets the short-to-voltage (voltage high or open circuit) fault.

#### **TPS Limp-in**

When the TPS indicates a voltage that is too low, too high or not believable, the PCM sets a DTC. When the DTC is set, the MIL is illuminated and the PCM moves into limp-in mode. Limp-in for the TPS is divided into three categories: idle, part-throttle and WOT. These limp-in values are mainly rpm-based, although the MAP sensor has an input to the program. Refer to the Diagnostic Test Procedures Manual for complete diagnostic information.

### **ACTIVITY 5 — THROTTLE POSITION SENSOR**

- 1. Turn key ON and OFF several times. What happened to MIN TPS? Will clear-flood occur?
- 2. Start engine. Move throttle. What happened to MIN TPS? \_\_\_\_\_
- 3. With key ON, engine OFF and DRB III at sensors, move throttle. What happened to TPS and Injector Pulse Width?\_\_\_\_\_
- 4. Connect fuel simulator (preset potentiometer). Raise TPS value at simulator. What happened?
- 5. Create a custom display on the DRB III:
  - TPS voltage
  - TPS Calculated
  - MIN TPS
  - TPS %
  - Eng. RPM
  - MAP
  - Upstream O2 voltage
  - Injector Pulse Width
  - IAC steps
  - Spark advance
- 6. Increase TPS value until open loop (upstream O2). Return to minimum TPS and then snap (rotate quickly) TPS, watch pulse width. What did you see?
- 7. Rotate potentiometer downward, then raise it up. What did you notice TPS learning?
- 8. Rotate way down and move accelerator linkage. In what mode is the PCM?

### **ENGINE COOLANT TEMPERATURE (ECT) SENSOR**

The PCM uses inputs from the ECT sensor to calculate:

- Injector pulse width.
- Spark-advance curves.
- Idle Air Control (IAC) motor key-on steps.
- Initial fuel injection.
- O2 Sensor closed-loop times (30° and above).
- Purge solenoid on/off times.
- Target idle speed.

The ECT input is the second most powerful modifier of injector pulse width. The ECT sensor is a two-wire Negative Thermal Coefficient (NTC) sensor. The PCM sends five volts to the sensor, and is grounded through the sensor return line (fig. 36). As temperature increases, resistance in the sensor decreases.

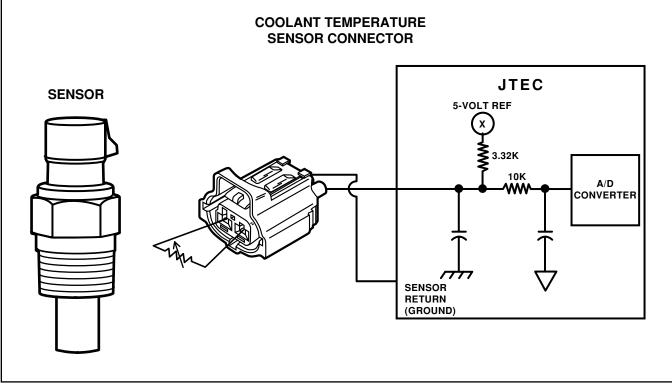
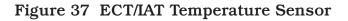


Figure 36 Engine Coolant Temperature Sensor Circuit

As the temperature goes up, the voltage drop increases, which causes a lower voltage at the A/D converter. **Unlike prior years (SBEC), this is not a dual-ranging circuit (fig. 37).** 

TEMPERATURE		RESISTANCE (OHMS)	
с	F	MIN	MAX
-40	-40	291,490	381,710
-20	-4	85,850	108,390
-10	14	49,250	61,430 35,990
0 10	32 50	29,330 17,990	21,810
20	68	11,370	13,610
25	77	9,120	10,880
30	86	7,370	8,750
40	104	4,900	5,750
50	122	3,330	3,880
60	140	2,310	2,670
70	158	1,630	1,870
80	176	1,170	1,340
90	194	860	970
100	212	640	720
110	230	480	540
120	248	370	410



The resistance of the ECT sensor changes based on temperature (fig. 38):

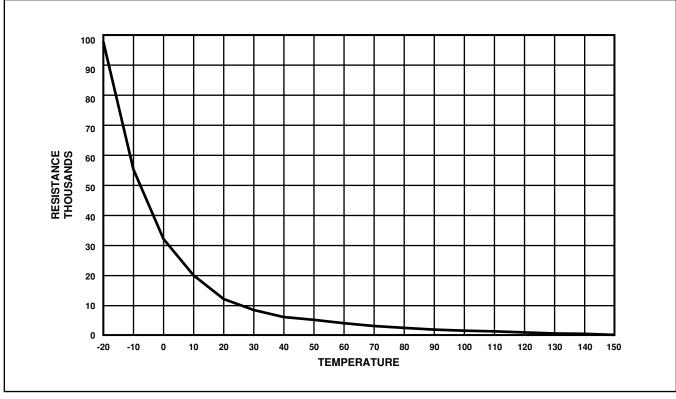
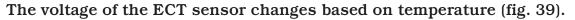


Figure 38 ECT/IAT Temperature/Resistance Curve



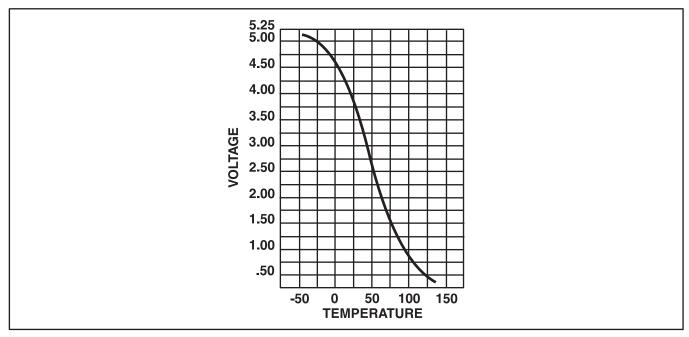


Figure 39 ECT/IAT Temperature/Voltage Curve

### **ECT Sensor Diagnostics**

There are four ECT diagnostic routines:

- ECT Too High is set when voltage is above 4.9 volts for 3 seconds.
- ECT Too Low is set when voltage is below 0.08 volt for 3 seconds.
- ECT Too-Cold, Too-Long Fault is set when the ECT is between 19° and 212°F at start-up and the engine runs for 14 minutes under any condition, then runs another 14 minutes above 28 mph and ECT does not reach 160°F.
- The closed loop temperature not reached, fault is set when the engine fails to reach a calibrated (approximately 50°F) temperature within approximately five minutes.

The two rationality faults (ECT too-cold too-long and closed-loop temperature not reached) will turn the "Check Engine" light on if the fault is present for two trips. For more information, refer to the OBD II course.

### **ECT Sensor Limp-in**

When the ECT sensor indicates voltage that is too high or too low, the PCM sets a DTC. When a DTC is set, the MIL is illuminated and the PCM moves into limp-in mode. Limp-in mode for the ECT sensor is a preset value.

### **CCD Bus**

On 1996 ZJ and 1997 AN vehicles, the engine-coolant temperature information is bused from the PCM to the instrument cluster.

### **ACTIVITY 6 — ENGINE COOLANT TEMPERATURE SENSOR**

**3.9L** 

#### **Activities**

- 1. Using a voltmeter, measure the voltage on the two wires. What is the voltage?
- 2. Plug the connector together and change the DRB III to read DTCs. What DTC is present and why?

If the ECT sensor wire was shorted to ground, what DTC would be present?

Hook up ECT on simulator. Rotate potentiometer and watch values on custom display. Note rpm increase at high temperature. Repeat procedure with engine on. Then, short the circuit to ground.

- 3. Connect BOB and DRB III. Build a custom display:
  - Coolant Temp Degrees
     Upstream O2 Voltage
  - Coolant Temp Voltage
    Engine RPM
    Closed Loop Timer
    IAC Steps

  - Target Idle
  - Injector Pulse Width

- Spark Advance

Find the sensor on the vehicle and unplug the connector. What does the DRB III indicate for temperature and voltage?

- 4. Using the simulator and DRB III, change the ECT output to read 0° F. What happened to IAC, target idle and injector pulse width? Why? \_\_\_\_\_
- 5. Slowly increase the temperature toward hot. As the temperature increased, what happened to the voltage? Why?
- 6. Using the simulator and DRB III, change the ECT output to read 240° F. What happened to IAC, target idle and injector pulse width? Why?

### 5.2L/5.9L

### **Activities**

- 1. Using a voltmeter, measure the voltage on the two wires. What is the voltage?
- 2. Plug the connector together and change the DRB III to read DTCs. What DTC is present and why? \_\_\_\_\_

If the ECT sensor wire was shorted to ground, what DTC would be present?

Hook up ECT on simulator. Rotate potentiometer and watch values on custom display. Note rpm increase at high temperature. Repeat procedure with engine on. Then, short the circuit to ground.

- 3. Connect BOB and DRB III. Build a custom display:
  - Coolant Temp Degrees
     Upstream O2 Voltage
  - Coolant Temp Voltage
     Closed Loop Timer
    - IAC Steps

• Target Idle

• Engine RPM

• Injector Pulse Width

Find the sensor on the vehicle and unplug the connector. What does the DRB III indicate for temperature and voltage?

- 4. Using the simulator and DRB III, change the ECT output to read 0° F. What happened to IAC, target idle and injector pulse width? Why? \_\_\_\_\_
- 5. Slowly increase the temperature toward hot with engine running. As the temperature increases, what happens to the voltage?\_\_\_\_\_ Why? \_\_\_\_\_
- 6. Using the simulator and DRB III, change the ECT output to read 240° F. What happened to IAC, target idle and injector pulse width? Why?

- Spark Advance

### Intake Air Temperature (IAT) Sensor

The IAT sensor sends information to the PCM on the density of the air entering the intake manifold, based upon temperature (fig. 41). The PCM uses this input to calculate:

- Injector pulse width.
- Adjustment of spark timing (to prevent knock with high-intake air temperatures).

The IAT sensor exerts more control at cold temperatures and during wide-open throttle (high rpm, low manifold vacuum). At a temperature of  $-20^{\circ}$  F and wide-open throttle, the PCM can increase fuel injector pulse width by as much as 37%, based upon input from the IAT sensor.

The PCM sends 5 volts to the sensor and is grounded through the sensor return line (fig. 40). As temperature increases, resistance in the sensor decreases. The resistance of the IAT sensor is the same as for the ECT sensor. The differences between the IAT sensor and the ECT sensor are as follows:

- Connectors are indexed differently.
- IAT sensor thread diameter is smaller.
- IAT sensor material is exposed through a plastic cage (to quicken response time).

The IAT sensor and its circuit function exactly the same as the ECT sensor and its circuit.

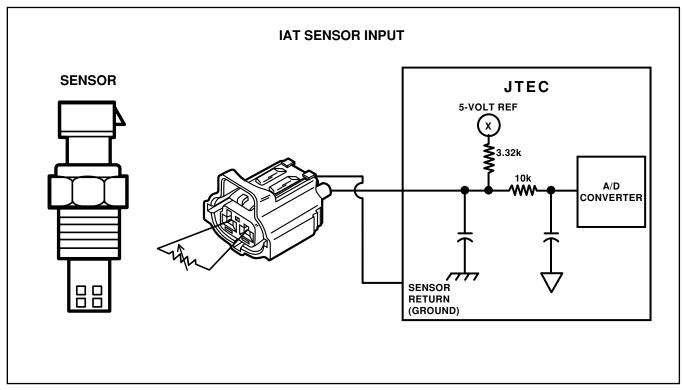


Figure 40 Intake Air Temperature Sensor Circuit

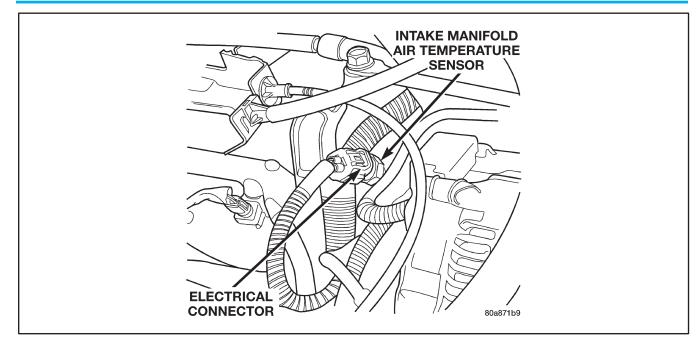


Figure 41 IAT Sensor

#### **IAT Sensor Diagnostics**

- Voltage Too Low is set when voltage is below 0.1 volt
- Voltage Too High is set when voltage is above 4.9 volts

### **IAT Sensor Limp-in**

When the IAT sensor indicates voltage that is too high or too low, the PCM sets a DTC. When the DTC is set, the MIL is illuminated and the PCM moves into limp-in mode. The IAT sensor uses the BTS information, as long as the information is believed to be accurate. If the BTS is already in limp-in, the PCM uses a temperature that has very little effect on fuel and spark programming.

### **ACTIVITY 7 — INTAKE AIR TEMPERATURE SENSOR**

### **Activities**

- 1. Find the sensor on the vehicle and unplug the connector. What does the DRB III indicate for temperature and voltage?
- 2. Using a voltmeter, measure the voltage on the two wires. What is the voltage?
- 3. Plug the connector together and change the DRB III to read DTCs. What DTC is present and why? \_\_\_\_\_ If the IAT sensor wire was shorted to ground, what DTC would be present?

Hook up IAT sensor on simulator. Rotate potentiometer and watch values on custom display. Note rpm increase at high temperature. Repeat procedure with engine on. Then, short the circuit to ground.

- 4. Connect BOB and DRB III. Build a custom display:
  - Coolant Temp Degrees
     Upstream O2 Voltage
  - IAT Voltage
  - Engine RPMTarget Idle
- IAC Steps

Closed Loop Timer

- Injector Pulse Width
- Spark Advance
- 5. Using the simulator and DRB III, change the IAT output to read 0° F. What happened to IAC, target idle and injector pulse width? Why?
- 6. Slowly increase the temperature toward hot. As the temperature increased, what happened to the voltage? Why?
- 7. Using the simulator and DRB III, change the IAT output to read 240° F. What happened to IAC, target idle and injector pulse width? Why?

#### **SENSED BATTERY VOLTAGE**

The direct battery circuit to the PCM is also used as a reference point to sense battery voltage.

#### **Fuel Injectors**

Fuel injectors are rated for operation at a specific voltage. If the voltage increases, the plunger will open faster and farther (more efficiently). If voltage decreases, the injector will open slowly and not as far. If sensed battery voltage drops, the PCM will increase pulse width to maintain the same volume of fuel through the injector.

#### Charging

The PCM uses sensed battery voltage to verify that target charging voltage (determined by Battery Temperature Sensor) is being reached. To maintain the target charging voltage, the PCM will full-field the generator to 0.5 volt above target, then turn off to 0.5 volt below target. The PCM performs charging voltage maintenance at approximately 100 times per second (100 Hz frequency).

### **OXYGEN (02) SENSORS**

### **General Information**

Starting in 1996, all vehicles use two O2 Sensors\*. An O2 Sensor provides the PCM with a voltage signal (0–1 volt) inversely proportional to the amount of oxygen in the exhaust. In other words, if oxygen content is low, voltage output is high. If oxygen content is high, voltage output is low. This information allows the PCM to adjust injector pulse width to achieve the air/fuel ratio necessary for proper engine operation and to control emissions.

An O2 Sensor must have a source of oxygen from outside of the exhaust stream for comparison. Current O2 Sensors receive their fresh oxygen supply through the wire harness. This is why it is important to never solder an O2 Sensor connector, or pack the connector with grease (fig. 42).

The downstream sensor, located just after the catalytic converter, produces a similar signal input that the PCM uses for two purposes. One function is to verify catalytic converter efficiency, as part of required OBD II diagnostics. The other function is to provide fuel correction information, based on actual catalytic converter output.

Both O2 Sensors are zirconium dioxide, four-wire, and heated. The heaters on both sensors are fed battery voltage from the ASD relay, which is also controlled by the PCM (refer to ASD relay for more information). Both sensor heaters use a common ground. One of the other two wires is the input to the PCM and the last wire is the sensor ground. Both circuits are isolated from each other and the sensor housing.

The O2 Sensor uses a Positive Thermal Coefficient (PTC) heater element. As temperature increases, resistance increases. At ambient temperatures around 70° F, the resistance of the heating element is approximately 6 ohms. As sensor temperature increases, resistance in the heater element increases. Even though these are heating elements, current flow is low.

At 70°F, current flow is approximately 600 milliamps. As it approaches operating temperature, it drops to approximately 200 milliamps. This allows the heater to maintain the optimum operating temperature of approximately 1400°– 1500°F. Although both sensors operate the same, physical differences, due to the environment in which they operate, keep them from being interchangeable.

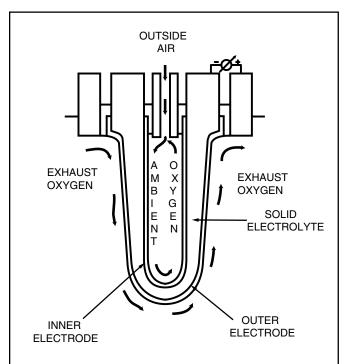


Figure 42 Oxygen Sensor Internal Operation

\* The 5.9L Heavy-duty engine uses two upstream O2 Sensors. These two sensors are used as a stereo (each side individually) control.

### **Stoichiometric Ratio**

Catalyst efficiency can be maximized to a point that would minimize hydrocarbon, carbon monoxide and nitrous oxide emissions, by controlling the air/fuel ratio. This air/fuel ratio is 14.7 to 1 (ideal for both fuel efficiency and emission control). In other words, 14.7 units of air are mixed with every unit of fuel, to produce the minimum amount of emissions. This ratio is called the stoichiometric (stoy-key-ohmet-rick) ratio (fig. 43).

However, conditions inside an engine's combustion chamber are not ideal. There just is not enough time in the engine's operating cycle to allow complete combustion to take place. So, even with a stoichiometric ratio, the engine exhaust gases contain a certain percentage of pollutants in the form of HC and CO. The severe conditions (principally high temperatures) inside the combustion chamber cause some of the free oxygen and nitrogen in the air/fuel mixture to combine, forming various oxides of nitrogen ( $NO_x$ ). All things considered, the stoichiometric ratio is the optimum air/fuel ratio, for minimizing undesirable emissions.

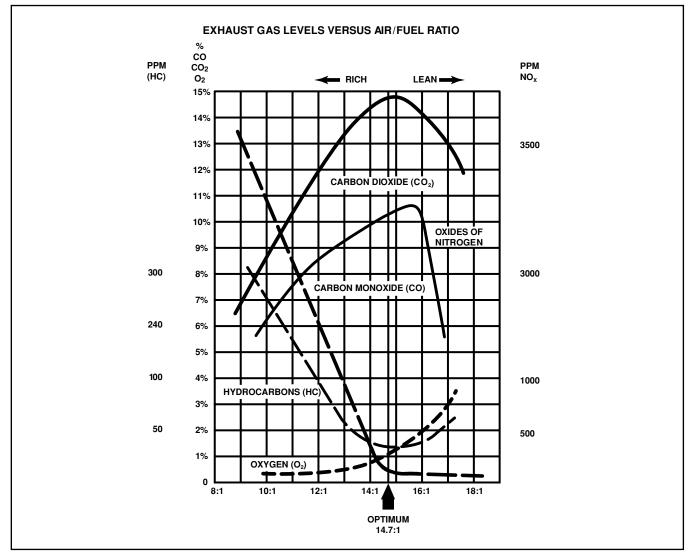
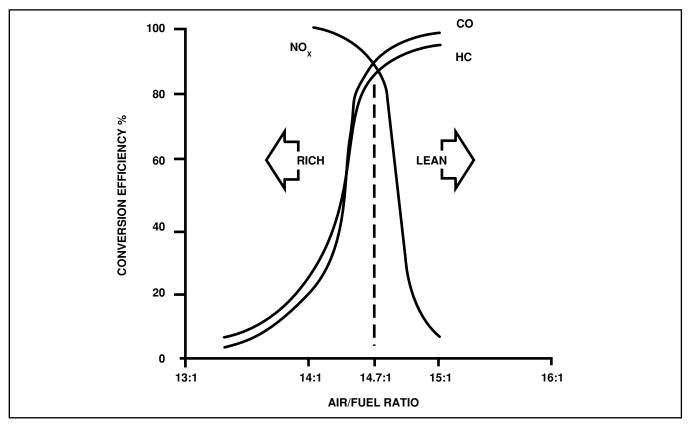
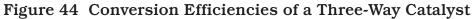


Figure 43 Exhaust Emissions vs. Air/Fuel Ratio

### Catalyst

The latest technology provides the use of a three-way catalytic converter on most automobiles. The three-way catalyst simultaneously converts three harmful exhaust emissions into harmless gases. Specifically, HC and CO emissions are converted into water ( $H_2O$ ) and carbon dioxide ( $CO_2$ ). Oxides of nitrogen ( $NO_x$ ) are converted into elemental nitrogen (N) and oxygen. The three-way catalyst is most efficient in converting HC, CO and  $NO_x$  at the stoichiometric air/fuel ratio of 14.7:1 (fig. 44). If the mixture becomes leaner than 14.7:1 (extra oxygen), the ability to convert  $NO_x$  drops. As the mixture becomes richer than 14.7:1 (less oxygen), the ability to convert HC and CO drops.



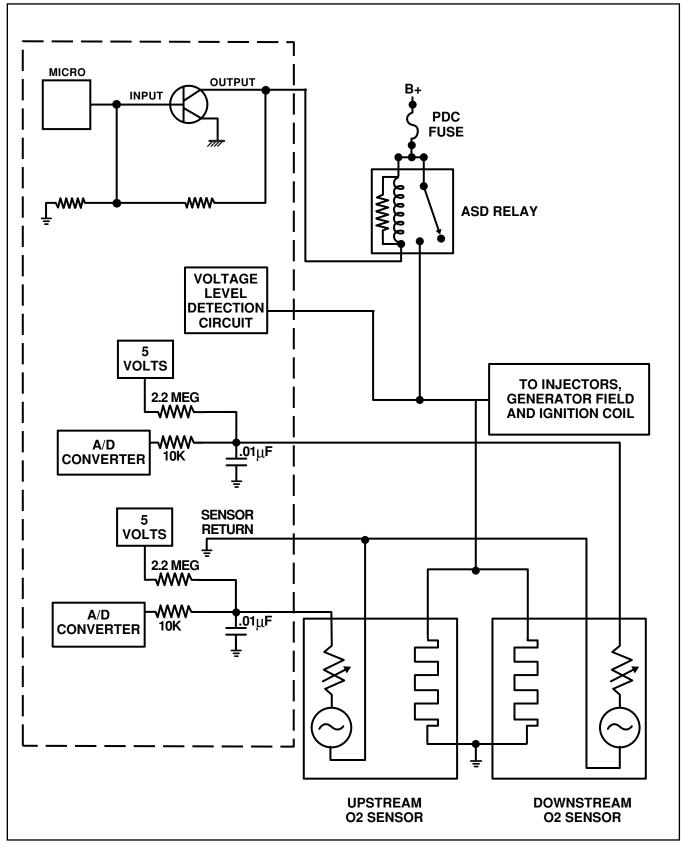


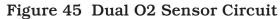
### **O2S Electrical Operation**

When the O2S is cold, resistance is extremely high (infinite). As the sensor heats up, two things happen. First, the resistance of the sensors drops. Second, once it heats to a certain temperature, above  $660^{\circ}$  F, the sensor becomes a galvanic battery, actually creating a voltage output.

The PCM must be able to power up the heaters, read an input voltage and diagnose the circuit, and the operation of the sensors. To be able to do all this, the PCM uses a 5-volt diagnostic circuit (fig. 45). On a cold start, the PCM sends out 5 volts to the O2 Sensor. As the sensor heats up, resistance decreases through it. As the resistance decreases, the 5 volts should drop. After a short time delay, the PCM measures how long it takes to move from 4 volts to 3 volts. If the voltage goes too low, a short to ground will be indicated.

To detect a short to  $B_+$ , the PCM waits until the O2 Sensor should be putting out a voltage between .5 and 1.0 volt. If the PCM reads a voltage of 1.5 volts or higher from the sensor, a shorted high fault will be set.





#### **O2 Sensor Diagnostics**

- O2 Sensor shorted to ground (low). At a cold start, ECT below 147°F, if O2S voltage is below 0.156 volt, the fault is set in one trip.
- O2 Sensor shorted to voltage (high) is set with the engine running, ECT has been above 176° for 4 minutes and the O2 Sensor voltage is above 1.5 volts. The upstream sensor fault will set in one trip. However, the downstream sensor takes two trips to set the fault.
- There are also tests required for OBD II. Refer to OBD II section for test descriptions.

#### **Upstream O2 Sensor**

The upstream sensor is located on the exhaust manifold and is used to maintain an Air/Fuel (A/F) ratio of approximately 14.7:1 (stoichiometric). This is accomplished by the fact that an O2 Sensor acts like a switch when the A/F ratio is near 14.7:1 (fig. 46). When the A/F is lean (extra oxygen), the sensor output will be very close to 0 volt. As the A/F becomes richer (less oxygen), the sensor output will change rapidly to 0.5 volt and can continue movement up to 1 volt if the mixture becomes too rich. Based on these operating characteristics, the PCM can be programmed with switch points, to maintain the proper A/F ratio. The O2 Sensor must reach a minimum of 660°F in order to effectively monitor oxygen content in the exhaust system. To provide optimum functioning of the O2 Sensor, the PCM waits until the system goes into closed loop before it controls the air/fuel ratio; it does not attempt to control the ratio immediately after start-up.

Closed-loop parameters are:

- Engine temperature exceeds 35°F.
- O2 Sensor is in the ready mode.
- All timers have timed out, following the START to RUN transfer (the timer lengths vary, based upon engine temperature at key-on) as follows:
  - 35°F/41 sec.
  - 50°F/36 sec.
  - $70^{\circ}$ F/19 sec.
  - $167^{\circ}$ F/11 sec.

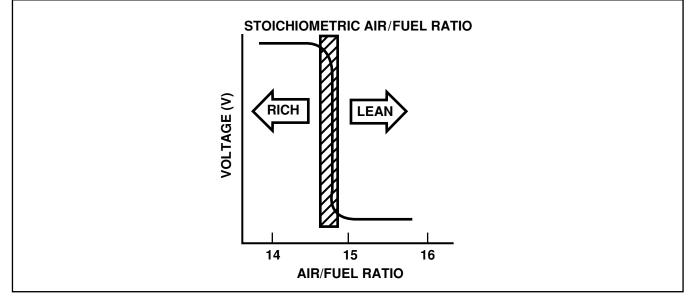


Figure 46 Oxygen Sensor Output

**NOTE:** These times and temperatures may vary for each engine package.

The feedback systems begin to operate during closed loop.

#### ACTIVITY 8 — UPSTREAM O2

Have the instructor assign you to a vehicle equipped with either a V6 or V8 engine. Use the Service Manual and DRB III to assist in answering the following questions.

- 2. Connect a jumper wire from the PCM side of the switch to your hand. With your other hand, touch the positive battery terminal. What voltage does the DRB III indicate?
- 3. Using the DRB III, perform the O2 heater test. How long did it take for the voltage to begin dropping? \_\_\_\_\_\_
- 4. How long did it take for the voltage to reach single digits?

#### **Downstream O2 Sensor**

As mentioned previously, the downstream O2S has two functions. One is to measure catalyst efficiency. This is an OBD II requirement. Briefly, the oxygen content of the exhaust gases, leaving the converter, has significantly less fluctuation than at the inlet, if the converter is working properly. The PCM compares the upstream and downstream O2S switch rates under specific operating conditions to determine if the catalyst is functioning properly. Refer to the OBD II Training Course for more information.

The other function is new for 1996 model-year vehicles equipped with JTEC PCMs. While the upstream O2S input is used to maintain the 14.7:1 Air/Fuel (A/F), variations in engines, exhaust systems and catalytic converters may cause this ratio to be less than ideal for a particular catalyst and engine. To help maintain the catalyst operating at maximum efficiency, the PCM will fine tune the A/F ratio entering the catalyst, based upon the oxygen content leaving the catalyst. This is accomplished by modifying the upstream O2S voltage goal. In the past, this goal was a preprogrammed fixed value, based on where the catalyst was believed to operate most efficiently. With the new downstream O2S fuel control, the upstream O2 goal is moved up and down, within the window of operation of the O2 Sensor. If the oxygen content leaving the catalyst is too lean (excess oxygen), the PCM will move the upstream O2 goal up, which will increase fuel in the mixture, causing less oxygen to be left over. Conversely, if the oxygen content leaving the catalyst is too rich (not enough oxygen), the PCM will move the upstream O2 goal down, which will remove fuel from the mixture, causing more oxygen to be left over.

This function only occurs during cruise mode operation. Currently, this function is not being used on 5.9L heavy-duty engines with automatic transmissions. The 5.9L heavy-duty vehicles do not have downstream O2 Sensors.

#### **OBD II**

There are several OBD II tests performed by and on the O2 Sensors. A brief description of each follows.

#### **Catalyst Monitor**

The downstream O2 Sensor measures the content of the O2 passing through the catalytic converter. Normally, the downstream O2 Sensor switch rate is extremely slow, compared to that of the upstream sensor rate. As the converter deteriorates, the O2 Sensor switch rate increases. The PCM can compare the signals produced by the upstream and the downstream O2 Sensors to determine the operating efficiency of the catalyst.

#### **O2** Monitor

Even though an O2 Sensor may be switching and not exceeding the thresholds, it must switch with a certain frequency to allow the PCM enough time to make correction before emissions are exceeded. When certain conditions are met (at idle), the PCM checks the switch rate of the O2 Sensor. It looks for how fast it switches, as well as how many times it switches, within a calibrated time. As part of OBD II, the PCM monitors the switching frequency, under specific conditions and will set a fault if the sensor becomes slow or lazy. Refer to the OBD II course for more information.

#### **O2 Heater Monitor**

The O2 heater allows the O2S to reach operating temperature sooner after start-up. It is also necessary because prolonged idle conditions cannot maintain O2 Sensor temperature. If these fail to function, vehicle emissions can increase under certain conditions. On Board Diagnostics II requires monitoring these heaters for proper operation.

If certain conditions have been met at key-on, a test is performed. The heater element itself is not tested. The resistance in oxygen sensor output circuits is tested to determine (infer) heater operation. The resistance is normally between 100 ohms and 4.5 megohms. When oxygen sensor temperature increases, the resistance in the internal circuit decreases. The PCM sends a five-volt signal through the oxygen sensors to monitor this circuit. As temperature increases, resistance decreases and the PCM detects a lower voltage at the reference signal.

The test is performed if the engine coolant temperature is less than 147°F and the ECT sensor and BTS are within 27°F of one another. The PCM measures how long it takes for the voltage to change from above 4 volts to less than 3 volts.

#### **ADAPTIVE MEMORIES**

#### **Short-Term Adaptive Memory**

As mentioned earlier, when the fuel system goes into closed-loop operation, two adaptive memory systems begin to operate. The first system that becomes functional is called short-term memory or short-term correction (fig. 47). This system corrects fuel delivery in direct proportion to the readings from the upstream O2 Sensor. In other words, as the Air/Fuel (A/F) mixture changes, the O2 Sensor voltage tells the PCM that the A/F ratio contains either more or less oxygen. The PCM then begins either to add or remove fuel until the O2 Sensor reaches its switch point. When the switch point is reached, short-term correction begins with a quick change (kicks). Then it ramps slowly, until the O2 Sensor's output voltage indicates the switch point in the opposite direction. Short-term adaptive memory will keep increasing or decreasing injector pulse width, based upon the O2 Sensor input. The maximum range of authority for short-term memory is  $\pm$  33% of base pulse width.

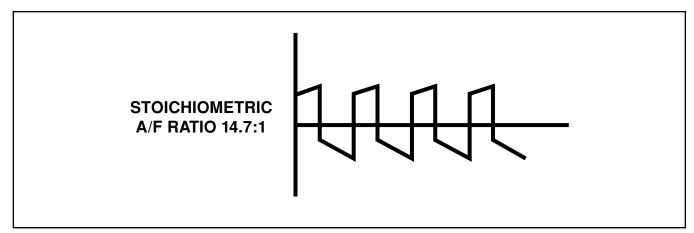


Figure 47 Short-Term Fuel Compensation

For example, if there is a low fuel-pressure problem, the O2 Sensor will start moving toward zero volt, lean mixture (excess oxygen). Short-term fuel correction will begin to add fuel and continue to add (up to 33% of total pulse width), until the O2 Sensor begins switching again.

The PCM's goal is to keep the O2 Sensor switching around the goal voltage.

#### **Long-Term Adaptive Memory**

The second system is called Long-Term Adaptive Memory (fig. 48). In order to maintain correct emission throughout all operating ranges of the engine, it was decided that a cell structure, based on Load and engine rpm, should be used (Table 3). There are up to 22 cells. Two are used only during idle, based upon TPS and Park/Neutral switch inputs. There may be another two cells used for deceleration, based on TPS, engine rpm and vehicle speed. The other 17 cells represent a manifold pressure and an rpm range. Each of these cells are a specific MAP voltage range. The values shown in Table 3 are an example only. These values are calibrated for each powertrain package. As the engine enters one of these cells, the PCM looks at the amount of short-term correction being used. Because the goal is to keep short-term at zero (O2 switching at 0.5 volt), long-term will update in the same direction as short-term correction was moving to bring the short-term back to zero. Once short-term is back at zero, the long-term correction factor will be stored in memory.

			Open '	Throttle	 	Decel	Idle
RPM							
1701 to 3000*	2	5					
1217-1504	1	4					21
0-1216	0	3					20
MAP	14	.6"					

**V8** 

**V6** 

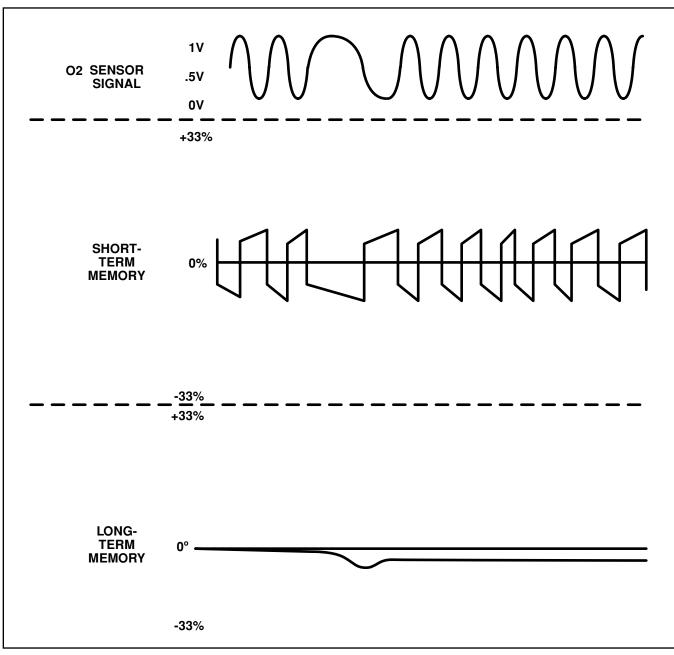
| -----| Decel Idle

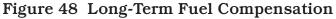
RPM				-					
1601								]	
to 3200*		2	5	8	11	14	17		
1281-1600		1	4	7	10	13	16	19	21
0-1280		0	3	6	9	12	15	18	20
MAP 23.58" 19.57" 15.71" 11.81" 9.33" 4.45"									

\* Long term is used up to RPM limiter, however, it is not updated above the approximate rpm shown.

**NOTE:** The 5.9L heavy-duty engine has twin adaptive memories. This means that there are 22 memory cells for each cylinder bank.

Table 3 Long-Term Adaptive Memory Fuel Cells





The values stored in long-term adaptive memory are used for all operating conditions, including open loop. However, updating long-term memory occurs after the engine has exceeded approximately  $170^{\circ}$ F, with fuel control in closed loop and two minutes of engine run time. This is done to prevent any transitional temperature or start-up compensations from corrupting long-term fuel correction.

Using the low fuel-pressure example, the PCM had stored a fuel correction in longterm memory to compensate for the low fuel pressure. At key-on, cold engine, when the PCM does its pulse-width calculation, the long-term factor will be added, because it knows there was a problem in that cell. Long-term adaptive can change the pulse width by as much as 33%, which means it can correct for all of shortterm. It is possible to have a problem that would drive long-term to 33% and shortterm to another 33% for a total change of 66%, away from base pulse-width calculation.

Short- and long-term is expressed as a percentage of pulse-width change.

#### **Purge-Free Cells**

Purge-free memory cells are used to identify the fuel vapor content of the evaporative canister. Since the evaporative canister is not purged 100% of the time, the PCM stores information about its vapor content in a memory cell. The construction of purge-free cells is similar to that of certain purge-normal cells. For example: the V8 purge-free cells have the same rpm and MAP structure of cells 6, 7, 10, and 20. The purge-free cells can be monitored by the DRB III scan tool. They are represented by Idle Purge-Free Cell "PF6, PF7, PF10, PF20." The only difference between the purge-free cells and normal adaptive cells is that in purge-free, the purge is turned off completely. This gives the PCM the ability to compare purge and purge-free operation.

#### **Purge Corruption Reset Feature**

At a cold start, the PCM compares the value of the purge-free cell to the value in long-term memory. If the difference is too large, the PCM will replace the value in long-term memory with the corresponding purge-free cell value (fig. 49). The cells that do not have corresponding purge-free will be replaced with the largest purge-free value. If a cell is already higher than the highest purge-free, it will not be changed.

LONG-TERM ADAPTIVE MEMORY																								
		<b>-</b> ø	+1		3⁄1	+1		-3	+1 +1		+3		+1											
	C2			C5			<b>C</b> 8			C11			C14			C17						[		
		-4	+1		3⁄2	+1		-ø	+1		ø	+1		-1	+1		-1	+1		-1	+1		4	+1
	C1			C4			C7			C10			C13			C16			C19			C21		
		-4	+1	-	3⁄2	+1		-3⁄0	-3		-3⁄	+1		-1	+1		ø	+1		+2		-2	t	-4
	<b>C</b> 0			C3			C6			C9			C12			C15			C18			C20		
													-											
		-3			+1			+1			-4													
	PF3	I		PF6			PF7	PF7 PF20																
	V8   Open Throttle   Decel Idle RPM																							
	601																							
	to 3200* 2 5 8 11 14 17																							
1	281	-16	600				1		4		7			10	)	1	3		16		1	.9		21
0	0-1280 0 3 6 9 12 15 18 20									20														
*L	MAP 23.58" 19.57" 15.71" 11.81" 9.33" 4.45" *Long term is used up to RPM limiter, however, it is not updated above the approximate rpm shown.																							

Figure 49 Purge Corruption Reset

#### **DRB III Display**

The DRB III can be used to display both of these systems. The long-term memory cells are shown with the long-term correction factor in each cell. The short-term correction is always changing and is displayed above the long-term memory cells. The DRB III displays long-term adaptive memory cells similar to Table 3.

#### **ACTIVITY 9 — FUEL ADAPTIVE MEMORY**

#### Instructions

Have the instructor assign you to a vehicle. Using the appropriate Service Manual or Powertrain Diagnostic Procedures Manual as reference material, answer the following questions.

1. With the engine running, use the simulator to reduce fuel pressure. What happened to adaptive memories?

Restore fuel pressure.

- Using the simulator, change MAP both up and down. What happened to adaptive memories?
   Why?

- 6. Pull off a spark plug wire. What happened to adaptive memories?

#### PARK/NEUTRAL SWITCH (AUTO TRANSMISSION ONLY)

The Park/Neutral switch is located on the transmission housing. The Park/Neutral switch uses the same contacts as the starter relay, and provides a path to ground when the vehicle is shifted into PARK or NEUTRAL.

The PCM delivers 12 volts to the center terminal of the Park/Neutral switch (fig. 50). When the gear shift lever is moved to either the PARK or the NEUTRAL position, the PCM receives a ground signal from the Park/Neutral switch. With the shift lever positioned in DRIVE or REVERSE, the Park/Neutral switch contacts open, causing the signal to the PCM to increase.

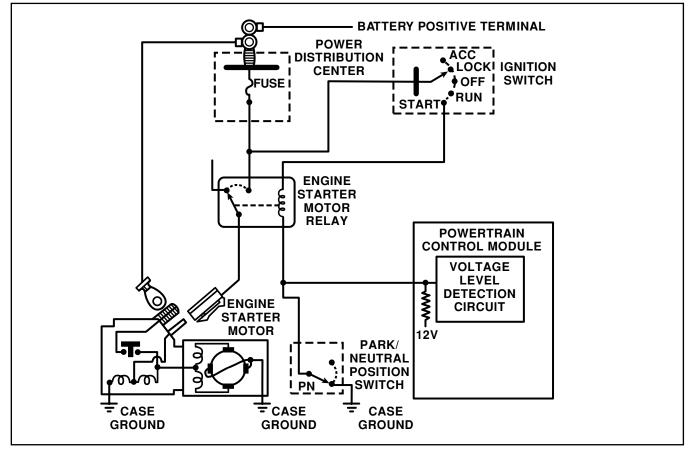


Figure 50 Park/Neutral Switch Circuit

The Park/Neutral switch sends a signal to the PCM to identify gear engagement. From the time that the shift lever is moved into a forward or reverse gear, until the transmission is fully engaged into a gear, may be several milliseconds. When the Park/Neutral switch changes, identifying when the transmission is shifted into gear, the PCM increases the IAC steps before the transmission clutch engages. This prevents the engine rpm dropping as the transmission engages and puts a load on the engine.

#### **OBD II Rationality Test**

There is an OBD II rationality fault for the Park/Neutral switch. If the PCM sees vehicle movement based on vehicle speed, MAP, TPS, engine rpm, and the wrong Park/Neutral state is indicated, a fault will be set. The PCM also checks for indication of Park/Neutral during start and will set a fault if the vehicle is started in Drive.

#### **Clutch Pedal Position Switch**

If the vehicle is equipped with a manual transmission, it has a clutch pedal position switch installed in series between the ignition switch and the coil battery terminal of the starter relay. This normally open switch prevents the starter relay from being energized unless the clutch pedal is depressed. This prevents starter operation while the clutch disc and flywheel are engaged. The starter relay is always grounded on vehicles with manual transmissions.

The PCM uses information from the Park/Neutral switch to calculate the following:

- Spark-advance programs (idle control)
- Injector pulse-width programs (long-term memory cells 20 and 21)
- Speed-control disengagement
- Target idle
- Anticipation of the load increase (IAC and timing)
- There are no OBD II diagnostics in Park/Neutral

#### **BRAKE SWITCH**

When the brakes are applied, the brake switch provides an input to the PCM to disengage the speed control. It is also used to influence transmission torque-converter clutch disengagement.

The brake switch is equipped with three sets of contacts, one normally open and the other two, normally closed (brakes disengaged). The PCM sends a 12-volt signal to one of the normally closed contacts in the brake switch, which is connected to a ground. With the contacts closed, the 12-volt signal is pulled to ground, causing the signal to go low. The low-voltage signal, monitored by the PCM, indicates that the brakes are not applied. When the brakes are applied, the contacts open, causing the PCM's output voltage to go high, disengaging the speed control, if so equipped (fig. 51).

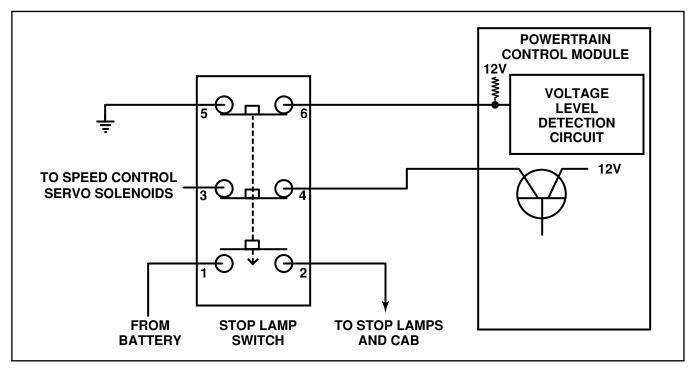


Figure 51 Brake Switch Circuit

If the brake switch circuit is pulled high, with or without brake pedal application:

- speed control will not work.
- there will be no torque converter lockup on vehicles equipped with an automatic transmission.

#### **Component Location**

The brake switch is located rearward of the brake pedal and is attached to the brake pedal sled (fig. 52).

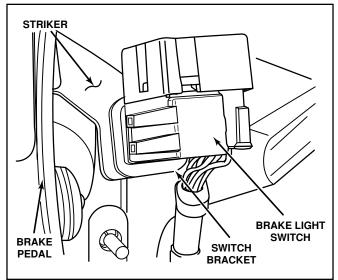
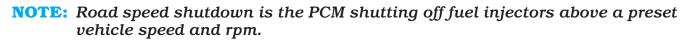


Figure 52 Brake Switch Location

#### **VEHICLE SPEED SENSOR (VSS)**

On all  $Jeep_{@}$  and truck vehicles, vehicle speed is transmitted to the PCM via the Vehicle Speed Sensor, which is located in the transmission extension housing. The PCM requires the VSS to control the following programs:

- Speed control
- IAC motor (during deceleration)
- Injection pulse width (during deceleration)
- OBD II diagnostics
- PCM mileage EEPROM
- Road speed shutdown
- Speedometer/Odometer



The VSS is a Hall-effect sensor. This sensor is mechanically driven by a pinion gear that is located on the output shaft of the transmission for 2-wheel drive vehicles, and on the output shaft of the transfer case for 4-wheel drive vehicles. The Hall-effect sensor switches a five-volt signal sent from the PCM from a ground to an open circuit at a rate of eight pulses per revolution. When the PCM counts pulses (8,000), the PCM assumes the vehicle has traveled one mile.

Like all Hall-effect sensors, the sensor electronics need a power source. This power source, the secondary 5-volt supply, is provided by the PCM (fig. 53). It is the same five-volt power supply that is used by the Transmission Pressure sensors on RE transmissions.

#### **Vehicle-Speed Sensor Diagnostics**

If the ECT indicates a warm engine while MAP and engine indicate vehicle movement and there is no VSS signal, a rationality fault will be set.

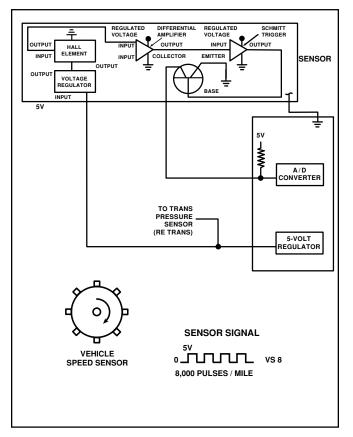


Figure 53 Vehicle Speed Sensor Circuit

#### **FUEL-LEVEL SENSOR INPUT**

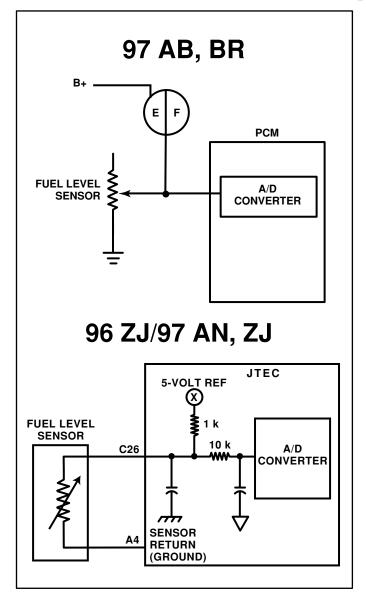
Fuel level is an input that is used as a disabler for OBD II. However, on 1996 BR and AN vehicles, this function was not enabled. These two vehicles do not have dual trace cards on the level sensor. On  $\text{Jeep}_{\mathbb{R}}$  vehicles and Dodge trucks, the fuel level is input directly to the PCM (fig. 54).

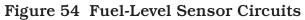
#### 97 AB, BR

On these vehicles, 12 volts is supplied through the fuel gauge to the sensor and PCM. The PCM measures the voltage drop across the resistor of the sensor.

#### 96 ZJ and 97 AN, ZJ

On these vehicles, the PCM sends five volts to the Fuel Level sensor. Depending on the level sensor resistance, the voltage drop changes and is converted to a fuel level. This information is then bused to the instrument cluster and BCM (if equipped).





## <u>3.9L/5.2L/5.9L Magnum Fuel Injection</u>

#### **BATTERY/AMBIENT TEMPERATURE SENSOR**

The PCM uses an input from the Battery/Ambient Temperature Sensor (BTS) located on the battery tray (fig. 55). The function of the BTS is to enable control of the generator output, based upon ambient temperature. As temperature increases, the charging rate should decrease. As temperature decreases, the charging rate should increase. The PCM maintains the maximum output of the generator by monitoring battery voltage and controlling battery voltage to a range of 13.5-14.7 volts.

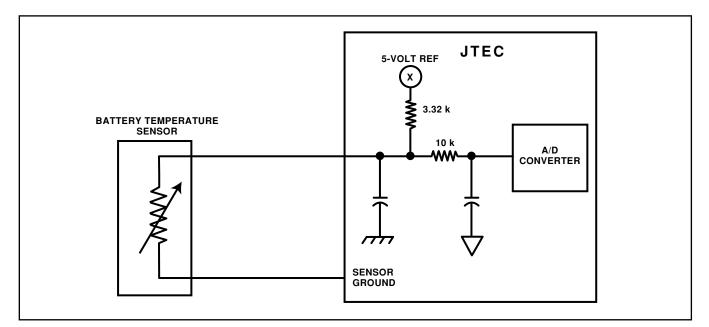


Figure 55 Battery/Ambient Temperature Sensor Circuit

Battery Temperature (°F)	Target Charging Rate
-4	15.19 - 14.33
32	14.82 - 13.96
68	14.51 – 13.65
104	14.08 – 13.22
144	13.77 – 13.04

Table 4Charging Rates

The PCM sends 5 volts to the sensor and is grounded through the sensor return line. As temperature increases, resistance in the sensor decreases (fig. 56).

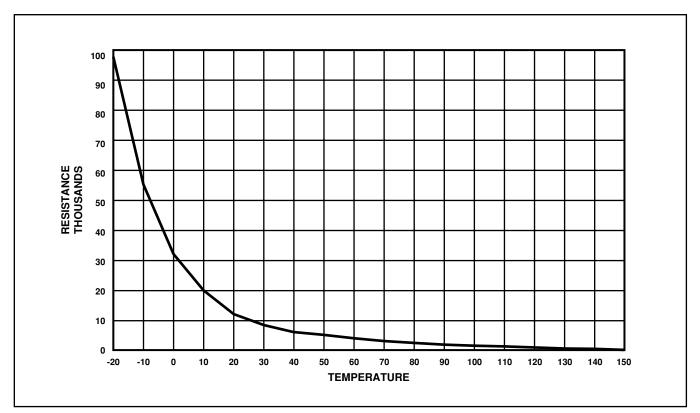


Figure 56 Battery Temperature Sensor — Resistance vs. Temperature

As temperature increases, detection voltage at the PCM decreases (fig. 57).

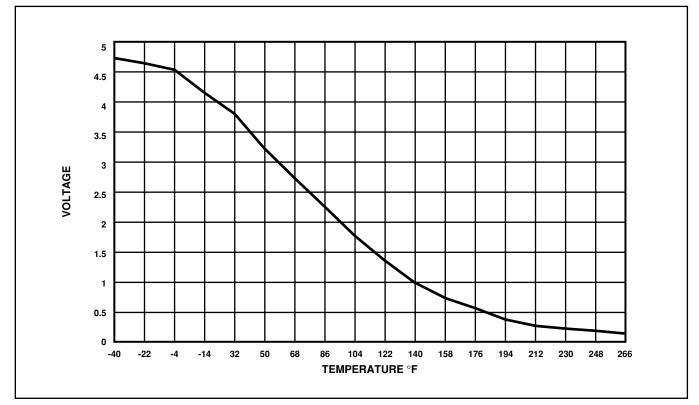


Figure 57 Battery Temperature Sensor — Temperature vs. Voltage

The BTS is also used for OBD II diagnostics. Certain faults and OBD II monitors are either enabled or disabled, depending upon BTS input (for example, disable purge and enable Leak Detection Pump (LDP) and O2 Sensor heater tests). Most OBD II monitors are disabled below 20°F.

If the BTS signal indicates a voltage that is too high or too low, the PCM sets a DTC. When the DTC is set, the MIL is illuminated and the PCM moves into limp-in mode. In limp-in, the PCM will substitute a preset value. Using this substitute temperature, the PCM changes to a preset target-charging system voltage.

#### **Battery Temperature Sensor Diagnostics**

- Batt Temp Sensor Voltage Low is set if the sensor voltage is below 0.08 volt.
- Batt Temp Sensor Voltage High is set if sensor voltage is above 4.9 volts.

#### AIR CONDITIONING SWITCH

#### **BR/AN**

When the A/C-heater control switch is moved to an A/C position or the defroster position, the PCM A/C select circuit is pulled low when ground is provided through the panel switch. The PCM request circuit is also pulled low if the A/C pressure switches are closed (fig. 58). Refer to the A/C section for more information.

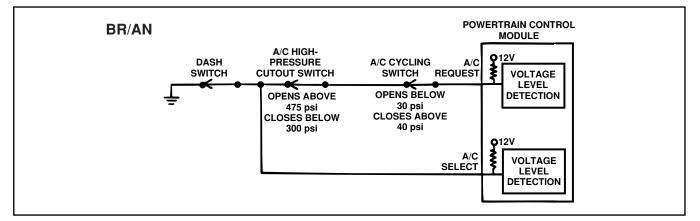


Figure 58 BR/AN Air Conditioning Switch Circuit

#### ZJ

When the A/C-heater control switch is moved to an A/C position or the defroster position, a signal is sent to the Body Control Module (BCM). The BCM then sends a message over the CCD bus to the PCM (fig. 59). The PCM request circuit is pulled low if the A/C pressure switches are closed. Refer to the A/C section for more information.

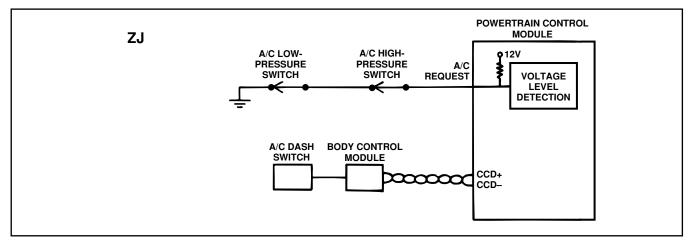


Figure 59 ZJ Air Conditioning Switch Circuit

#### AB

When the A/C heater control switch is moved to an A/C position, or the defroster position, the PCM A/C select circuit is pulled low when ground is provided through the panel switch. The PCM request circuit is also pulled low if both the high and low pressure switches and the electronic cycling switch are closed (fig. 60).

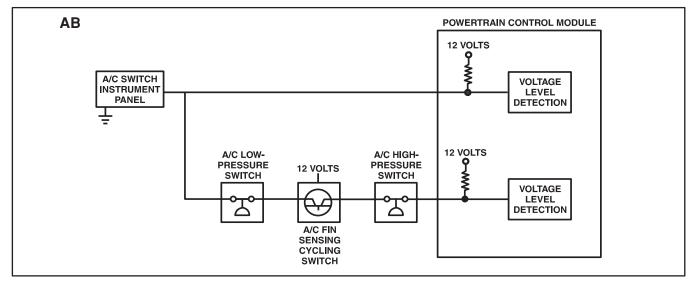


Figure 60 AB Air-Conditioning Switch Circuit

#### **TORQUE REDUCTION (TORQUE MANAGEMENT)**

Torque reduction is a function of the TCM portion of the PCM (JTEC), commanding the engine control portion to momentarily decrease spark advance. This occurs while the transmission is performing high-torque, high-speed shifts (1-2, 2-3). The decrease in spark advance happens so rapidly that the driver is never aware that the timing change occurred. The reason for torque reduction is that when the transmission is shifting from one gear to the next, one clutch must release before the next gear clutch is applied. A fraction of a second goes by while the transmissions actually not in any gear. When the engine is at WOT, the transmission will be under the most adverse conditions. To help eliminate the abrupt transfer of torque on the clutch discs, the PCM will reduce timing advance to zero degrees.

#### **STALL TORQUE MANAGEMENT**

To reduce torque converter stall at high loads and low rpm, the PCM limits engine torque to approximately 225 lb-ft for engine speeds under 2,100 rpm at WOT and less than 400 rpm transmission output shaft speed.

#### **TRANSMISSION-FLUID TEMPERATURE SENSOR**

Transmission fluid temperatures are supplied to the TCM portion of the PCM. The input is used in the shift operation for 4-speed electronic transmissions only. The temperature data is used for:

- Torque converter clutch operation.
- Overdrive shift.
- Low-temperature shift compensation.
- Wide-open-throttle shift strategy.
- Governor-pressure transducer calibration.

Refer to the transmission section for more information.

#### **TRANSMISSION-GOVERNOR PRESSURE SENSOR**

The governor pressure sensor measures output pressure of the governor-pressure solenoid valve. This input is used with 4-speed electronic transmissions only. The sensor provides the PCM with the necessary feedback to control the governor-pressure solenoid, which regulates transmission governor pressure.

Refer to the transmission section for more information.

#### **TRANSMISSION-OUTPUT SHAFT SPEED SENSOR**

This sensor generates an AC signal to the PCM relating to the speed of the transmission main driveshaft. This input is used with 4-speed electronic transmissions only.

Refer to the transmission section for more information.

#### **OVERDRIVE OFF SWITCH**

On vehicles equipped with an automatic transmission and overdrive, there is a momentary contact switch that signals the PCM to toggle current status of the overdrive function. The overdrive push-button switch is normally open (overdrive allowed) when the lamp is not illuminated. It momentarily closes (overdrive not allowed) when the operator presses the switch and the lamp is illuminated. Overdrive will revert to ON (lamp off) each time the ignition switch is turned off and then back on.

Refer to the transmission section for more information.

#### **VEHICLE SPEED CONTROL**

To operate the speed control system, the PCM requires inputs from:

- Speed control switches.
- Brake switch.
- Park/Neutral switch.
- Vehicle speed sensor.
- Engine speed.

Refer to the Vehicle Speed Control section in this publication for more information.

#### **LEAK DETECTION PUMP**

A reed switch is attached to the vacuum-driven pump and wired to the PCM. The PCM monitors the change in switch state to determine how long the pump has operated. This input is used to determine if there is a leak in the evaporative system. Refer to the Emission Control Systems section of this publication for more information.

#### **ASD SENSE CIRCUIT**

The PCM receives a battery voltage signal at pin C12, indicating that the Automatic Shut Down (ASD) relay has energized. It uses this input for diagnostic purposes. The PCM provides the relay coil with a path to ground as an output function. Refer to the Output Section on the ASD relay for more information.

#### ACTIVITY 10 — PCM INPUTS

#### VSS

- 1. Change DRB III to find vehicle speed. With engine running at idle, closed throttle, slowly increase road speed to 60 mph. What happened to engine speed? Why?
- 2. Open throttle to 3,000 rpm. Slowly increase road speed. At what speed did the road speed shutdown occur?
- 3. With vehicle in road speed shutdown, what does injector pulse width display?
- 4. With road speed at closed throttle 30 mph, what does VSS display on Lab Scope?
- 5. Change road speed. What happened to display?\_\_\_\_\_
- 6. Disconnect simulator. Open VSS switch. What does voltage read on both sides of the switch?

#### Engine off.

- 7. Change DRB III to read fuel level. What level is shown?
- 8. Change DRB III to read Batt/Ambient Temp Sensor. What does it show for voltage?

\_\_\_\_\_

And temperature?\_\_\_\_\_

Erase codes when done.

NOTES

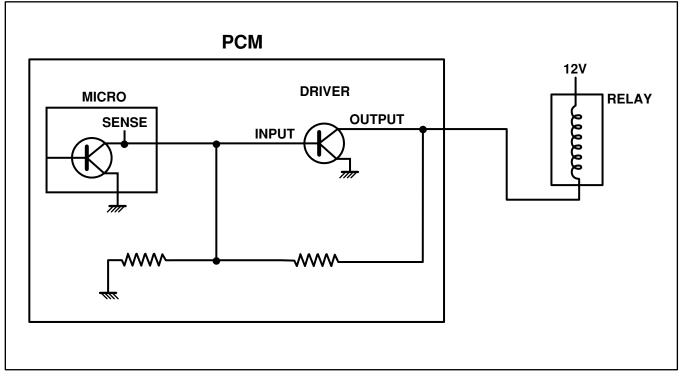
### **LESSON 5**

#### **FUEL INJECTION SYSTEM — PCM OUTPUTS**

#### **SOLENOID AND RELAY CONTROL**

Most of the output relays and solenoids are controlled by quad drivers. A quad driver is a single microchip that contains four separate driver circuits that are used for controlling high current output devices.

A voltage divider circuit has been added to diagnose the operation of the driver circuit. This voltage divider is located between the output of the driver and the input command (from microprocessor) to the driver.





There is a sense circuit located at the microprocessor on the input command line to the driver. When the command is OFF, the 12 volts from the relay coil will go through the voltage divider leaving 6 volts at the sense point. Therefore, an OFF command will look for voltage to be high (fig. 61).

When the command is ON, the micro closes a circuit allowing the 6 volts to go to ground. This energizes the driver. When the driver is energized, the 12 volts are allowed to go to ground through the driver. Once this occurs, the voltage at the sense point goes low. Therefore, an ON command will look for voltage to be low.

Because of this design, the PCM is capable of continuous diagnostics, without the need for a request to change state.

When the key is first turned on, some relays and solenoids are actuated very quickly (before engine starts) to verify the circuitry.

Once the key is turned on, the sense point is continuously monitored. If a circuit opens or a short to ground occurs when the requested state is off, a fault will be set. However, if a circuit should open or short to ground when the requested state is ON, this will not be detected until the state is changed to OFF. This is due to the fact that when the state is ON, the circuit is already low, so it is not possible to know that an open has occurred.

<u>Caution</u>: Both diode- and resistor-suppressed relays have been used. If an incorrect relay is used, damage may occur to the relay, circuit or PCM.

#### **AUTOMATIC SHUTDOWN RELAY (ASD)**

When energized, the ASD relay provides power to operate the injectors, ignition coil, generator field (1996) and O2 Sensor heaters (upstream and downstream). It also provides a sense circuit to the PCM for diagnostic purposes. The PCM energizes the ASD relay:

- Anytime there is a Crankshaft Position sensor signal that exceeds a predetermined value.
- For approximately 1.8 seconds during the initial key-on cycle.

With the PCM (JTEC), the ASD relay electromagnet is fed battery voltage from the ignition switch (figs. 62 and 63). The PCM still provides the ground.

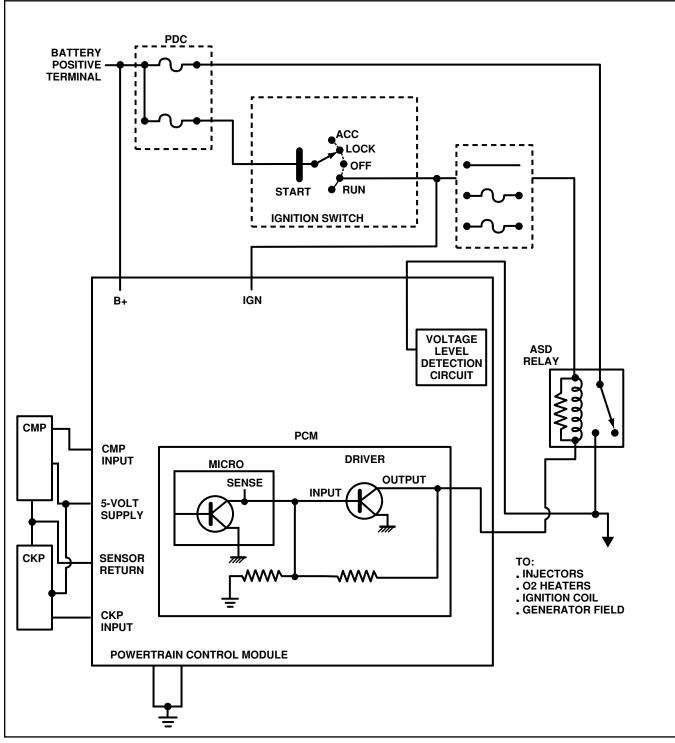


Figure 62 ASD Relay Circuit — Typical '96

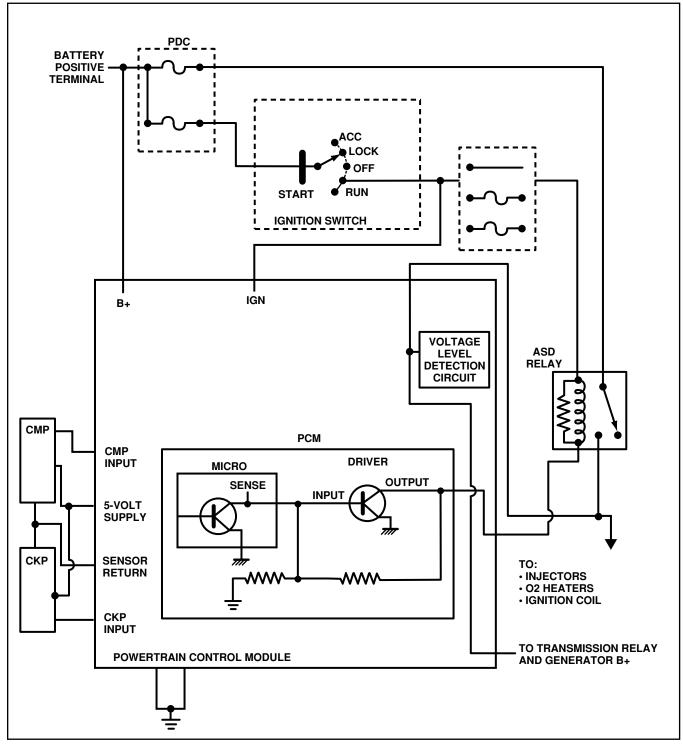


Figure 63 ASD Relay Circuit — Typical '97

#### FUEL PUMP RELAY

The fuel pump relay is energized to provide power to operate the fuel pump under the following conditions:

- For approximately 1.8 seconds during the initial key-on cycle.
- While the CKP sensor is providing an rpm signal that exceeds a predetermined value.

Ignition voltage is provided to the fuel pump relay's electromagnet any time the key is in the RUN position (fig. 64). The PCM provides the ground control to energize the relay. Unlike previous Chrysler systems, the fuel pump relay does not provide power to operate the O2 Sensor heaters.

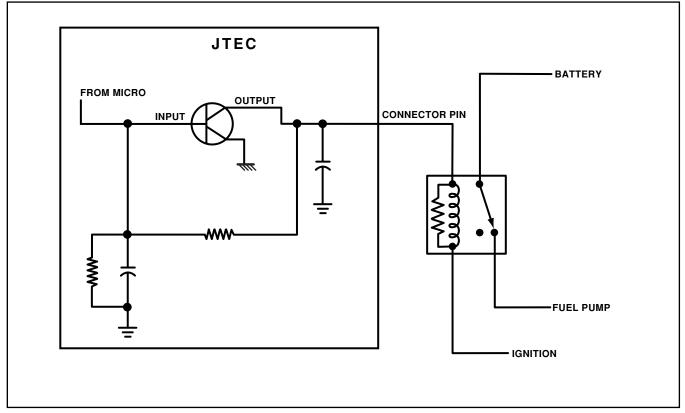


Figure 64 Fuel Pump Relay Circuit

The relay is energized when the key is cycled to RUN in order to prime the fuel rail with liquid fuel, allowing for a quick start-up. Anytime the Crankshaft Position sensor indicates that there is an rpm signal that exceeds a predetermined value, the relay is energized to ensure proper fuel pressure and volume during engine cranking and running conditions. Anytime the Crankshaft Position sensor signal is lost (engine has been shut off, or the sensor indicates no rpm), the fuel pump relay is de-energized.

#### **FUEL INJECTORS**

The PCM provides battery voltage to each injector through the ASD relay (fig. 65). Injector operation is controlled by a ground path, provided for each injector by the PCM. Injector on-time (pulse width) is variable, and is determined by the duration of the ground path provided.

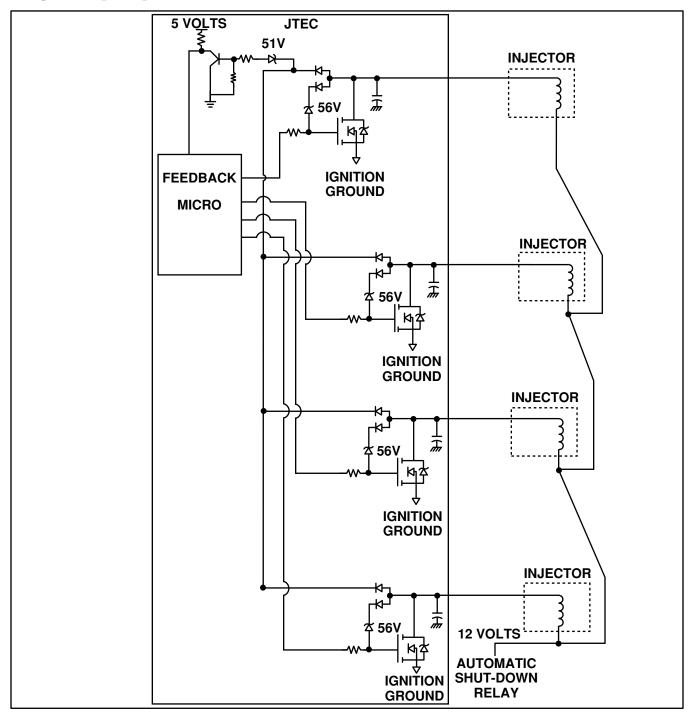


Figure 65 Fuel Injection Circuit

#### **Fuel Injector Diagnostics**

To diagnose an injector, the PCM monitors the voltage spike created by the collapse of the magnetic field through the injector coil. The inductive kick is typically about 60 volts (fig. 66). Any condition that restricts maximum current flow would not allow the kick to occur, resulting in an injector fault.

See the description of fuel injectors in the Fuel System Components section of this reference guide, for further information.

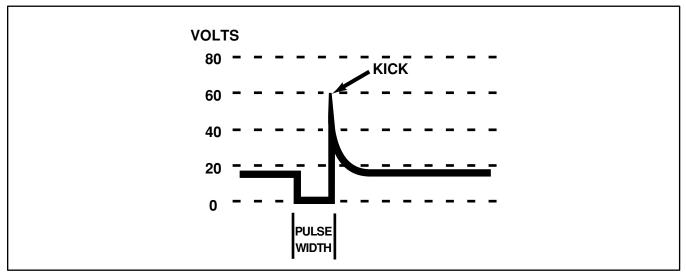


Figure 66 Injector Spike

#### **ACTIVITY 11 — FUEL PUMP/FUEL INJECTORS**

#### Activities

Have the instructor assign you to a vehicle equipped with either a V6 or V8 engine. Use the DRB III and PEP module to assist in answering the following questions:

- 1. Connect a DRB III to the vehicle and actuate the ASD relay test. What happens?
- 2. Actuate the fuel pump relay test. What happens? \_\_\_\_\_
- 3. Change the DRB III to a lab scope. How much voltage is generated by either relay when the coil field collapses?\_\_\_\_\_
- 4. Start engine. Go to sensors on the DRB III and display pulse width. How much time is shown?
- 5. Change the DRB III back to a lab scope. How much voltage is generated when the injector coil collapses?\_\_\_\_\_
- 6. Open the ground path to an injector. What does the scope display?

#### **IGNITION COIL**

The PCM provides battery voltage to the ignition coil through the ASD relay (fig. 67). Coil operation is controlled by a ground path provided to the coil by the PCM. The ignition coil fires a spark plug at every power stroke.

The PCM determines when to fire the coil, based on the crankshaft sensor input. The ignition coil primary is joined to the power wire from the ASD relay. The ASD relay provides battery feed to the ignition coil, while the PCM provides a ground contact for energizing the coil. When the PCM breaks the ground contact, power transfers from the primary to the secondary, causing the spark.

Resistance on the primary side of the coil should be between 0.95 and 1.20 ohms. The resistance of the secondary side is between 11,300 and 15,300 ohms. The coil has the ability to provide up to 40,000 volts, if needed.

There are two different suppliers for ignition coils. Refer to the Service Manual for the correct specifications.

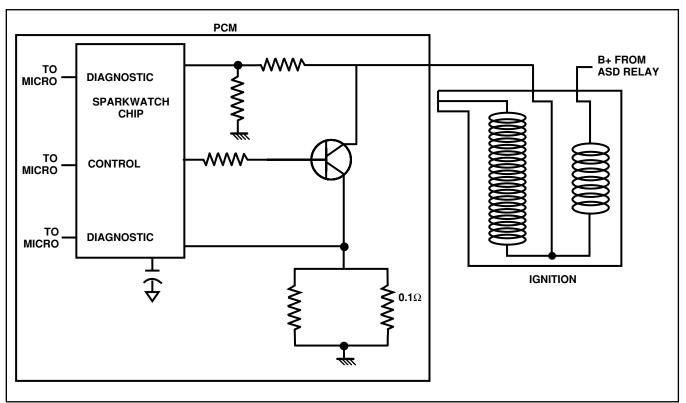


Figure 67 Ignition Control Circuit

#### **Coil Operation**

When a conductor is formed into a coil, the magnetic field is many times stronger than that of a single straight conductor. To increase the strength of the magnetic field, you must either increase the number of loops in the coil, increase the amount of current flowing in the coil, or use a low-reluctance material for the core of the coil.

If one coil is placed near another coil, and the first coil is connected to a current, the expanding magnetic field induces a current into the second coil. The current induced into a coiled conductor is much higher than a current induced into a straight conductor. The coil that carries current into this type of induction system is the primary winding of the coil. The coil into which electromotive force is induced, is the secondary winding of the coil. This mutual induction is the principle behind automotive ignition coils.

To induce a current, the magnetic field must be moving. Once the magnetic field has stabilized and is not expanding through the secondary conductor, no current is induced in the secondary conductor. As the field collapses, the lines of force pass through the secondary winding, which now induces a current in the opposite direction. When the field has completely collapsed, current flow in the secondary conductor stops.

The amount of secondary voltage generated depends on the amount of flux, the number of turns in the secondary coil, and the speed at which the primary current is interrupted. "Flux" refers to the lines of force in motion, which create a magnetic field. The amount of flux depends on the primary circuit. More current in this circuit means more flux. The flux moves through the windings of the secondary coil, so, more turns in the secondary coil result in more voltage. Flux collapses through the secondary coil when the primary current is interrupted. A quick interruption causes the flux to cut through the secondary windings faster. A quicker interruption results in more secondary voltage than a slow interruption.

#### **PCM Operation**

The PCM toggles the ignition coil current driver ON, and then at some point before the CKP sensor indicates TDC, toggles it off. The amount of ON time (dwell), and the point at which the PCM toggles the driver OFF, is determined by several inputs to the PCM. To achieve the best spark advance program, the PCM calculates when to energize and de-energize the ignition coil.

These calculations require inputs from:

- CKP sensor
- MAP sensor
- ECT sensor
- IAT sensor
- TPS
- Engine EPM
- Battery voltage
- Park/Neutral position switch

Base timing is non-adjustable but is set from the factory at approximately  $10^{\circ}$  BTDC, when the engine is warm and idling.

Dwell is a constant at low rpm based on battery voltage. The constant dwell allows for a constant voltage at the coil for a consistent spark. However, at higher rpm there is not enough time for full saturation, so the PCM changes to an 80-20 duty cycle. By allowing current to flow 80% of the time, a sufficient magnetic field can be built regardless of rpm. This duty cycle allows for sufficient spark to operate.

#### **IDLE AIR CONTROL (IAC) STEPPER MOTOR**

#### Description

The IAC stepper motor is mounted to the throttle body and regulates the amount of air bypassing the control of the throttle plate. As engine load and ambient temperature changes, engine rpm also changes. A pintle on the IAC stepper motor protrudes into a passage in the throttle body, controlling airflow through the passage. The IAC is controlled by the PCM to maintain the target engine idle speed.

At idle, engine speed can be increased by retracting the pintle and allowing more air to pass through the port, it can be decreased by restricting the passage with the pintle and diminishing the amount of air bypassing the throttle plate.

When engine rpm is above idle speed, the IAC is used for the functions listed below.

- Off-idle dashpot
- Deceleration airflow control
- A/C compressor load control (also opens the passage slightly before the compressor is engaged so that the engine rpm does not dip down when the compressor engages)

The PCM can control polarity of the circuit to control direction of the stepper motor.

#### **Operation**

The IAC is called a stepper motor because it is moved in "steps." The IAC motor is capable of 255 total steps, from fully closed to fully open. Opening the IAC in turn opens an air passage around the throttle blade which increases engine rpm.

The PCM uses the IAC motor to control idle speed (along with timing) and to reach a desired MAP during decel (keep engine from stalling).

The stepper motor has four wires (fig. 68). Two wires are for 12 volts and ground. The other two wires are for 12 volts and ground. The stepper motor is not really a motor at all. The pintle that moves in and out can be thought of as a bolt with threads (fig. 69). The "nut" is a permanent magnet. There are two windings by the permanent magnet. When the PCM energizes one set of windings, this makes an electromagnet. The permanent magnet, which is allowed to rotate, is attracted to the electromagnet and rotates until the north and south poles line up. Once the poles line up, the nut stops turning. At this time, the PCM will energize the other winding. This moves the "nut" one more step. As the nut turns, the pintle (bolt) moves out or in.

To make the IAC go in the opposite direction, the PCM just reverses polarity on both windings. If only one wire is open, the IAC can only be moved one step in either direction.

# **NOTE:** To keep the IAC motor in position when no movement is needed, the PCM will energize both windings at the same time. This locks the IAC motor in place.

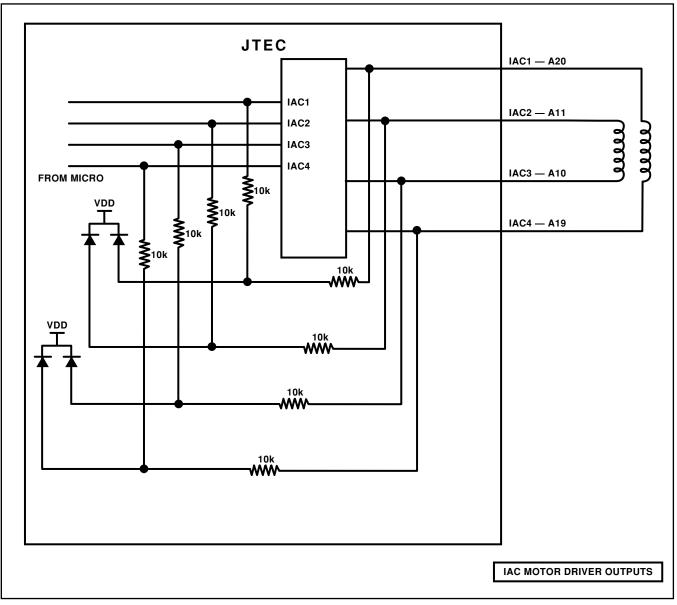


Figure 68 IAC Motor Control Circuit

In the IAC motor system, the PCM will count every step that the motor is moved. This allows the PCM to "know" the motor pintle position. If the memory is cleared, the PCM no longer knows the position of the pintle. So, at the first key ON, the PCM drives the IAC motor closed, regardless of where it was before. This "zeros" the counter. From this point, the PCM will back out the IAC motor and keep track of its position again.

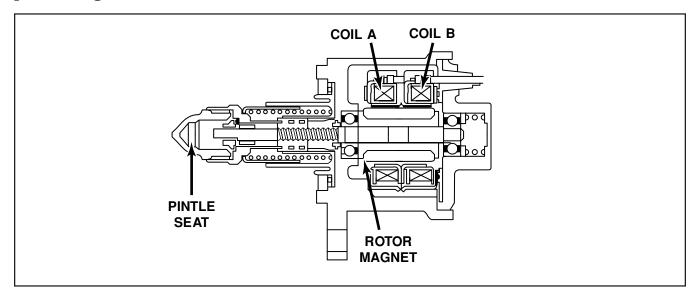


Figure 69 IAC Internal View

#### IAC Stepper Motor Program

When the pintle has completely blocked the air passage, the IAC stepper motor is at step zero (fig. 70). The PCM has the authority to increase the opening by approximately 220 steps. The IAC stepper motor cannot identify in exactly which position the pintle is, so the PCM has a program that enables it to learn the position of the IAC pintle.

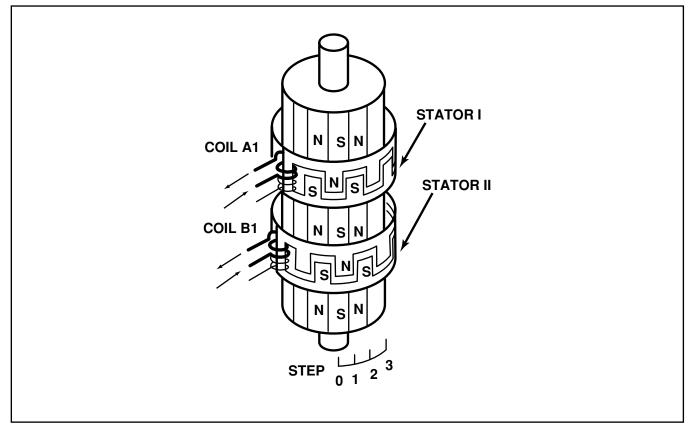


Figure 70 IAC Motor

The program begins by learning step zero. This is accomplished by the PCM driving the IAC stepper motor closed for several seconds when the key is first turned to the RUN position after a battery disconnect. The PCM assumes that, at the end of the cycle, the IAC stepper motor should be at step zero. Once the stepper motor finds step zero, the PCM backs the motor to the open position. The number of steps needed to arrive at the open position is based upon information delivered by the ECT sensor. The program can be updated by the DRB III, or by disconnecting battery voltage from the PCM and then reconnecting it.

The PCM is also equipped with a memory program that records the number of steps the IAC stepper motor most recently advanced to during a certain set of parameters. For example: The PCM was attempting to maintain a 750 rpm target during a hot start-up cycle. The last recorded number of steps for that may have been 27. That value would be recorded in the memory cell, so that the next time the PCM recognizes the identical conditions, the PCM recalls that 27 steps were required to maintain the target. This program allows for greater customer satisfaction due to greater control of engine idle.

Another function of the memory program during that key cycle occurs when the A/C request circuit requires the IAC stepper motor to control engine rpm. This is the recording of the last targeted steps.

As mentioned earlier, the PCM can "anticipate" compressor loads. This is accomplished by delaying compressor operation for approximately 0.5 second, until the PCM moves the IAC stepper motor to the recorded steps that were loaded into the memory cell. Using this program helps eliminate idle-quality changes as loads change.

#### **Target Idle**

Target idle, as shown on the DRB III, is determined by the following inputs:

- Engine Coolant Temperature sensor
- Park/Neutral Position switch

The IAC motor position is determined by the following inputs:

- IAC Motor Position
- Battery Voltage
- Vehicle Speed (VSS)
- Throttle Angle (TPS)
- MAP
- Engine Coolant Temperature
- Park/Neutral Position switch
  - RPM
  - A/C compressor

#### **IAC Stepper Motor Service**

Anytime the IAC stepper motor or its circuit is serviced, the IAC memory cell must be updated. Use the DRB III to "Reset IAC." This ensures that the PCM can identify step zero. Also, be sure that when the IAC stepper motor is installed into the throttle body, the passage is clear of debris and that the pintle does not protrude too much. Before installing an IAC motor, make sure that the pintle is in a retracted position. This will ensure that the pintle and seat are not damaged when the IAC motor is installed.

#### **IAC Diagnostics**

IAC Diagnostics have changed with the use of the JTEC. Open circuits are diagnosed if they are present at key-on. However, if a driver circuit opens while the engine is running, it will not be diagnosed until the next key-on cycle.

Short circuits to B+ and ground are diagnosed at key-on and also while the engine is running.

#### **Minimum Airflow**

Minimum airflow is the volume of air flowing past the throttle blades at idle and through any other components that might allow air to flow into the intake manifold at idle, such as the PCV valve.

Minimum airflow specifications aid in complete engine system diagnostics. Items such as poor driveability, worn engine components, engine components out of adjustment, exhaust restrictions, and many other items can have an effect on minimum airflow. In short, a minimum airflow check can be done only after all fuel, ignition, emission, and engine mechanical components have been verified as good. Other concerns include components that might put a load on the engine at idle (radiator or condenser fans operating or the A/C compressor being engaged during the test).

When performing a minimum airflow check, all accessories should be off. The test is performed with Tool 6714 (Metering Orifice) and the DRB III scan tool. The tool is simply a 0.185-in. orifice, and the DRB III scan tool is used to access a program that causes the IAC motor to close off the idle air bypass port completely. The tool is installed to allow the engine to run on a calibrated airflow. Minimum airflow specifications are:

• Idle should be between 500 and 900 rpm.

Refer to the Service Manual for proper installation procedures.

If idle speed is too high, check for a vacuum leak or see if the IAC motor is not fully seated.

If idle speed is too low, check for a dirty throttle body or mechanical problems. DO NOT adjust the idle stop screw.

#### ACTIVITY 12 — IAC MOTOR

Use DRB III and create custom display:

- MAP vacuum
- Min TPS

• Eng. RPM

• Actual TPS volts

- Target idle
- IAC STEPS
- Target IAC STEPS
- Spark advance

1. Restrict airflow (dirty air cleaner) by hand. What did you observe?

- 2. Make a vacuum leak. What did you observe?\_\_\_\_\_
- 3. Open the circuit at all four IAC circuits. What did you observe?
- 4. Close the vacuum leak. Note timing, rpm and IAC steps. What did you observe?
- 5. Turn the engine OFF. Close all four IAC circuits. Turn key ON. Where are the steps now?

 Was there an idle flare?

 Should there have been one?

6. Move P/N to drive gear (open BOB). What happened to IAC steps?

#### **Systems Test**

7. Perform the IAC wiggle test. Open one circuit on BOB. What happened to IAC steps?

#### Miscellaneous

- 8. Reset memory and IAC counter. Go back to custom display. Start the engine. What did you observe? \_\_\_\_\_
- 9. Hook up a second IAC. Go to Misc. Reset IAC. What did the pintle do? \_\_\_\_\_

#### **Generator Field Control**

The PCM regulates charging system voltage and determines the final goal or "target charging voltage." The target charging voltage is controlled mainly by the battery temperature sensor, which is located under the battery tray. Power to the generator field wiring is supplied by the ASD relay. For 1997 instead of the ASD supplying the power to the field winding, the PCM supplies the power at pin B10. This supply is connected internally to the ASD relay sense input. Field control is still accomplished by the PCM supplying the ground for the field winding (fig. 71). The PCM monitors battery voltage. If it senses that battery voltage is more than 0.5 volt lower than the target voltage, the PCM grounds the field winding until sensed battery voltage is 0.5 volt above target voltage. A circuit in the PCM cycles the ground side of the generator field up to 100 times per second (100 Hz), but has the capability to ground the field control wire 100% of the time full field, to achieve the target voltage. If the charging rate cannot be monitored (limp-in), a duty cycle of 25% is used by the PCM in order to have some generator output.

For 1997, instead of supplying the power to the field winding, the PCM supplies the power at pin B10. This supply is connected internally to the ASD relay sense input. Field control is still accomplished by the PCM supplying the ground for the field winding (fig. 72).

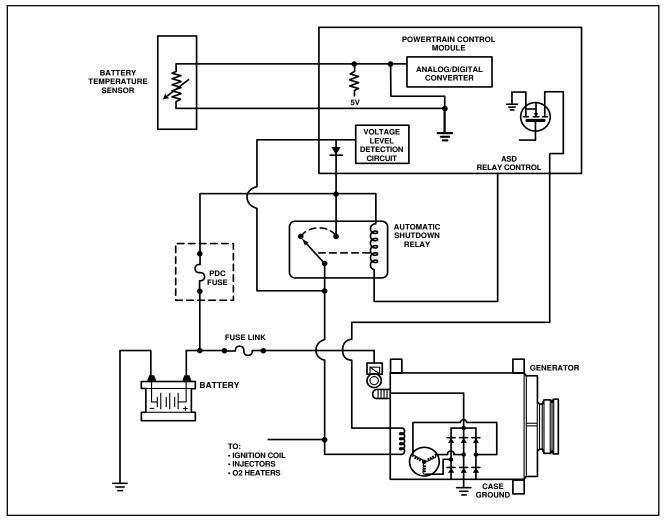


Figure 71 Generator Field Control Circuit — Typical '96

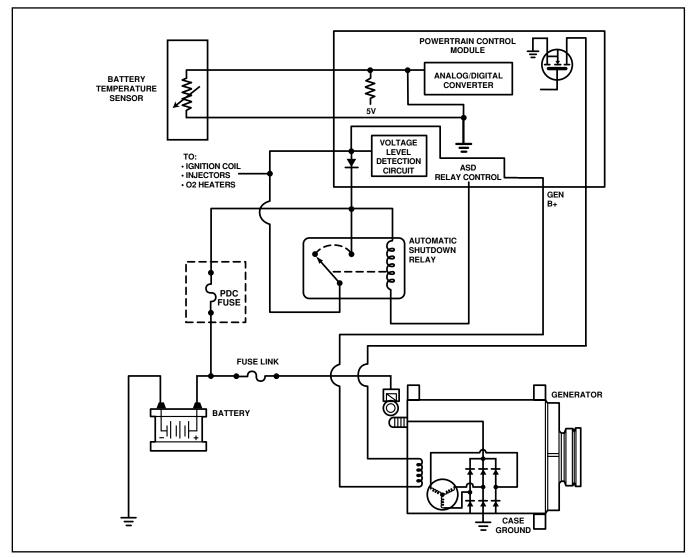


Figure 72 Generator Field Control Circuit — Typical '97

#### **CHARGING SYSTEM INDICATOR LIGHT (GENERATOR LAMP)**

The PCM controls the operation of the charging-system indicator light, located in the vehicle instrument cluster. On 1996 vehicles (except ZJ), the PCM provides a ground to complete the lamp circuit if the charging output falls below a specified threshold (fig. 73). In 1997 the ZJ and AN vehicles transmit the charging-system indicator light signal over the CCD bus to the instrument cluster.

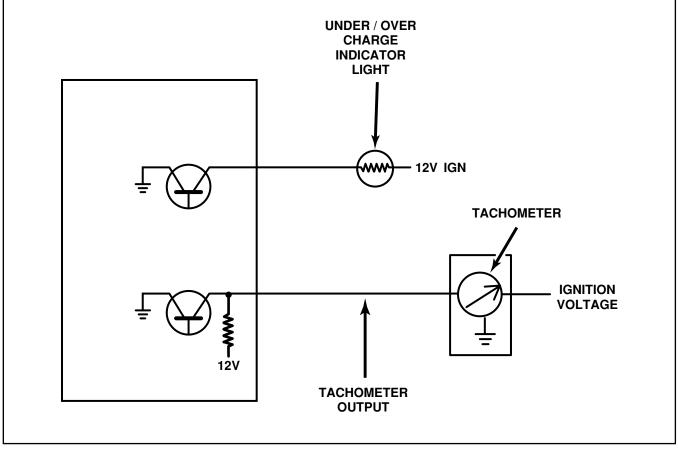


Figure 73 Generator Lamp Control Circuit

#### **TACHOMETER**

On 1996 vehicles (except ZJ), the PCM operates the tachometer which is located in the instrument panel. The PCM provides duty-cycle output voltage to the tachometer. The frequency of the duty cycle is based upon engine speed which is calculated from inputs from the CKP and CMP sensors. The 1996 ZJ and 1997 AN vehicles transmit the engine rpm signal over the CCD bus to the instrument cluster.

#### **OVERDRIVE LAMP**

This circuit controls a signal for the operation of the push-button overdrive lamp switch. When the lamp is illuminated, overdrive is disengaged.

Refer to the Transmission section for more information.

#### **TRANSMISSION RELAY**

The output to this relay provides battery voltage to the 3-4 shift solenoid, torqueconverter clutch solenoid and the governor pressure solenoid. Once battery voltage is applied to the solenoids, they are individually activated by the PCM through OD, TCC and governor pressure outputs.

If the relay output is open or shorted to ground when it should be off, or the output is shorted to 12 volts when it should be on, a fault will be set.

#### **THREE-FOUR SHIFT SOLENOID**

This output controls the transmission 3-4 shift solenoid. It is used on 4-speed, electronically controlled, automatic transmissions only.

Refer to the Transmission section for more information.

#### **GOVERNOR PRESSURE SOLENOID**

This solenoid regulates the transmission-fluid line pressure to produce the governor pressure necessary for transmission shift control. It is used on 4-speed, electronically controlled, automatic transmissions only.

Refer to the Transmission section for more information.

#### **MALFUNCTION INDICATOR LAMP (MIL)**

The MIL (CHECK ENGINE) lamp is located in the instrument cluster and can illuminate under more conditions than on previous models.

The PCM operates the MIL which illuminates for a three-second bulb test whenever the ignition is turned ON. The MIL lamp remains continuously illuminated when an emissions component fails, or when the vehicle enters a limp-in mode. In limp-in mode, the PCM provides programmed inputs to keep the vehicle operational.

Because the vehicle is equipped with OBD II diagnostic capabilities, the MIL flashes if the onboard diagnostic system detects engine misfire severe enough to damage the catalytic converter. The vehicle should not be driven if this occurs.

Anytime the MIL is illuminated, a DTC is stored and the PCM must meet certain criteria to extinguish the lamp. On vehicles equipped with OBD I diagnostics, the MIL extinguishes only after the problem that caused the MIL to illuminate is repaired, and the key has been cycled from OFF to ON one time. On vehicles equipped with OBD II diagnostics, three consecutive good trips must occur to extinguish the MIL.

If a problem occurred with one of the main monitors, the PCM must pass the test of the monitor that failed three consecutive times. On the fourth key-on register the MIL is extinguished.

DTCs that are stored can be erased automatically only after the MIL has been extinguished and 40 warm-up cycles have occurred.

#### **Trip Definition**

The term "trip" has different meanings depending on the circumstances. If the MIL (Malfunction Indicator Lamp) is OFF, a trip is when the Oxygen Sensor Monitor and the Catalyst Monitor have been completed in the same drive cycle.

When any emission DTC is set, the MIL on the dash is turned ON. When the MIL is ON, it takes three "good" trips to turn the MIL OFF. In this case, it depends on what type of DTC is set to know what a trip is.

For the Fuel Monitor or Misfire Monitor (continuous monitor), the vehicle must be operated in the "Similar Condition Window" for a specified amount of time to be considered a good trip.

Non-continuous OBD II monitors include:

- Oxygen Sensor.
- Catalyst Monitor.
- Purge Flow Monitor.
- Leak Detection Pump Monitor (if so equipped).
- EGR Monitor (if so equipped).
- Oxygen Sensor Heater Monitor.

If any of these monitors fail twice in a row, turn on the MIL, and successfully rerun on the next start-up, it is considered a good trip.

Other examples of good trips are:

- Completion of O2 Sensor and Catalyst monitors after an emissions DTC (not an ODB II monitor) is set.
- Engine run-time of two minutes if the Oxygen Sensor Monitor or Catalyst Monitor have been stopped from running.

It can take up to two failures in a row to turn on the MIL. After the MIL is ON, it takes three good trips to turn the MIL OFF. After the MIL is OFF, the PCM will selferase the DTC after 40 warm-up cycles. A warm-up cycle is counted when the ECT (Engine Coolant Temperature) sensor has crossed  $160^{\circ}$ F and has risen by at least  $40^{\circ}$ F since the engine was started.

Refer to the OBD II course for a complete explanation.

#### **EVAPORATIVE PURGE SOLENOID**

The PCM controls Evaporative Purge Solenoid operation and provides a ground path that allows the solenoid to open. Refer to the Emission Control Systems section of this publication for more information.

#### **LEAK-DETECTION PUMP SOLENOID**

The PCM energizes the Leak-Detection Pump Solenoid when specific operating conditions have been met. Refer to the Emission Control Systems section of this publication for more information.

#### **SPEED-CONTROL SERVO SOLENOIDS**

The PCM on all vehicles operates the ground side of the vacuum and vent solenoids of the servo. Refer to the Vehicle Speed Control System section of this publication for more information.

### **LESSON 6**

#### **EMISSIONS CONTROL SYSTEMS**

The emissions control system is comprised of two major segments: evaporative emissions and exhaust emissions. Its function is to control the output of hydrocarbons (HC), carbon monoxide (CO) and oxides of nitrogen  $(NO_x)$ . The PCM controls exhaust emissions by monitoring the inputs and controlling fuel and ignition systems. A three-way catalyst is also used.

#### **EVAPORATIVE EMISSION CONTROL**

The evaporative control system consists of a fuel cap, rollover valves, vapor lines, fuel filler neck, evaporative canister, Duty Cycle Purge (DCP) solenoid, orifice and vapor lines. On some vehicles, there is also an Evaporative System Leak Detection pump (fig. 74).

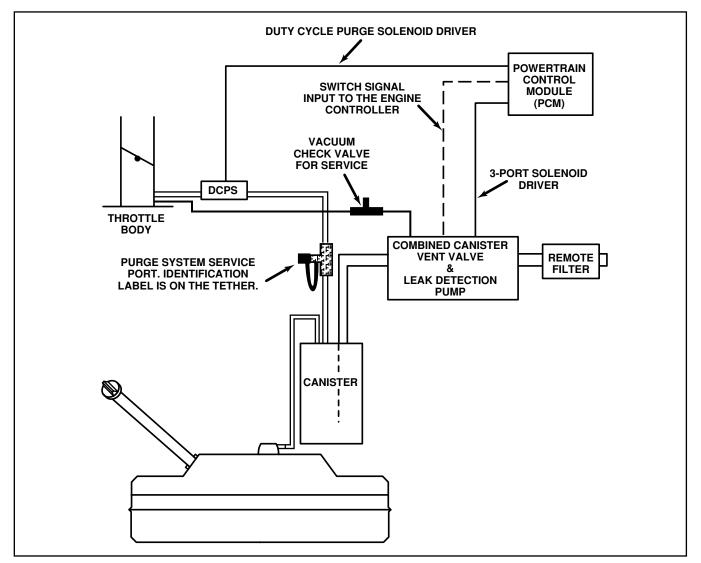


Figure 74 EVAP LDP System

#### **Fuel Filler Cap**

The fuel filler cap is a screw-on type, with a ratchet mechanism to keep the tightening force on the filler cap constant. Also, the cap is equipped with a valve to relieve both pressure and vacuum extremes in the fuel tank.

#### **Fuel-Filler Neck Flapper Valve**

On all 1997 ZJ vehicles, a flapper valve has been installed in the fuel filler neck to prevent an MIL illumination if the fuel filler cap is left off. The LDP pressurizes the evaporative system. If the fuel filler cap is left off, a large leak fault will be set. The flapper valve is spring-loaded to close and seat the filler neck when the pump nozzle is removed.

#### **Rollover Valves**

The rollover value is designed to allow fuel tank vapors to be routed to the canister. If an accident causes the vehicle to overturn, a check value prevents fuel from entering the vapor line.

#### ZJ

On 1996  $\text{Jeep}_{\otimes}$  Grand Cherokee vehicles, the rollover value is located on top of the fuel tank. The value can be removed and replaced.

On 1997  $\text{Jeep}_{\mathbb{B}}$  Grand Cherokee vehicles, the rollover value is permanently installed into the top of the tank. If the value needs replacement, the tank must be replaced.

#### AN

On the 1996 Dakota, the rollover valve is located in the top of the fuel pump module and is replaceable.

On the 1997 Dakota, the rollover valve is permanently installed into the top of the tank. If the valve needs replacement, the tank must be replaced.

#### BR

On 1996 and 1997 Ram pickup trucks, the rollover valve is located in the top of the fuel pump module and is replaceable.

#### AB

On 1996 and 1997 Ram vans, there are two rollover valves located in the top of the fuel tank. Both of the valves can be removed and replaced.

#### **Evaporative Charcoal Canister**

The evaporative charcoal canister temporarily stores fuel vapors until intake manifold vacuum draws them into the combustion chamber. The charcoal canister has its own fresh air intake.

#### **Duty-Cycle Purge Solenoid**

The Duty-Cycle Purge solenoid is used to control the flow of vapors to the intake manifold. Operation of the solenoid is controlled by the PCM which provides a ground path that allows the solenoid to open, allowing vapor flow (fig. 75).

#### Fuel-Vapor Recovery System (Duty-Cycle Purge Control)

Duty Cycle Purge is a system that feeds fuel gases from the purge canister and gasoline tank into the throttle body for mixing with incoming air. The system meters gases when the JTEC (PCM) duty-cycles the purge solenoid.

The system is disabled during Wide Open Throttle (WOT) conditions and while the engine is below a specified coolant temperature. When engine temperature exceeds a calibrated parameter, duty cycle purge is delayed for a calibrated time. Once purge delay is over, purge will be ramped in to soften the effect of dumping additional fuel into the engine.

The JTEC provides a duty cycle operating at 5 Hz (at closed throttle) or 10 Hz (at open throttle) to control this system. The duty-cycle is based upon a calculated airflow (based upon known fuel flow through the injector at a given pulse width and rpm) and is adjusted to compensate for changes in flow due to varying engine vacuum.

The duty-cycle represents the amount of On/Off time, while the Hz represents how often the duty-cycle is repeated.

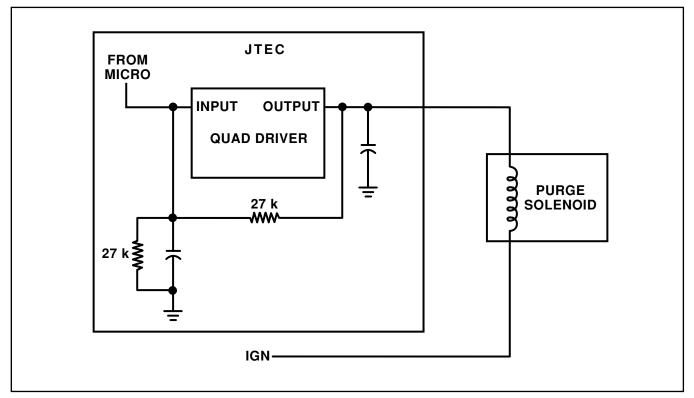


Figure 75 Duty-Cycle Purge Solenoid Control Circuit

#### Leak Detection Pump

The leak detection pump is a device that pressurizes the evaporative system to determine if there are any leaks. When certain conditions are met, the PCM will activate the pump and start counting pump strokes (fig. 76). If the pump stops within a calibrated number of strokes, the system is determined to be leak free. If the pump does not stop, a DTC will be set. Refer to the OBD II course for more information.

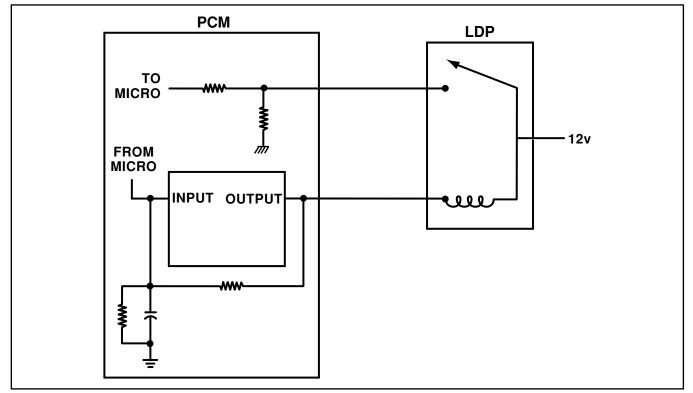


Figure 76 Leak-Detection Pump Control Circuit

### LESSON 7

#### **VEHICLE SPEED CONTROL SYSTEM**

#### **System Operation**

Vehicle speed control is accomplished through the PCM. The various speed control switches are a multiplex design, hard-wired to the PCM. A vacuum-operated speed control servo contains solenoids that are also controlled by the PCM.

The speed control switches provide inputs to the PCM to indicate the speed control modes: On, Off, Set, Resume, Cancel, Accelerate, Coast.

Depending on the vehicle, there is either a one- or two-switch assembly. The steering-column-mounted switches use multiplexed circuits to provide inputs to the PCM for ON/OFF, Resume/Accelerate, Set/Coast or Coast and Cancel modes (if equipped).

When speed control is selected by depressing the ON/OFF switch, the PCM allows a set speed to be stored in RAM for speed control. To store a set speed, depress the COAST/SET switch while the vehicle is moving at a speed between 35 and 85 mph. In order for the speed control to engage, the brakes cannot be applied, and the transmission must not be in Park or Neutral. If equipped with a manual transmission, it must be in either third, fourth, or fifth gear and engine rpm must be below 6,000 rpm.

The speed control can be disengaged manually by:

- Stepping on the brake pedal
- Selecting the OFF position
- Depressing the CANCEL switch (if equipped)
- Allowing vehicle to decelerate (coast) to below 25 mph
- Depressing the clutch

The speed control can also be disengaged by any of the following conditions:

- An indication of Park or Neutral
- An rpm increase without a VSS signal increase (indicates that the clutch has been disengaged)
- Excessive engine rpm (indicates that the transmission may be in a low gear)

The previous disengagement conditions are programmed for added safety.

Once the speed control has been disengaged, depressing the RES/ACCEL switch restores the vehicle to the target speed that was stored in the PCM's RAM.

#### **Speed Control Switch Operation**

When the ON switch is depressed, the indicator lamp comes on and the PCM sends 12 volts to the speed control servo through a set of contacts in the brake switch that are closed with the pedal at rest (fig. 77).

**NOTE:** Depressing the ON/OFF switch will erase the set-speed stored in the PCM's RAM and turn off power to the servo.

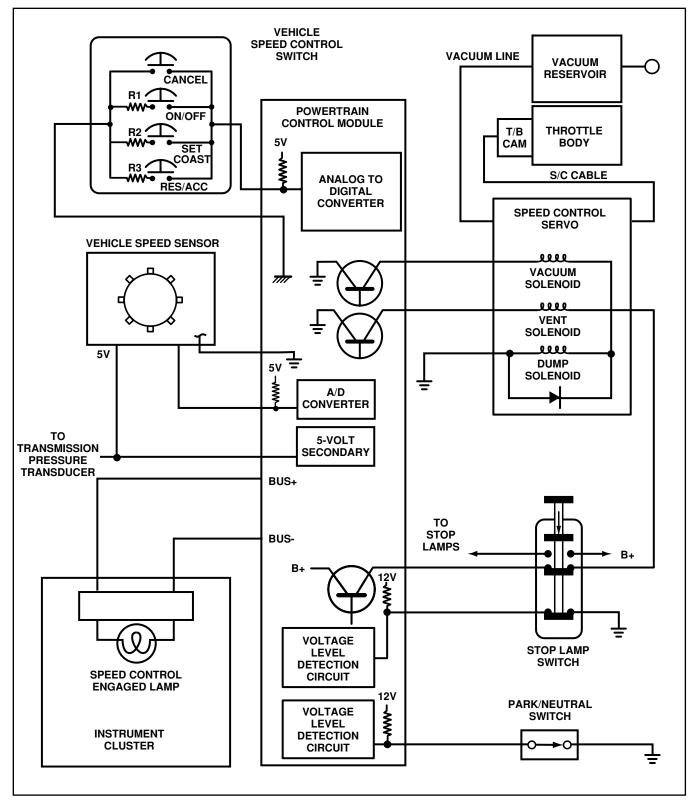


Figure 77 Typical Speed-Control System Circuit Schematic

While traveling between 35 and 85 mph, the SET button can be depressed causing a value to be stored in the RAM of the PCM.

The PCM is programmed for an acceleration feature which allows the driver to increase vehicle speed while the speed control is engaged. With the RES/ACCEL switch held closed, the vehicle accelerates slowly to the desired speed. The new target speed is stored in the RAM when the RES/ACCEL switch is released. The PCM also has a "tap-up" feature which increases vehicle speed at a rate of approximately two mph for each momentary switch activation of the RES/ACCEL switch.

There are two ways to disengage the speed control system. Depressing either the brake pedal or cancel switch will disengage the speed control system without losing the target speed in memory. When the brakes are applied, two things happen:

- The PCM recognizes an input that the brakes are applied. This causes the PCM to disengage speed control operation and retain the target speed in memory.
- The PCM interrupts the power supply to the speed control servo.

The PCM also provides a means to decelerate without disengaging speed control. To decelerate from an existing recorded target speed, depress and hold the SET/COAST switch until the desired speed is reached. Releasing the switch causes a new target speed to be stored in RAM.

#### **Speed Control Servo**

The speed control servo consists of three solenoids:

- Vacuum
- Vent
- Dump

There is also a diaphragm with a cable attached to control the throttle linkage.

As mentioned earlier, power is supplied to the servo by the PCM through the brake switch. The PCM also controls the ground path for the vacuum and vent solenoids.

The dump solenoid is energized anytime it receives power. If power to the dump solenoid is interrupted, the solenoid dumps vacuum in the servo. This provides a safety backup to the vent and vacuum solenoids.

To operate, the vacuum and vent solenoids must be grounded at the PCM. When the PCM grounds the vacuum servo solenoid, the solenoid allows vacuum to enter the servo through a cable and pull open the throttle plate. When the PCM breaks the ground, the solenoid closes and allows no more vacuum to enter the servo. The PCM also operates the vent solenoid via ground. The vent solenoid opens and closes a passage to bleed or hold vacuum in the servo as required.

The PCM "duty cycles" the vacuum and vent solenoids to maintain the set speed or to accelerate and decelerate the vehicle. To increase throttle opening, the PCM grounds the vacuum and vent solenoids. To decrease throttle opening, the PCM removes the grounds from the vacuum and vent solenoids. When the brake is released, if vehicle speed exceeds 25 mph to resume, 30 mph to set, and the RES/ACCEL switch has been depressed, ground for the vent and vacuum circuits is restored.

#### **Speed-Control Switch Input**

Speed control switch input is accomplished by multiplexing, which allows the PCM to identify more than one signal from a single wire. To accomplish this, the speed control switch uses resistors that cause different voltage signals at the PCM.

#### Multiplexing

The PCM sends out five volts through a fixed resistor and monitors the voltage change between the fixed resistor and the switches (Table 5). If none of the switches are depressed, the PCM will measure five volts at the sensor point (open circuit). If a switch with no resistor is closed, the PCM will measure zero volts (grounded circuit). Now, if a resistor is added to a switch, then the PCM will measure some voltage, proportional to the size of the resistor. By adding a different resistor to each switch, the PCM will see a different voltage, depending on which switch is pushed.

#### **Brake Switch**

The brake switch provides an input to the PCM to disengage the speed control when the brakes are applied (fig. 78). It is also used to influence transmission torqueconverter clutch disengagement, and indicates when the driver has depressed the brake pedal. The brake switch is equipped with three sets of contacts, one normally open and the other two normally closed (brakes disengaged). The PCM sends a 12-volt signal to one of the normally closed contacts in the brake switch, which is connected to a ground. With the contacts closed, the 12-volt signal is pulled to ground, causing the signal to go low. The low-voltage signal, monitored by the PCM, indicates that the brakes are not applied. When the brakes are applied, the contacts open, causing PCM output voltage to go high, disengaging the speed control and grounding the dump solenoid.

Voltage	Resistance	ZJ	97 BR/AB	96 AN/BR/AB	97 AN
0	0 Ω	Cancel	—	—	Cancel
1.5	945 Ω	On/Off	On/Off	On/Off	On/Off
2.9	<b>2.9K</b> Ω	Coast	—	—	Coast
3.8	7Κ Ω	Set	Set/Coast	Set/Coast	Set
4.4	15.8K Ω	Resume/ Accel	Resume/ Accel	Resume/ Accel	Resume/ Accel
5.0	∞	At Rest	At Rest	At Rest	At Rest

#### **Voltage Resistance Values**

Table 5Speed Control Switches

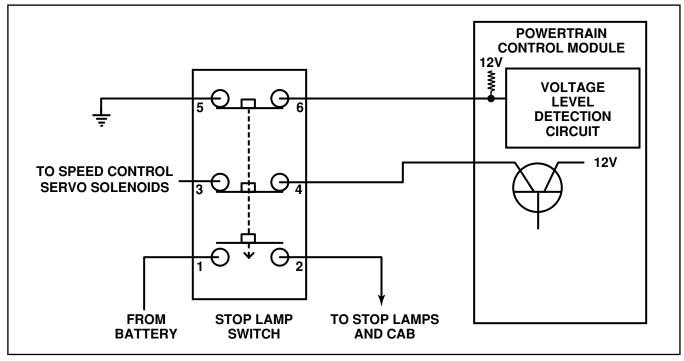


Figure 78 Brake Switch Circuit

The second set of normally closed contacts receives battery voltage anytime speed control is selected. From the brake switch, current is routed to the speed control servo solenoids. The speed control solenoids (vacuum, vent, and dump) are provided with current anytime the speed control is ON and the brakes are disengaged. When the driver applies the brakes, the contacts open and current to the solenoids is interrupted. The normally open contacts are fed battery voltage. When the brakes are applied, battery voltage is supplied to the stop lamps and the speed control relay, if so equipped. Refer to Brake Switch in the PCM Inputs section of this publication for more information.

#### **Adaptive Learning Strategy**

An adaptive strategy compensates for vehicle-to-vehicle variations in speed control cable lengths. When the speed control is set with the vehicle operator's foot off of the accelerator pedal, the speed control senses excessive speed control cable slack and adapts. If the lift foot sets are continually used, the speed control overshoot/ undershoot condition will develop.

To "unlearn" the overshoot/undershoot condition, use the following steps:

- 1. Press and release the set button while maintaining the desired set speed with the accelerator pedal. Do not accelerate or decelerate.
- 2. After waiting 10 seconds, turn the cruise control switch to the OFF position (or press the CANCEL button if equipped).

This procedure must be performed approximately 10-15 times to unlearn the overshoot/undershoot condition completely.

#### **Interactive Speed Control**

"Interactive" means that communication between the PCM and the TCM portion is taking place. Interactive speed control avoids unnecessary shifting for smoother, quieter operation and, when downshifts are required, makes the shifts smoother.

#### When Climbing a Grade

Interactive speed control tries to maintain the set speed by increasing the throttle opening. If opening the throttle alone cannot maintain the set speed and the vehicle speed drops more than three mph below the set speed, the transmission will downshift to third gear. If the vehicle continues to lose speed, the transmission will downshift farther, until it selects a gear that can maintain the set speed. After the vehicle encounters a less-steep grade, or has crested the grade (reduced the load on the powertrain) and can maintain the set speed at a reduced throttle position, the transmission will upshift, as appropriate, until the set speed can be maintained in Overdrive.

#### **Downshift Delay**

Downshift delay features have been added to reduce the number and frequency of downshifts when operating in hilly or mountainous country. While operating, interactive speed control delays or avoids downshifts by applying up to early wideopen throttle without the TCM portion scheduling a downshift. If the interactive speed control is not engaged or the driver manually overrides the throttle while interactive speed control is engaged, the downshift delay feature is not activated.

Torque converter lock and unlock shifts are not affected by the downshift delay feature and will occur at the same throttle angle at a given speed regardless of whether interactive speed control operates or not.

#### **Grade Hunting**

All vehicles equipped with a four-speed automatic transmission have a gradehunting feature for the Third Gear-to-Overdrive upshift. The TCM portion identifies the powertrain loading conditions and selects the proper gear to maintain the current vehicle speed. Under moderate loading conditions, the transmission will stay in Third Gear until the top of the grade is reached or the powertrain loading is reduced. If conditions are more severe, hunting between Second and Third can occur.

Beginning with 1996, all vehicles equipped with a four-speed automatic transmission also have a grade hunting feature for the Second to Third Gear upshift. If powertrain loading is severe, the transmission may shift into Second Gear and remain there until powertrain loading is reduced, then a Second to Third Gear upshift will be scheduled. Grade hunting features always operate regardless of whether the interactive speed control is engaged. If the interactive speed control is not engaged and powertrain loading is not reduced, the driver may have to completely lift off of the throttle before an upshift will occur. If the driver does lift off the throttle to induce an upshift under these conditions, vehicle speed will reduce and the Overdrive-to-Third and Third-to-Second-Gear downshifts will reoccur when the throttle is reapplied. Transmission damage may result if the driver repeatedly induces grade hunting.

#### When Descending a Grade (Overspeed Reduction)

The overspeed reduction feature helps maintain the interactive speed-control set speed when descending a grade.

The TCM portion must sense that the interactive speed control is set. Then the interactive speed control will try to maintain the set speed by reducing or closing the throttle opening. If closing the throttle (a TPS signal of two degrees or less is considered closed throttle) is not enough to keep the vehicle within three mph over the set speed, the transmission will downshift to Third Gear. After the downshift to Third Gear, the interactive speed control continues normal operation. The TCM portion monitors conditions leading to a return to Overdrive. Once conditions are identified that grade hunting between Third and Overdrive is unlikely, the transmission will shift into Overdrive and resume normal operation.

If the downshift to Third Gear has taken place, pushing the brake pedal will disengage the interactive speed control but the transmission will stay in Third Gear. The transmission will upshift to Overdrive when the TCM receives a TPS signal of approximately five degrees or more.

If the downshift to Third Gear has taken place and the interactive speed control is still engaged, the transmission will upshift to Overdrive when the TCM receives a TPS signal of approximately eight degrees or more for approximately three seconds or more with the vehicle at the set speed or greater.

If the downshift to Third Gear has taken place and the interactive speed control is disengaged using the ON/OFF button or the CANCEL button, the transmission will upshift to Overdrive after a delay of approximately two seconds.

NOTES

### **LESSON 8**

#### **AIR CONDITIONING CONTROLS**

#### AN/BR

#### **Instrument Panel A/C Select Switch**

When the A/C-heater control switch is moved to an A/C position or the defroster position, the switch provides a ground for a 12-volt pull-up circuit. This tells the PCM that air conditioning has been selected.

#### **Air-Conditioning Request Signal**

After the driver has selected air conditioning, the PCM looks at the A/C request circuit to determine if system conditions are appropriate for compressor operation. The A/C request signal provides information to the engine controller for the A/C high and low pressure switches, as well as the evaporator fin temperature switch. This signal indicates that system pressures and evaporator temperature are in an acceptable range for air-conditioning application. If the PCM request circuit is pulled low with switches closed, the PCM will provide a ground for the A/C clutch relay. Normal A/C compressor cycling operation is controlled by the A/C low-pressure switch on the A/C request circuit.

#### **A/C Compressor Clutch Relay**

The PCM energizes the A/C compressor clutch relay by providing a ground for the relay coil. The PCM energizes the relay only after the following conditions have been met:

- Engine speed is greater than 500 rpm
- TPS voltage has not exceeded 2.5 volts above minimum TPS
- Approximately six seconds have elapsed since the start-to-run transfer occurred
- A/C compressor has operated for a minimum time (this varies with vehicle speed and throttle position)
- Pressure on the discharge line is below 450 to 490 psi
- Suction pressure is above 34 to 38 psi
- Engine coolant temperature is below 257°F

Once all of the above conditions have been met and the A/C request signal indicates that A/C compressor operation is desired, the PCM energizes the A/C compressor relay (fig. 79).

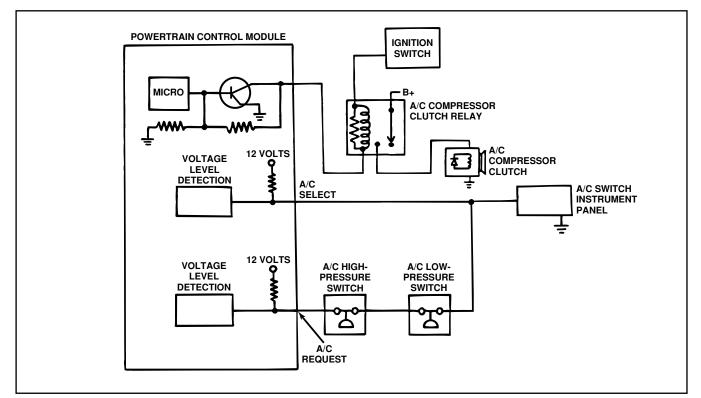


Figure 79 1996 BR, 1997 AN/BR A/C Circuit

#### AB

#### **Instrument Panel A/C Select Switch**

When the A/C-heater control switch is moved to an A/C position or the defroster position, the switch provides a ground for a 12-volt pull-up circuit. This tells the PCM that air conditioning has been selected.

#### **Air-Conditioning Request Signal**

After the driver has selected air conditioning, the PCM looks at the A/C request circuit to determine if system conditions are appropriate for compressor operation. The A/C request signal provides information to the engine controller for the A/C high and low pressure switches, as well as the evaporator fin temperature switch. This signal indicates that system pressures and evaporator temperature are in an acceptable range for air-conditioning application. If the PCM request circuit is pulled low with switches closed, the PCM will provide a ground for the A/C clutch relay (fig. 80). Normal A/C compressor cycling operation is controlled by the A/C low-pressure switch on the A/C request circuit.

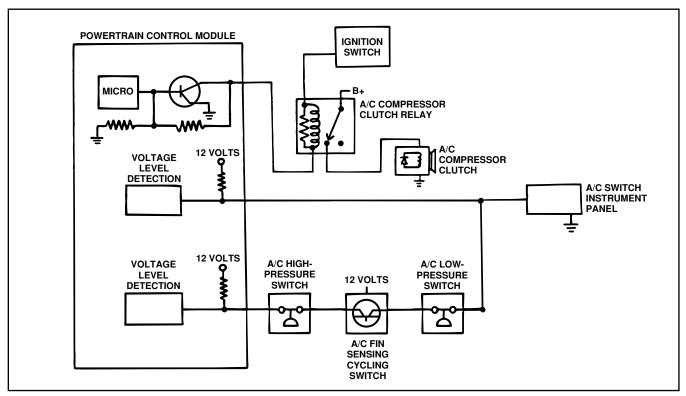


Figure 80 AB A/C Circuit

#### ZJ

#### **Instrument Panel A/C Select Switch**

When the A/C-heater control switch is moved to an A/C position or the defroster position, a signal is sent on a wire connected to the Body Control Module (BCM). The BCM then sends a message over the CCD bus to the PCM to turn on the A/C compressor (select command) informing the PCM that air conditioning has been selected.

#### **Air-Conditioning Request Signal**

After the driver has selected air conditioning, the PCM looks at the A/C request circuit to determine if system conditions are appropriate for compressor operation (fig. 81). The A/C request signal provides information to the engine controller from the A/C high and low pressure switches. This signal indicates that system pressures are in an acceptable range for air-conditioning application. If the PCM request circuit is pulled low with switches closed, the PCM will provide a ground for the A/C clutch relay. Normal A/C compressor cycling operation is controlled by the A/C low-pressure switch on the A/C request circuit.

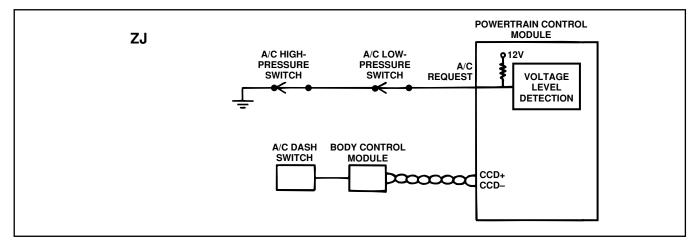


Figure 81 ZJ Air Conditioning Switch Circuit

### **LESSON 9**

#### **TRANSMISSION ELECTRONICS**

#### **GENERAL DESCRIPTION**

The 42/44/46RE transmissions are four-speed, rear-wheel-drive (RWD), automatic transmissions with an electronic governor.

Mechanical and hydraulic components are similar to those used in 42RH and 46RH transmissions. The major difference is the method of producing governor pressure for shift speed control. The RE-style transmissions use electronic components to develop governor pressure. A mechanical governor is used in the 42RH, 46RH, and 47RH.

The RE valve body transfer plate is completely new. It has been redesigned to accept a new governor body and different hydraulic circuitry. The governor pressure solenoid valve and sensor are mounted in this body. The new transfer plate channels line pressure through the governor body to the solenoid valve. It also channels governor pressure from the solenoid valve to the governor circuit. It is the solenoid valve that develops necessary governor pressure.

The RE 4WD overdrive unit is 5-1/4 inches shorter than previous overdrive units after eliminating the mechanical governor mechanism.

#### **FUNCTIONAL OPERATION**

The Powertrain Control Module (PCM) controls operation of the converter clutch, overdrive clutch, and governor pressure solenoid. It determines transmission shift points based on input signals from the transmission thermistor, transmission speed sensor, engine speed sensor, vehicle speed sensor and throttle position sensor.

The PCM continuously checks for internal transmission and electrical problems, as well as some hydraulic problems. When it senses a problem, the control module stores a diagnostic trouble code. Some of these codes cause the transmission to go into "default" mode. When the PCM detects a problem, the transmission defaults to third gear. When this happens, the only transmission functions are:

- PARK and NEUTRAL.
- REVERSE.
- THIRD GEAR.
- SECOND GEAR (Manual shift).

No upshifts or downshifts are allowed. The position of the manual valve alone allows the three available ranges. Although engine performance is seriously degraded while in this mode, it allows the owner to drive the vehicle in for service. The transmission can be shifted manually by quickly downshifting into first to achieve first gear, then shifting to second, then to third. However, default mode will not allow fourth gear, or any converter-clutch operation.

Once the DRB III is in the transmission portion of the diagnostic program, it constantly monitors the PCM, updating the DRB III screen with switch, sensor, and input/output states, as well as displaying diagnostic trouble codes and default status.

#### POWERFLOW

Clutch bands overrunning clutch and planetary gear sets in the transmission unit provide First- through Third-Gear ranges in the RE transmissions. Fourth-Gear range is provided by the overdrive unit, which contains an overdrive clutch, direct clutch, planetary gear set and overrunning clutch.

The overdrive clutch is applied in fourth gear only. The direct clutch is applied in all gears, except fourth.

#### **TORGUE CONVERTER ELECTRONICS**

The converter contains a converter-clutch mechanism. The converter clutch is electronically controlled. It always engages in Fourth Gear, but in Third Gear only when the overdrive control switch is in the OFF position.

The torque converter is not a serviceable component. Replace it as an assembly when diagnosis indicates a malfunction has occurred or when a major malfunction allows debris to enter the converter.

#### **RECOMMENDED FLUID**

The only fluid recommended for the RE transmissions is Mopar ATF Plus, type 7176. Do not use Dexron II, except in an emergency.

#### **ELECTRONIC GOVERNOR COMPONENTS**

Governor pressure is developed and controlled electronically in the RE transmissions. Components that develop and control governor pressure are:

- Governor body.
- New design valve body transfer plate.
- Governor pressure solenoid valve.
- Governor pressure sensor (transducer).
- Transmission fluid temperature sensor (thermistor).
- Transmission output speed sensor.
- Throttle position sensor.
- Powertrain Control Module (PCM).

#### **Governor Pressure Solenoid Valve**

The governor pressure solenoid valve is an electrohydraulic device, located in the governor body on the valve body transfer plate. The solenoid valve (fig. 82) generates the governor pressure needed for upshifts and downshifts.

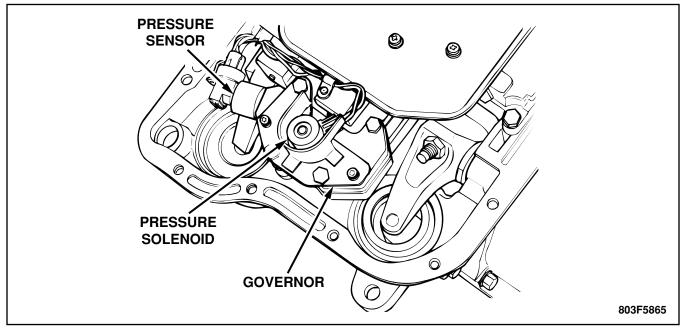


Figure 82 Governor Pressure Solenoid Location

The inlet side of the solenoid value is exposed to normal transmission line pressure. The outlet side leads to the value body governor circuit.

The solenoid valve regulates line pressure to produce governor pressure. The average current supplied to the solenoid valve controls governor pressure. One amp current produces zero psi governor pressure. Zero amps set the maximum governor pressure. Current is regulated by modulating the pulse width to 512 Hz driver frequency (512 cycles per second).

The PCM supplies electrical power to the solenoid valve. Operating voltage is 12 volts (DC) and is provided through the battery terminal on the module.

The solenoid is sensitive to polarity. The PCM energizes the solenoid by grounding it through pin B8 on the PCM.

If the voltage on the circuit (pin B8) does not match the expected voltage for approximately 5 seconds, a fault will be set.

**<u>Caution</u>**: Shorting pin B8 to 12 volts will damage the PCM.

#### **Governor Pressure Sensor**

The governor pressure sensor (fig. 83) measures output pressure of the governor pressure solenoid valve (fig. 84).

The sensor output signal provides the necessary feedback to the PCM. This feedback is needed to accurately control pressure. The unit is an absolute pressure device and the output is calibrated to be 0.35 to 0.65 volt at 14.7 psi (normal barometric pressure). Since this is an absolute pressure device, zero psi calibration is often required to compensate for changing atmospheric pressure or altitude. This voltage measured at zero psi, is referred to as zero pressure offset.

If the input voltage from this sensor remains below 0.1 volt or exceeds 4.73 volts for approximately 8 seconds, a fault will be set.

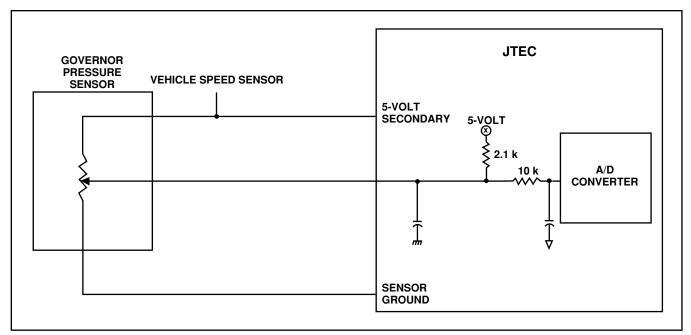


Figure 83 Governor Pressure Sensor Circuit

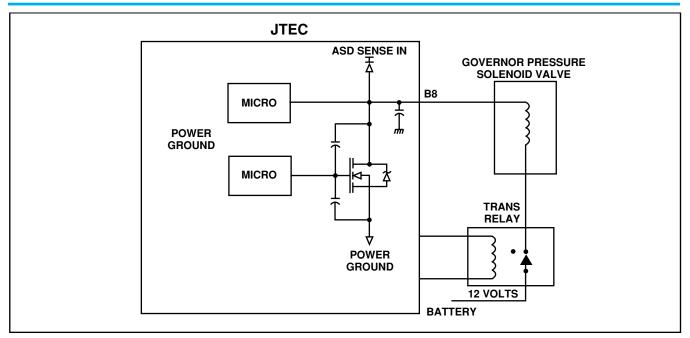


Figure 84 Governor Pressure Solenoid Valve Circuit

#### **Governor Body and Transfer Plate**

The RE valve body has a new transfer plate designed to supply transmission line pressure to the governor pressure solenoid valve, and to return governor pressure.

The governor pressure solenoid value is mounted to the governor body which is bolted to the lower side of the transfer plate.

#### **Transmission Fluid Temperature Thermistor**

The thermistor supplies transmission fluid temperature readings to the PCM. Its location has moved from the solenoid assembly into the governor pressure sensor for 1996. The temperature readings are used to control engagement of the overdrive clutch, the converter clutch and governor pressure. Normal resistance value for the thermistor at room temperature is approximately 1,000 ohms.

The PCM prevents engagement of the converter clutch and overdrive clutch when fluid temperature is below approximately 50°F.

If fluid temperature exceeds 260°F, the PCM causes a 4-3 downshift to engage the converter clutch. Engagement is according to the Third-Gear converter-clutch engagement schedule.

The overdrive OFF lamp in the instrument panel also illuminates when the shift back to Third occurs. The transmission does not allow Fourth-Gear operation until fluid temperature decreases to approximately 230°F.

Previously, the thermistor was mounted on the underside of the converter-clutch solenoid; but 1996 models incorporate it into the governor pressure sensor connector. The thermistor is immersed in fluid at all times.

If the input voltage from this sensor drops below 1.5 volts or rises above 3.75 volts, a fault will be set (fig. 85).

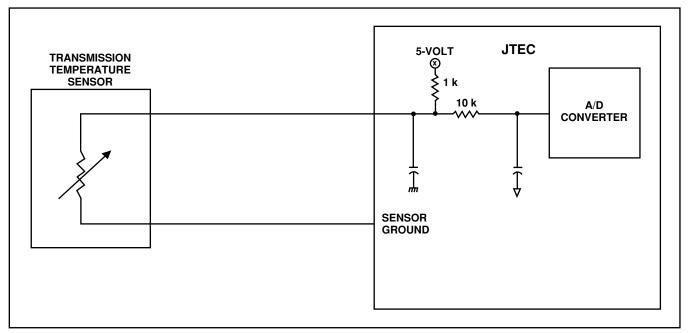


Figure 85 Transmission Temperature Sensor Circuit

#### **Transmission Speed Sensor**

The speed sensor (fig. 86) is located in the overdrive gear case, positioned over the park gear. It monitors transmission output-shaft rotating speed. The sensor used in the RE-style transmission is the same sensor used in Chrysler 41TE and 42LE front-drive transaxles.

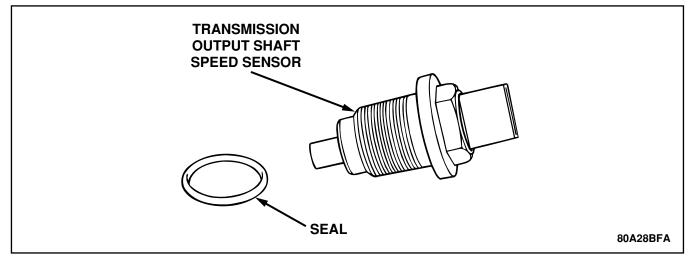


Figure 86 Speed Sensor Location

Speed sensor signals are triggered by the park gear lugs as they rotate past the sensor pickup face. One revolution of the output shaft produces 23 pulses. Input signals from the sensor are sent to the PCM for processing.

The vehicle speed sensor also serves as backup to the transmission speed sensor. If the output speed sensor fails, the vehicle speed sensor calculates governor pressure.

#### **Throttle Position Sensor**

The TPS provides throttle position input signals to the PCM. This input signal is used to determine overdrive and converter clutch shift schedule, and to select the proper governor curve.

#### **Powertrain Control Module (PCM)**

The PCM controls operation of the converter clutch, overdrive clutch and governor pressure solenoid.

The control module determines transmission shift points, based on input signals from the transmission thermistor, transmission output-shaft speed sensor, crankshaft speed sensor, vehicle speed sensor and throttle position sensor.

#### **Governor Pressure Curves**

Four governor pressure curves are programmed into the PCM. The different curves allow the module to adjust governor pressure for varying conditions.

One curve is used for operation when fluid temperature is at or below 30°F.

A second curve is used when fluid temperature is at or above 31°F, during normal city or highway driving.

A third curve is used during Wide Open Throttle (WOT) operation. This curve is implemented above 85% throttle opening.

The fourth curve is used when driving with the transfer case in low range. There is no direct input into the PCM for low-range operation. Engine acceleration in lowrange is more than twice the acceleration in high range. Transmission lag times become critical under this condition, requiring a separate governor pressure curve.

#### **Sensor Calibration**

Compensation is required for performance variations of two of the input devices. Though the slope of the transfer functions is tightly controlled, offset may vary due to various environmental factors or manufacturing tolerances.

#### **Governor Pressure Transducer Zero-Pressure Offset**

The pressure transducer is affected by barometric pressure as well as temperature. Calibration of the zero pressure offset is required to compensate for shifting output, due to these factors.

#### **Normal Governor-Pressure Transducer Calibration**

Normal calibration will be performed when sump temperature is above 50°F, or in the absence of sump temperature data, after the first 10 minutes of vehicle operation. Calibration of the pressure transducer offset occurs each time the output shaft speed falls below 200 rpm. Calibration is repeated each three seconds when the output shaft speed is below 200 rpm.

A 0.5-second pulse of 95% duty cycle is applied to the governor pressure solenoid valve and the transducer output is read during this pulse. Averaging the transducer signal is necessary to reject electrical noise.

#### **Cold Governor-Pressure Transducer Calibration**

Under cold conditions (below  $50^{\circ}$ F sump), the governor pressure solenoid valve response may be too slow to guarantee zero psi during the 0.5-second calibration pulse. Calibration pulses are continued during this period; but the transducer output values are discarded. Transducer offset must be read at key ON, under conditions which promote a stable reading. This value is retained and becomes the offset during the "cold" period of operation.

#### **Transmission Shifting**

Shift valve operation in the RE transmission with the electronic governor mechanism is basically unchanged. The 1-2 and 2-3 upshift sequence occurs exactly the same as in non-electronic governor transmissions.

The valve body shift valves are still moved by a combination of throttle and governor pressure. The only real difference is that governor pressure is generated by electrical components, instead of a mechanical valve and weight assembly.

The conditions under which a shift to Fourth will occur, also remain the same:

- Shift to Third not yet completed.
- Overdrive switch is in the OFF position.
- Throttle is at 3/4 to wide-open position.
- Vehicle speed is too low for 3-4 shift to occur.
- Transmission fluid temperature is below 30°F or above 250°F.

#### **OVERDRIVE OFF SWITCH**

The overdrive OFF (control) switch is located in the instrument panel. The switch is a momentary contact device that signals the PCM to toggle current status of the overdrive function (fig. 87). At key-on, overdrive operation is allowed. Pressing the switch once, causes the vehicle to enter the overdrive OFF mode and illuminates the overdrive OFF switch lamp. Pressing the switch a second time restores normal overdrive operation and turns the overdrive lamp off. The overdrive OFF mode defaults to ON after the ignition switch is cycled OFF and ON. The normal position for the control switch is the ON position. The switch must be in this position to energize the solenoid and allow a 3-4 upshift. The control switch indicator light illuminates only when the overdrive switch is pressed to the OFF position, or when illuminated by the PCM.

If the input voltage from this switch remains low (contacts closed) for more than five minutes, a fault will be set.

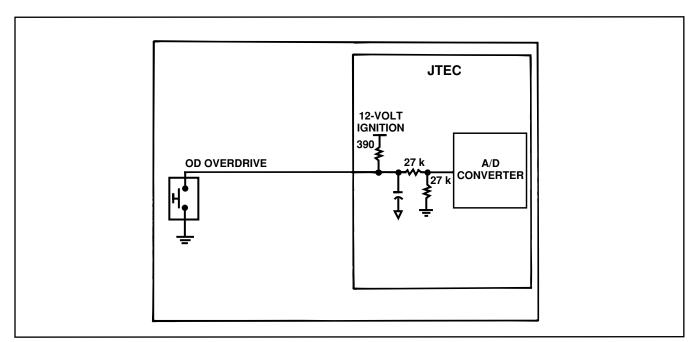


Figure 87 Overdrive Off Switch Circuit

#### **3-4 SHIFT SEQUENCE**

The overdrive clutch is applied in Fourth Gear only. The direct clutch is applied in all ranges except Fourth Gear. Fourth Gear overdrive range is electronically controlled and hydraulically activated.

Various sensor inputs are supplied to the PCM to operate the overdrive solenoid on the valve body. The solenoid contains a check ball that opens and closes a vent port in the 3-4 shift valve feed passage. The overdrive solenoid (and check ball) are not energized in First, Second, Third, or Reverse gear. The vent port remains open, diverting line pressure from the 2-3 shift valve away from the 3-4 shift valve. The overdrive control switch must be in the ON position to transmit overdrive status to the PCM.

A 3-4 upshift occurs only when the overdrive solenoid is energized by the PCM. The PCM energizes the overdrive solenoid during the 3-4 upshift. This causes the solenoid check ball to close the vent port allowing line pressure from the 2-3 shift valve to act directly on the 3-4 upshift valve. Line pressure on the 3-4 shift valve overcomes valve spring pressure, moving the valve to the upshift position. This action exposes the feed passages to the 3-4 timing valve, 3-4 quick fill valve, 3-4 accumulator, and ultimately to the overdrive piston. Line pressure through the timing valve moves the overdrive piston into contact with the overdrive clutch. The direct clutch is disengaged before the overdrive clutch is engaged. The boost valve provides increased fluid apply pressure to the overdrive clutch during 3-4 upshifts, and when accelerating in Fourth Gear. The 3-4 accumulator cushions overdrive clutch engagement to smooth 3-4 upshifts. The accumulator is charged at the same time as apply pressure acts against the overdrive piston.